



Progress Towards System-Security Co-design

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Content

1. **Goals**
2. Decentralized Label Model
3. Formal Framework
4. System-level Synthesis Framework
5. Next Steps

What Is Our Goal?

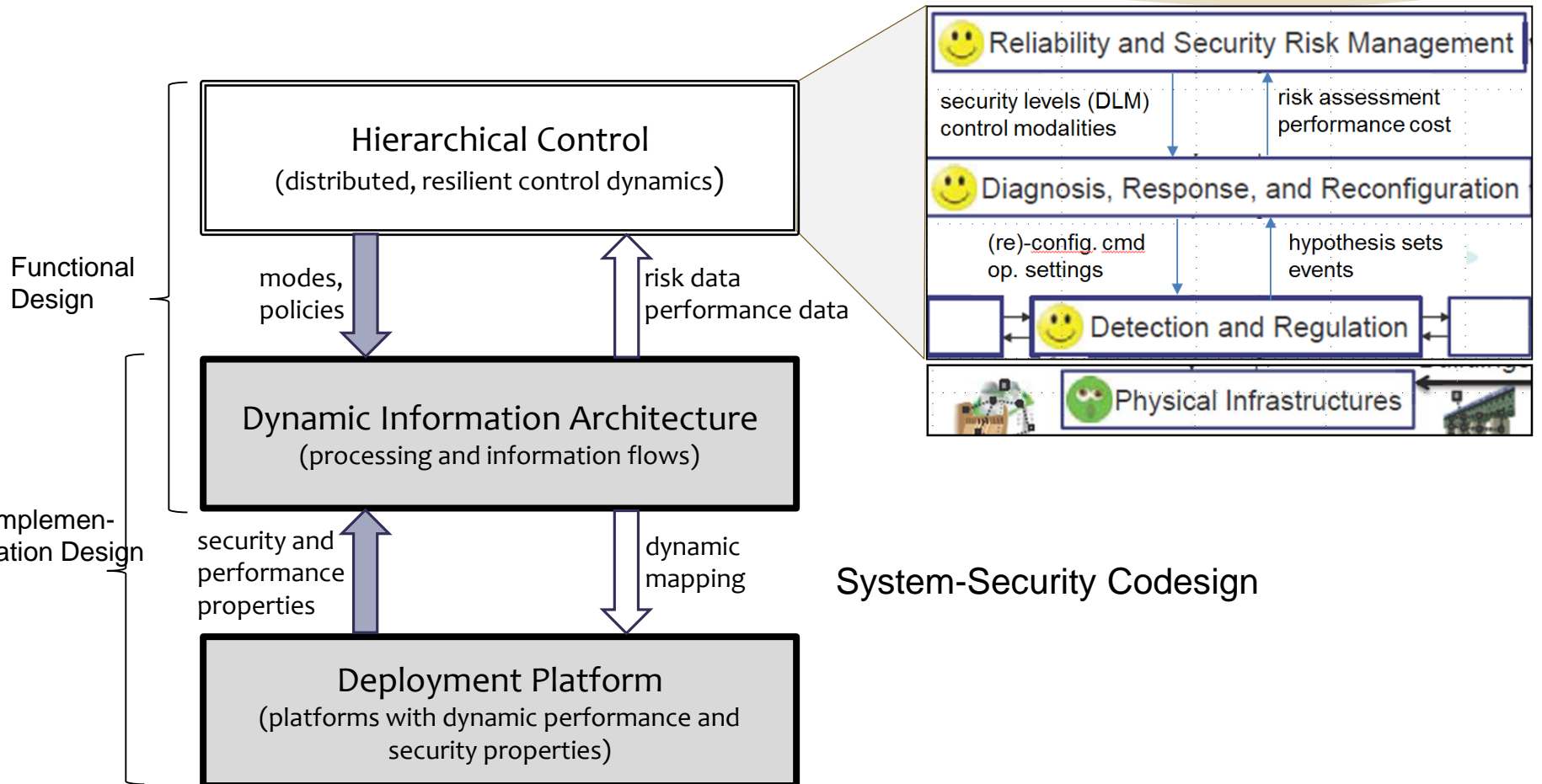
* **The traditional system-level synthesis problem for the “cyber” side of CPS:**

- Derive specification for the behavior of the system components that will be implemented using networked computing
- Derive a functional model for the information architecture and componentize the system
- Select computing/networking platform
- Derive deployment model assigning components of the information architecture to processing and communication platforms
- Generate code for software components and derive WCET and WCCT
- Perform timing analysis

* **Making security part of system-level co-design**

- Mitigation of security vulnerabilities cost performance, timing, even functionality
- Our goal is to address security requirements as part of the design trades embedded in the system-level design process

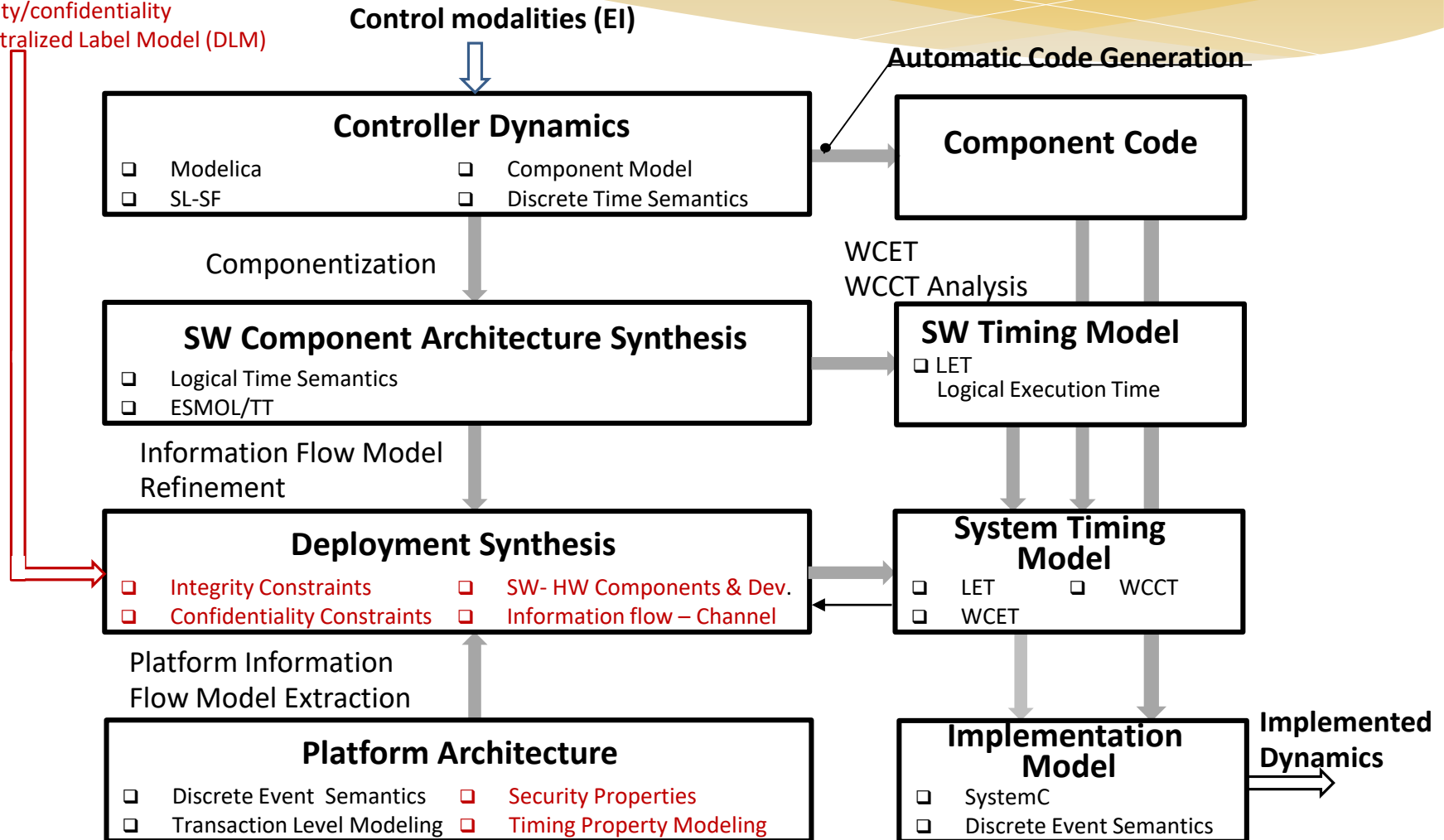
Co-design Problem in FORCES



Design Flow

Security Policies (EI)

integrity/confidentiality
Decentralized Label Model (DLM)



Challenges

- * Modeling language suite
(behavior, information flows, SW components, architecture, timing, platform, deployment) - reuse previous work
- * **Security Requirement Modeling**
(need to be composable with other modeling aspects)
- * **Common Semantic Domain and Formal Framework**
(functional, performance and security models need to be anchored to a semantic domain suitable for synthesis)
- * **Synthesis Framework and Co-design flow**
(mapping system-level synthesis problem on the formal framework and tools)
- * **Integrated Tool Suite and Validation**
(target domain rich enough for testing the co-design tool suite)

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Security Concerns Addressed

- * **Integrity attacks**

- Manipulate data (value, timestamp, source identity,..)

- * **Confidentiality attack**

- Leak critical data to unauthorized persons/systems

- * **Integrity and confidentiality restrictions impose constraints on information flows.**

- How to model these restrictions?
- How to integrate these restrictions with others (functional and timing) and formulate a co-design problem?

Decentralized Label Model (DLM) for Information Flow Control

- * Myers, Liskov (1997): Introduced security-typed languages by labeling variables with information flow security policies
- * Method was developed for programming languages, the result is *Jif*, a security-typed version of Java.
- * DLM provides mechanism for static/dynamic type checking of security labels in information flows to detect policy violations.
- * Example: *Jif*, a security-typed version of Java

DLM Concepts

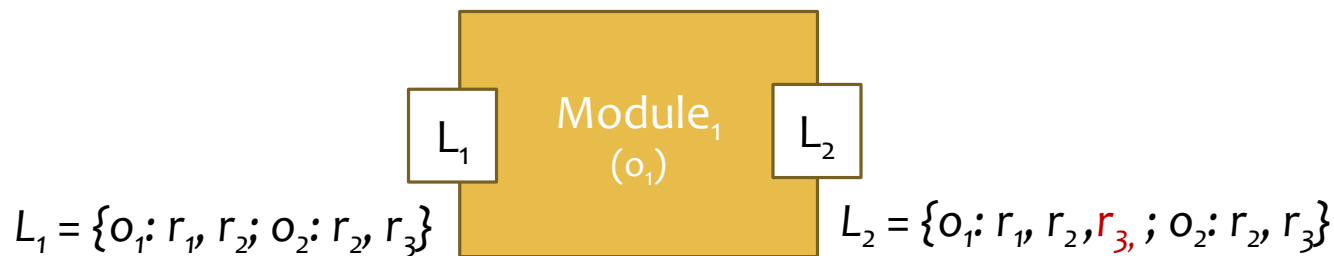
- * New semantic concepts introduced:
 - *Principles* that represent authority entities.
 - *Labels* expressing security classes encountered in most information flow models.
 - *Policies* that are elementary security primitives used in *labels*.
 - *Labeled entities* that have attached labels, such as *values*, *slots* (*variables*, *objects*, *i/o channels*). Copies of *values* can be relabeled, *slots* cannot.
 - *Operators* that can *relabel* or *declassify* values in information flows.
- * The model can be naturally applied to system-level information flow modeling languages by assigning security types to input/output ports

Working With Security Labels

- * Labels contain a set of policies. Each policy includes an owner and a set of readers allowed by the owner. The effective reader set for a label is the intersection of every reader set in it.

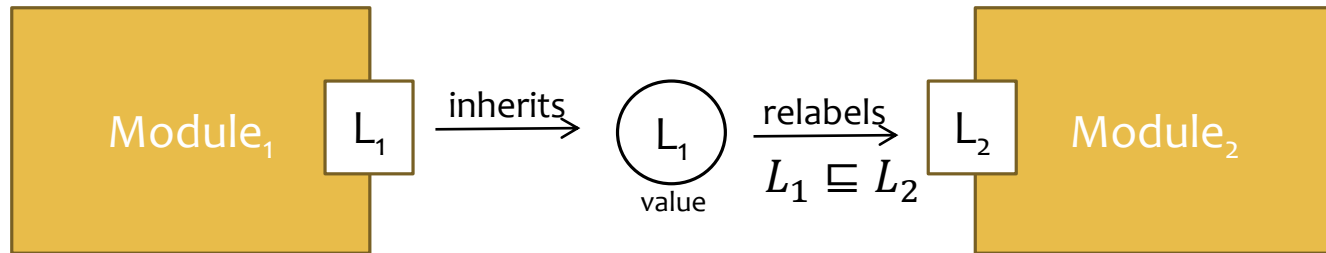
$$L = \{o_1: r_1, r_2; o_2: r_2, r_3\}$$

- * Processing blocks running under the authority of an owner can **declassify** the owner's policy by adding readers.



Propagation Rules

* Propagation rule-1 (restriction):

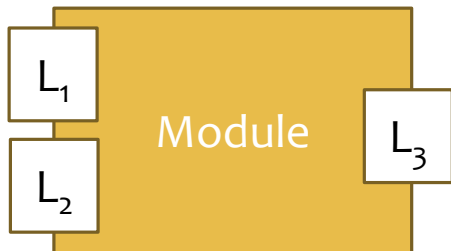


$$owners(L_1) \subseteq owners(L_2)$$

$$\forall o \in owners(L_1), readers(L_1, o) \supseteq readers(L_2, o)$$

(L₁ has more readers and fewer owners than L₂)

* Propagation rule-2 (join):



L₃ is the join of L₁ and L₂

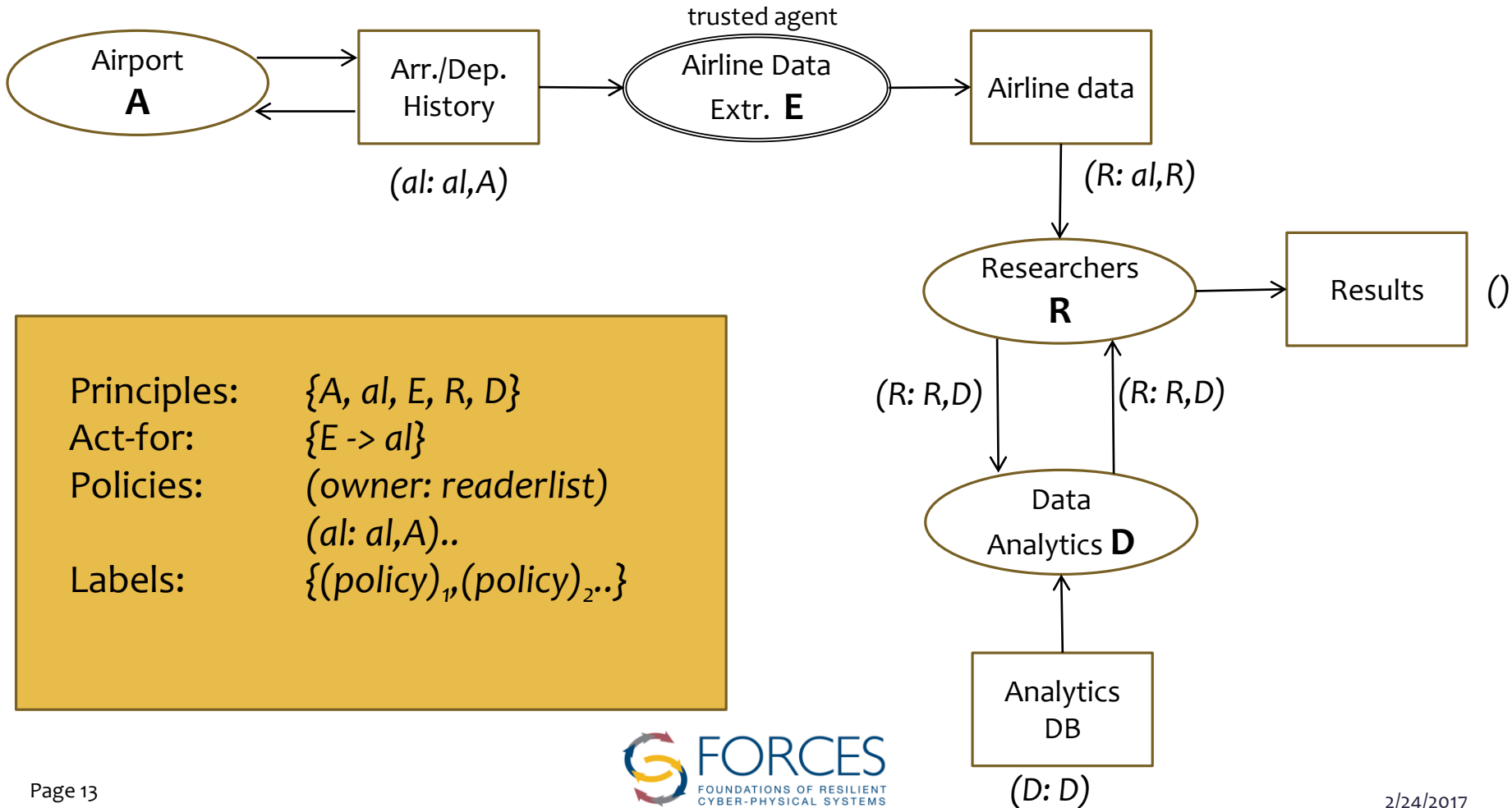
$$L_3 = L_1 \sqcup L_2$$

$$owners(L_1 \sqcup L_2) = owners(L_1) \cup owners(L_2)$$

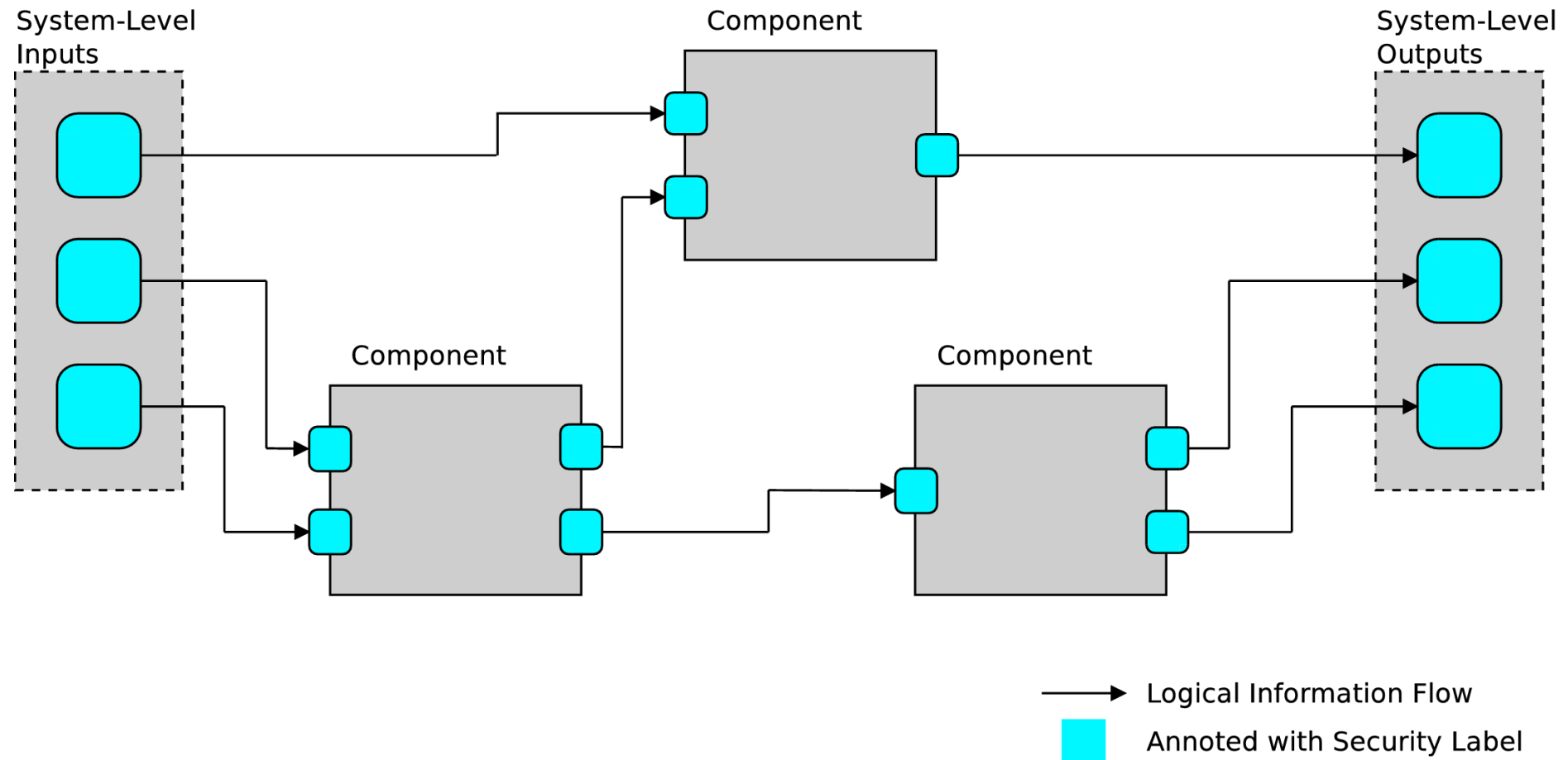
$$readers(L_1 \sqcup L_2, o) = readers(L_1, o) \cap readers(L_2, o)$$

(join L₁ and L₂ is the least restrictive label that maintains all the flow restrictions specified by L₁ and L₂)

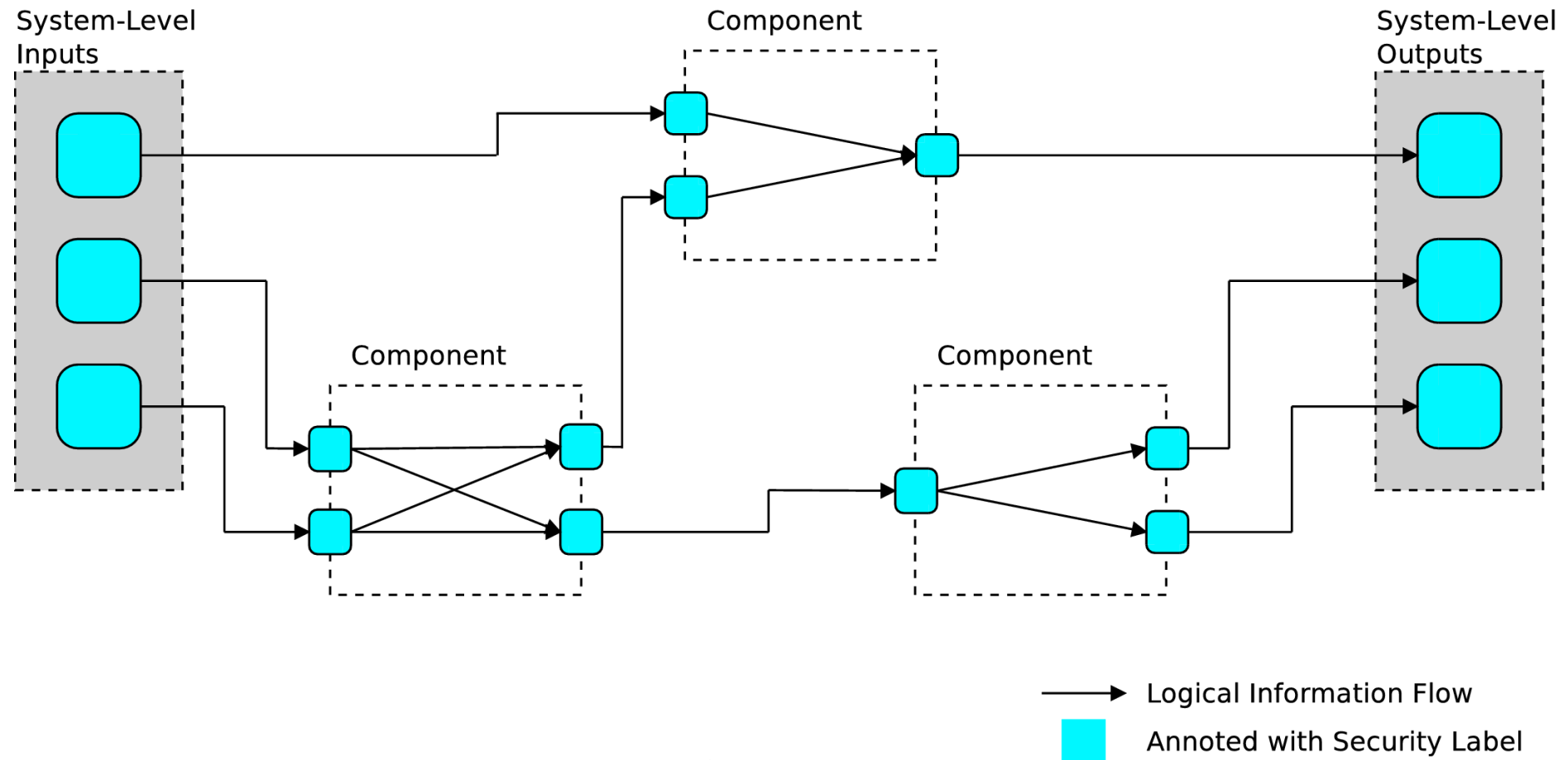
Simple Example



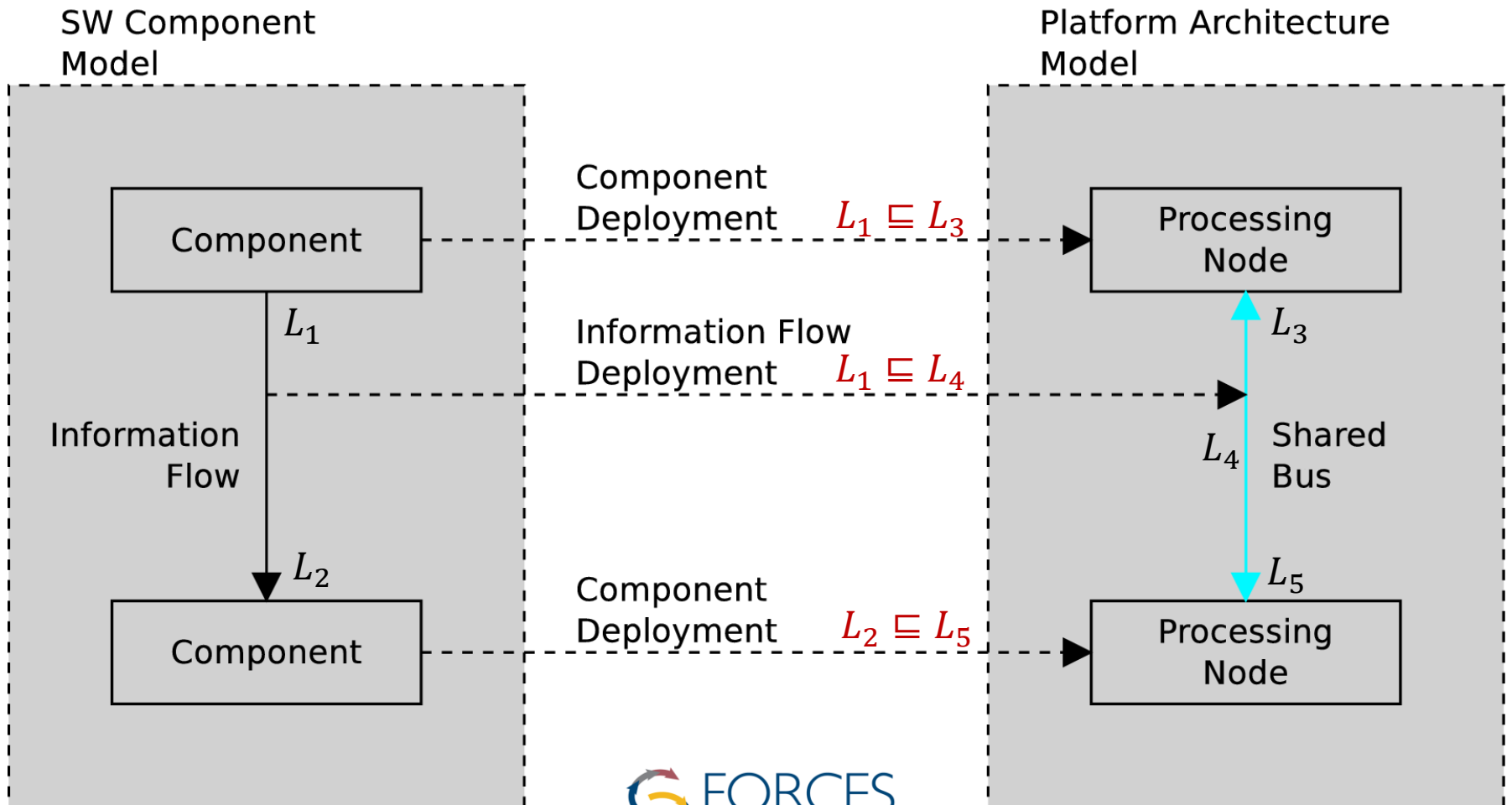
Information Flow Over SW Component Model



Information Flow Over SW Component Model



Information Flow Over System Platform -s



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FORMULA

- * Ethan Jackson (ISIS grad student 2004-2008; MSR 2009 – Present)
- * Algebraic Data Types (ADT) Open World Logic Programs (OLP) provide common semantic domain for DSMLs and model transformations.
- * Constraint Logic Programming provides execution semantics for model transformations.
- * Z3 backend for model finding.

Example: Deployments Domain

```
1:  domain Deployments
2:  {
3:    Service ::= new (name: String).
4:    Node ::= new (id: Natural).
5:    Conflict ::= new (s1: Service, s2: Service).
6:    Deploy ::= fun (s: Service => n: Node).
7:
8:    conforms no { n | Deploy(s, n), Deploy(s', n),
9:                  Conflict(s, s') }.
9: }
```

Example: Partial Model

```
1: partial model SpecificProblem of Deployments
2: {
3:     requires Deployments.conforms.
4:
5:     sVoice is Service("Voice Recognition").
6:     sDB is Service("Big Database").
7:     n0 is Node(0).
8:     n1 is Node(1).
9:     Conflict(sVoice, sDB).
10: }
```

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Principal Hierarchy

Stakeholders are denoted by principals, each uniquely identified by a name:

```
Principal ::= new (name:String).
```

A relation over principals:

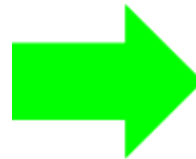
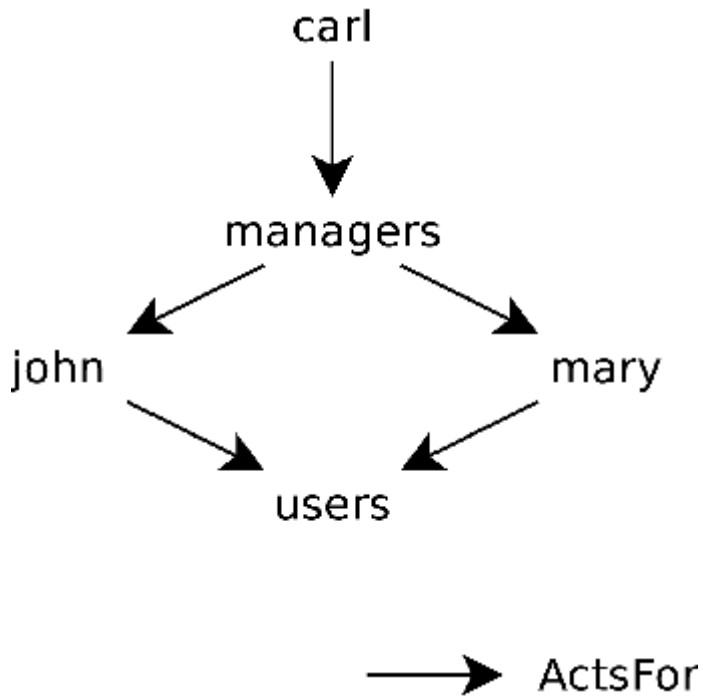
```
ActsFor ::= new (Principal, Principal).
```

The term $\text{ActsFor}(A, B)$ indicates that principal A is allowed to perform actions as if it were principal B.

The “ActsFor” relation is transitive and reflexive:

```
ActsForTR ::= (Principal, Principal).  
ActsForTR(x,x) :- x is Principal. //reflexivity  
ActsForTR(x,y) :- ActsFor(x,y).  
ActsForTR(x,z) :- ActsForTR(x,y), ActsFor(y,z). //transitivity
```

Principal Hierarchy Example



```
carl is Principal("carl").
managers is Principal("managers").
john is Principal("john").
mary is Principal("mary").
users is Principal("users").
ActsFor(carl, managers).
ActsFor(managers, john).
ActsFor(managers, mary).
ActsFor(john, users).
ActsFor(mary, users).
```

Policies and Labels

A policy consists of an owner principal and a set of allowed reader principals:

owner: reader1 reader2

A label is a (possibly empty) set of policies:

$L = \{ \text{policy1}; \text{policy2}; \dots \}$

Our encoding views a label as a tree where the label's identifier is the root, the policy owners make up the second level, and the corresponding readers make up the third level :

```
Label ::= new (name:String) .  
Policy ::= new (lbl:Label, owner:Principal) .  
Reader ::= new (pl:Policy, reader:Principal) .
```


Label Encoding Example

$L1 = \{ \text{sam: bob amy; john: bob} \}$



```
L1 is Label("L1").  
P1 is Policy(L1, Principal("sam")).  
Reader(P1, Principal("bob")).  
Reader(P1, Principal("amy")).  
P2 is Policy(L1, Principal("john")).  
Reader(P2, Principal("bob")).
```

Inferring Label Information

We can compute the effective readers set for each label:

```
EffReader(lbl, reader) :-  
  lbl is Label, reader is Principal, no CantRead(lbl, reader).  
CantRead(pl.lbl, r) :-  
  pl is Policy, r is Principal,  
  no { r' | ActsForTR(r, r'), Reader(pl, r') }.
```

We can compare the restrictiveness of labels based on their effective reader sets:

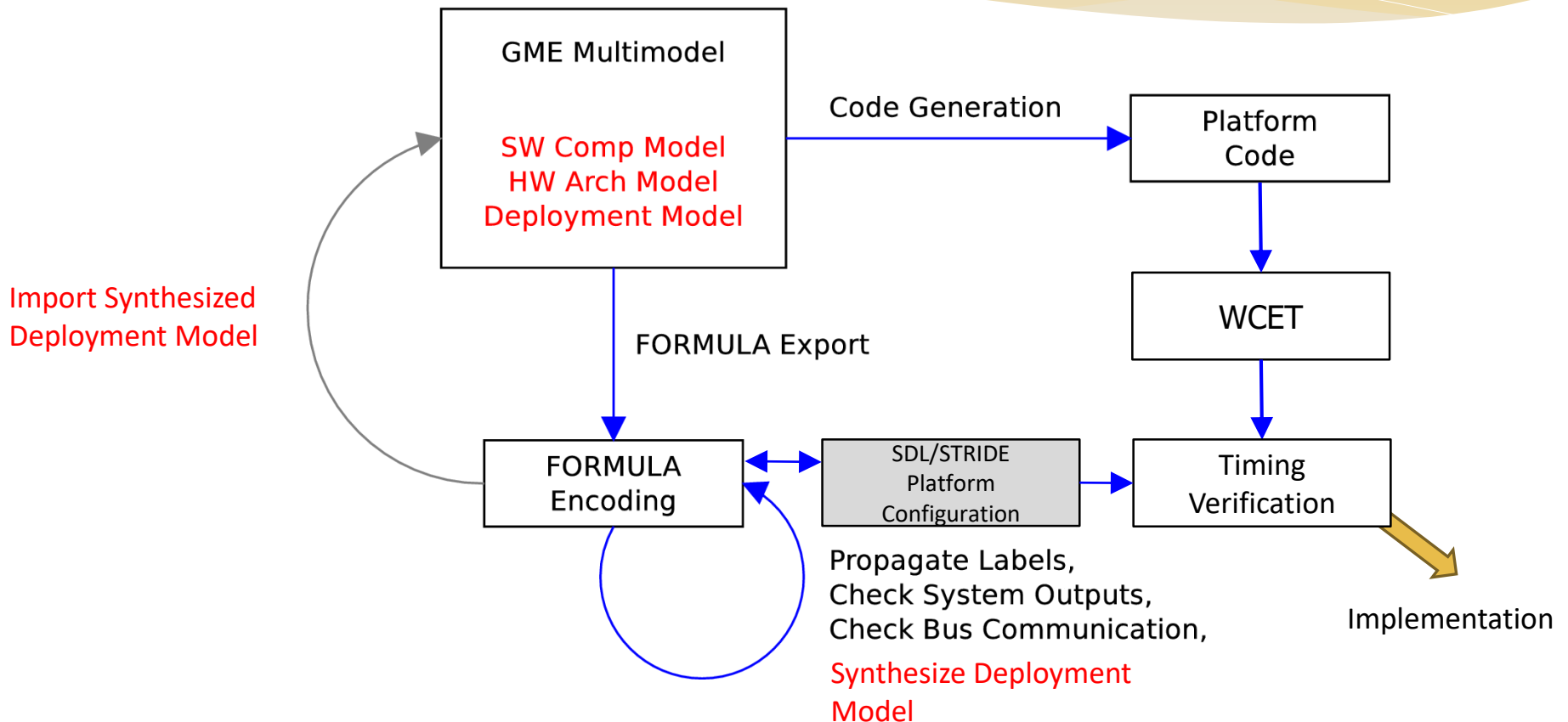
```
AtLeastAsRestrictive(lbl1, lbl2) :-  
  lbl1 is Label, lbl2 is Label,  
  no { x | EffReader(lbl1, x), CantRead(lbl2, x) }.
```

We can also “propagate” policies by computing the join (\sqcup) of two labels: the least restrictive label that is at least as restrictive as both labels.

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Workflow for Designing Secure Distributed Embedded Systems



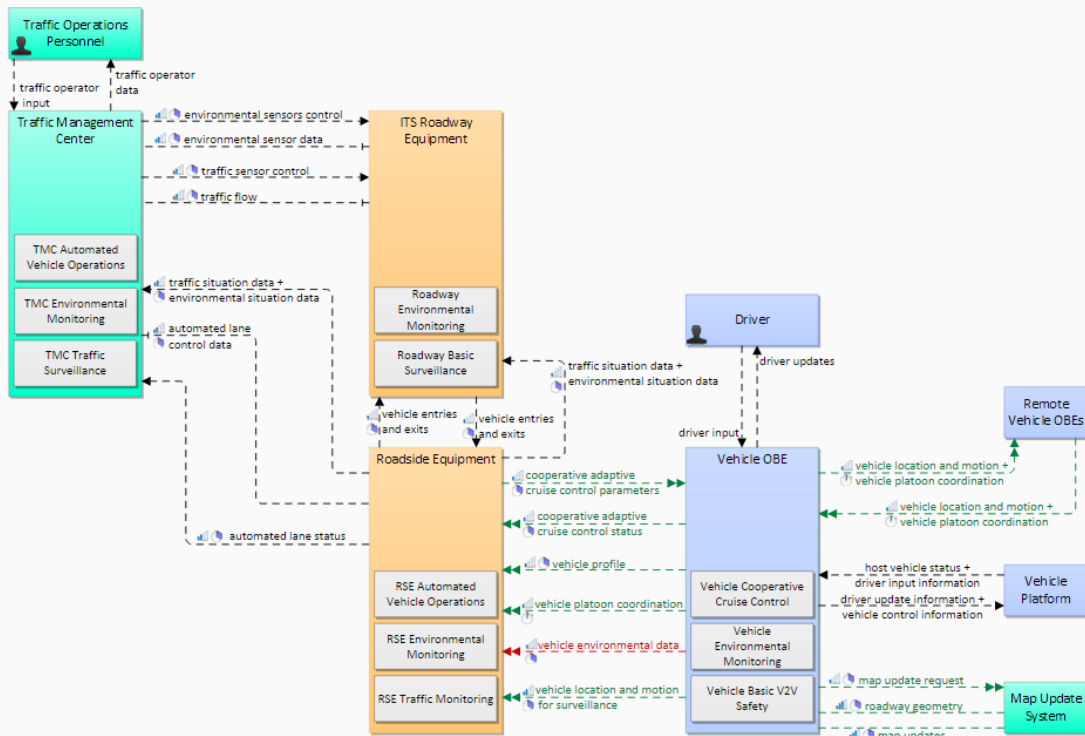
Test Cases – DOT/CVRIA

Physical

The physical diagram can be viewed in SVG or PNG format and the current format is SVG.

[SVG Diagram](#)

[PNG Diagram](#)



Eco-Cooperative Adaptive Cruise Control			
4	Physical	Jun 17, 2014	NAT

- Modeling Language Capture in GME
- Semantics in FORMULA
- DLM mapping
- Analysis Studies

Summary

Security Policies (EI)

integrity/confidentiality
Decentralized Label Model (DLM)

