



Optimization of Large-Scale Interdependent Systems: from Supermarket Refrigerators to Electrical Grids

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Trends in power and energy systems

I. Renewable sources: wind/solar generation

California: 33% by 2020



[wikipedia.org]

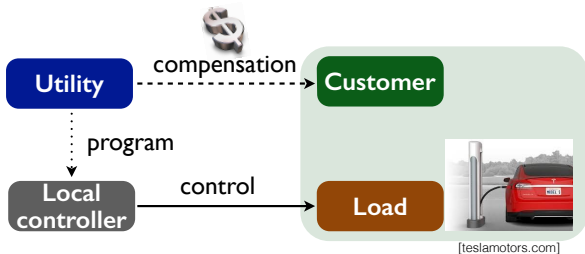
Trends in power and energy systems

1. Renewable sources: wind/solar generation

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2. Demand-side resources: air conditioners, EVs

Electric Vehicle-Grid Integration (VGI) [San Diego Gas & Electric]



Trends in power and energy systems

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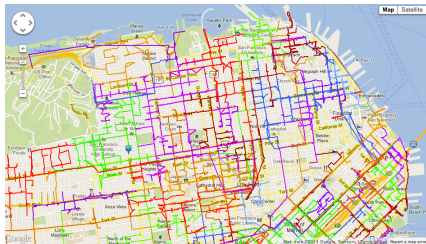
California: 33% by 2020

2. Demand-side resources: air conditioners, EVs

Electric Vehicle-Grid Integration (VGI) [San Diego Gas & Electric]

3. Automation

Distribution system automation [PG&E, CIEE]

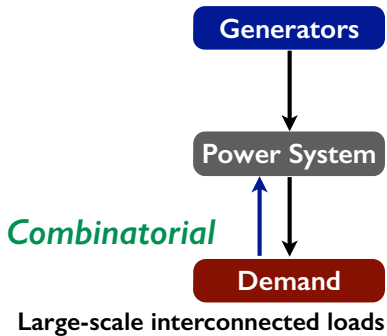


SF distribution networks [pge.com]



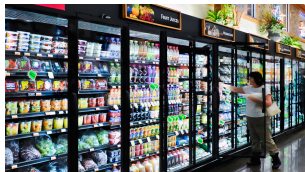
micro synchrophasor (sensor):
distribution grid visibility [pqubepmu.com]

Challenge: system interdependency

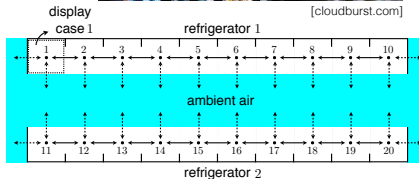


Supermarket refrigeration systems consume 7% of total commercial energy consumption in the US

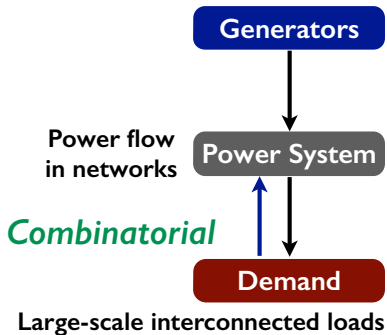
DOE, 2014



[cloudburst.com]

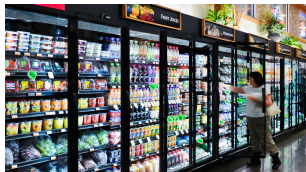


Challenge: system interdependency

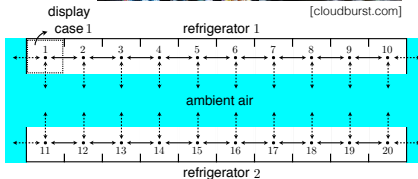


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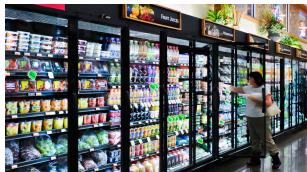
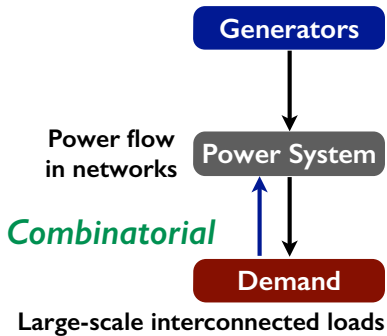
DOE, 2014



[cloudburst.com]



Challenge: system interdependency



[cloudburst.com]

Scalable optimization tools for interdependent systems

Towards control mechanisms for sustainable power systems

Goal:

- ▶ **real-time optimization of interdependent systems (e.g., loads, power networks)**

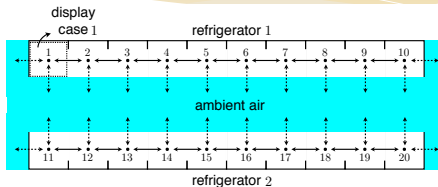
Challenges:

- ▶ **large-scale discrete control**
- ▶ **interdependent dynamics**
- ▶ **real-time requirements**

Engineering objectives:

Performance (optimality) + Scalability (computation)

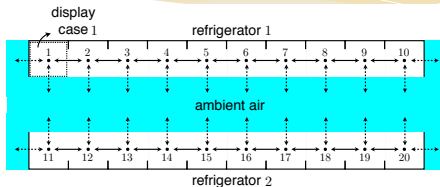
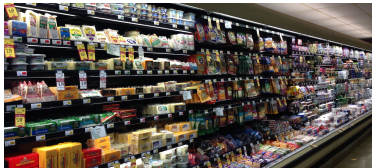
ON/OFF control of supermarket refrigeration systems



7% of the total commercial energy consumption in the US [DOE, 2012]

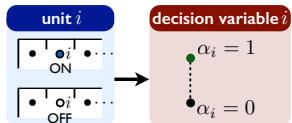
Good demand response potential: Pacific Gas & Electric - Safeway

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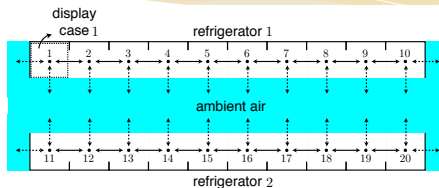
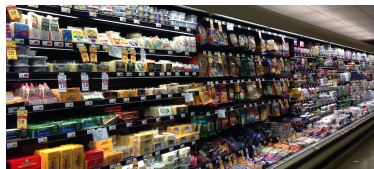


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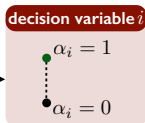
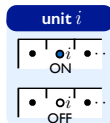


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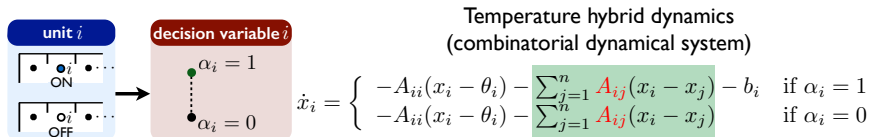
Temperature hybrid dynamics
(combinatorial dynamical system)

$$\dot{x}_i = \begin{cases} -A_{ii}(x_i - \theta_i) - \sum_{j=1}^n A_{ij}(x_i - x_j) - b_i & \text{if } \alpha_i = 1 \\ -A_{ii}(x_i - \theta_i) - \sum_{j=1}^n A_{ij}(x_i - x_j) & \text{if } \alpha_i = 0 \end{cases}$$

ON/OFF control of supermarket refrigeration systems

Demand Response Problem

One-step look ahead optimization at k (receding-horizon)

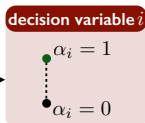
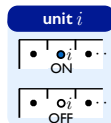


ON/OFF control of supermarket refrigeration systems

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$$\text{lower bound} \leq \underbrace{\# \text{ of ON units}}_{\sum_{i=1}^n \alpha_i} \leq \text{upper bound}$$



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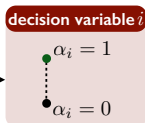
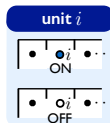
ON/OFF control of supermarket refrigeration systems

Demand Response Problem

One-step look ahead optimization at k (receding-horizon)

$$\max_{\alpha \in \{0,1\}^m} \int_{(k-1)\Delta t}^{k\Delta t} \text{Freshness}(x(t)) dt$$

subject to $\text{lower bound} \leq \underbrace{\# \text{ of ON units}}_{\sum_{i=1}^n \alpha_i} \leq \text{upper bound}$



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Towards scalability: linear approximation

Optimization of CDS

$$\max_{\alpha \in \{0,1\}^m} J(\alpha) := \int_0^T r(x^\alpha) dt + q(x^\alpha(T))$$

subject to $\mathbf{A}\alpha \leq \mathbf{b}$

$$\dot{x}^\alpha(t) = f(x^\alpha(t), \alpha) \quad \text{combinatorial dynamical systems (CDS)}$$

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$\bar{\alpha}$: linearization pt

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Linear approximation

$$\max_{\alpha \in \{0,1\}^m} DJ(\bar{\alpha})^\top \alpha$$

subject to $\mathbf{A}\alpha \leq \mathbf{b}$

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Q) How to define $DJ(\bar{\alpha})$?

Towards scalability: linear approximation

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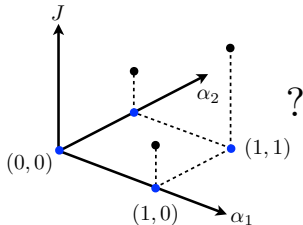
$\bar{\alpha}$: linearization pt



Linear approximation

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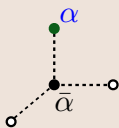
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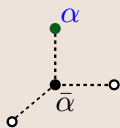
Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



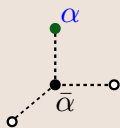
Space of vector fields

$$f(\cdot, \alpha) \bullet$$

$$f(\cdot, \bar{\alpha}) \bullet$$

Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



Space of vector fields

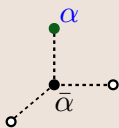
$$f(\cdot, \alpha) \bullet$$

$$f^{\epsilon(\bar{\alpha}, \alpha)}(\cdot) \bullet$$

$$f(\cdot, \bar{\alpha}) \bullet$$

Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



Space of vector fields

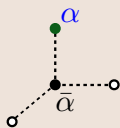
$$f(\cdot, \alpha) \bullet$$

$$f^{\epsilon(\bar{\alpha}, \alpha)}(\cdot) \bullet$$

$$f(\cdot, \bar{\alpha}) \bullet \quad \epsilon \rightarrow 0$$

Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



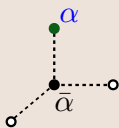
Space of vector fields

$$\begin{aligned} f(\cdot, \alpha) & \bullet \quad \epsilon \rightarrow 1 \\ f^{\epsilon(\bar{\alpha}, \alpha)}(\cdot) & \bullet \\ f(\cdot, \bar{\alpha}) & \bullet \quad \epsilon \rightarrow 0 \end{aligned}$$

A diagram showing three points representing vector fields. The top point is a brown dot labeled $f(\cdot, \alpha)$ with $\epsilon \rightarrow 1$ to its right. The middle point is a blue dot labeled $f^{\epsilon(\bar{\alpha}, \alpha)}(\cdot)$. The bottom point is a black dot labeled $f(\cdot, \bar{\alpha})$ with $\epsilon \rightarrow 0$ to its right. A vertical dashed line connects the brown dot to the black dot, with the blue dot in the middle.

Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space

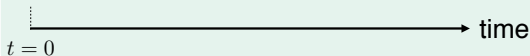


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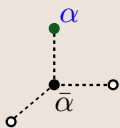
A vertical dashed line connects the three dots, with an arrow pointing downwards from the top dot to the bottom dot.

Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



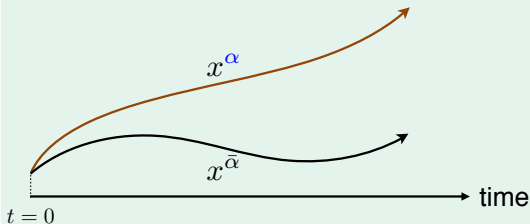
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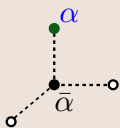


Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



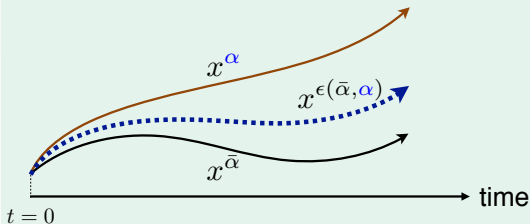
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A vertical dashed line with arrows at both ends connects the three points, indicating a transition from $\epsilon \rightarrow 1$ at the top to $\epsilon \rightarrow 0$ at the bottom.

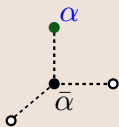


Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



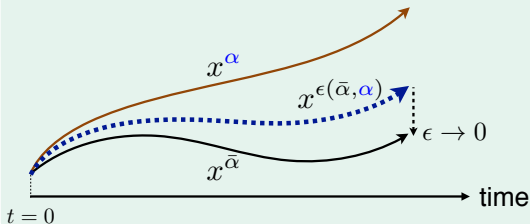
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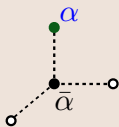


Space of dynamical systems



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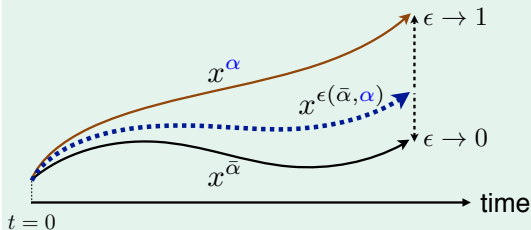
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A vertical dashed line with arrows at both ends connects the three points, indicating a transition from $\epsilon \rightarrow 0$ at the bottom to $\epsilon \rightarrow 1$ at the top.

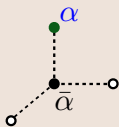


Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



Nonstandard (NS)
derivative

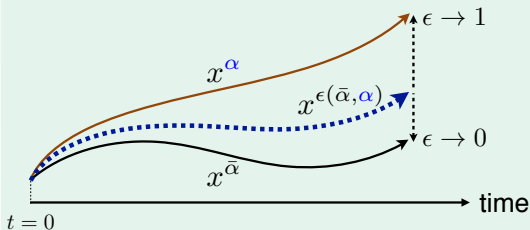
$$D^{\text{NS}} J(\bar{\alpha})$$

Space of vector fields

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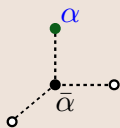


Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



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A vertical stack of three points representing vector fields. The top point is labeled $f(\cdot, \alpha)$ and has a dot with $\epsilon \rightarrow 1$ to its right. The middle point is labeled $f^{\epsilon(\bar{\alpha}, \alpha)}(\cdot)$ and has a dot. The bottom point is labeled $f(\cdot, \bar{\alpha})$ and has a dot with $\epsilon \rightarrow 0$ to its right. A vertical dashed line connects the top and bottom points, with a right-pointing arrow in the middle.

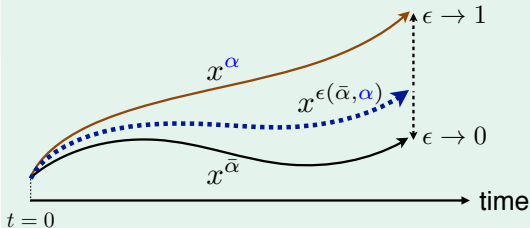
Nonstandard (NS)
derivative

$$D^{\text{NS}} J(\bar{\alpha})$$

Linear binary optimization

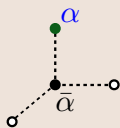
$$\begin{aligned} \max_{\alpha \in \{0, 1\}^m} \quad & D^{\text{NS}} J(\bar{\alpha})^\top \alpha \\ \text{subject to} \quad & \mathbf{A}\alpha \leq \mathbf{b} \end{aligned}$$

Space of dynamical systems



Nonstandard derivative: variation in vector fields

$\{0, 1\}^m$ discrete space



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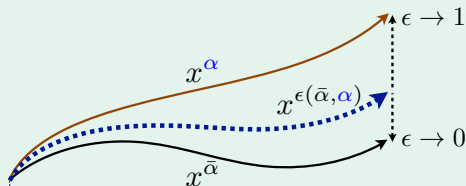
Linear binary optimization

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Space of dynamical systems



Contribution I.

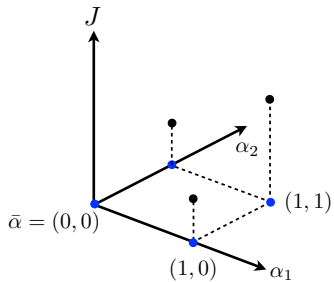
Scalability: linear approximation

Efficiency: no need to repeatedly solve ODEs

[Yang, Burden, Sastry, Tomlin, CDC, 2013]

[Yang, Burden, Rajagopal, Sastry, Tomlin, IEEE Trans. Automatic Control, conditionally accepted (arXiv:1409.7861)]

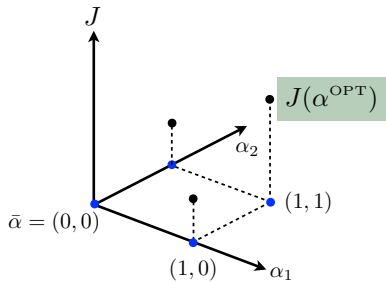
Suboptimality bound



α^{OPT} : optimal solution

α^* : approximate solution

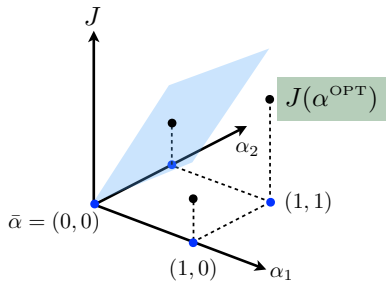
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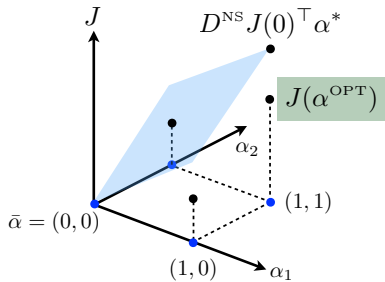
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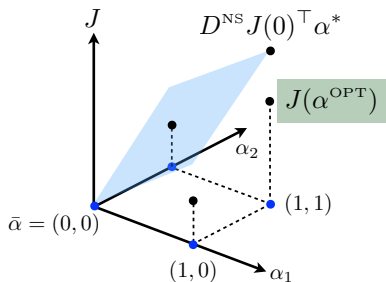
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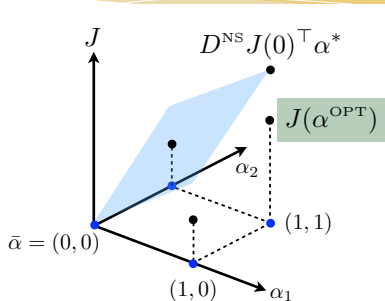
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If $J(\alpha) - J(\bar{\alpha}) \leq D^{\text{NS}} J(\bar{\alpha})^\top (\alpha - \bar{\alpha}) \quad \forall \alpha \in \{0, 1\}^m$,
then the following suboptimality bound holds:

$$\rho J(\alpha^{\text{OPT}}) \leq J(\alpha^*), \quad \rho := \frac{J(\alpha^*)}{D^{\text{NS}} J(\bar{\alpha})^\top (\alpha^* - \bar{\alpha})}.$$

Suboptimality bound



\hat{J} : reformulated problem

$$D^{\text{NS}} J \equiv D^{\text{S}} \hat{J}$$

$$J|_{\{0,1\}^m} \equiv \hat{J}|_{\{0,1\}^m}$$

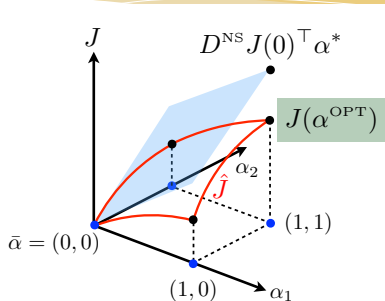
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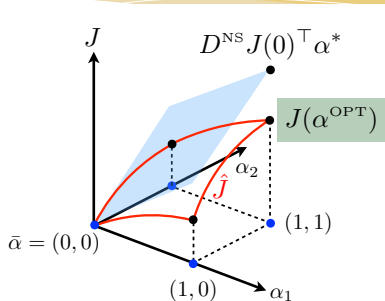
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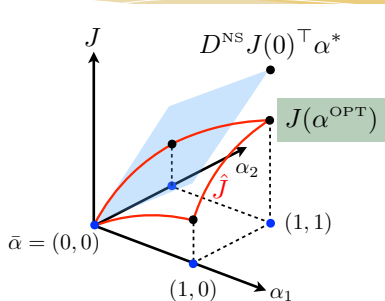
[Yang, Burden, Rajagopal, Sastry, Tomlin, IEEE Trans. Automatic Control, conditionally accepted (arXiv:1409.7861)]

Theorem (Suboptimality bound)

*If the reformulated problem is concave,
then the following suboptimality bound holds:*

$$\rho J(\alpha^{\text{OPT}}) \leq J(\alpha^*), \quad \rho := \frac{J(\alpha^*)}{D^{\text{NS}} J(\bar{\alpha})^\top (\alpha^* - \bar{\alpha})}.$$

Suboptimality bound



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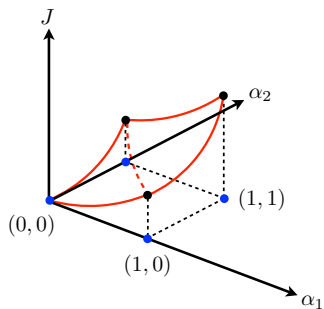
Contribution IV.

Performance guarantee: suboptimality bound

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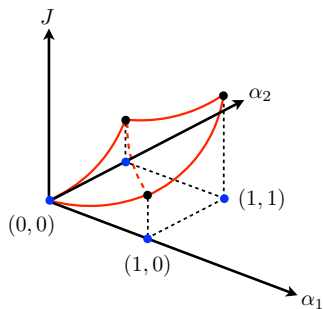
Example



$$x^\alpha = \alpha_1^2 + \alpha_2^2$$

$$J(\alpha) = x^\alpha - \frac{\alpha_1^2 + \alpha_2^2}{2}$$

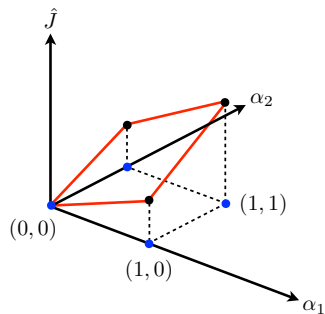
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Reformulated



ON/OFF control of supermarket refrigeration systems

Computation time (2.3GHz Intel Core i7, 16GB RAM, MATLAB):

($m = 20$) **Proposed:** 0.015s, **Greedy:** 0.57s, **Exhaustive search:** 3112s

($m = 1000$) **Proposed:** 0.81s

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90+% of oracle's performance

65+% suboptimality bound

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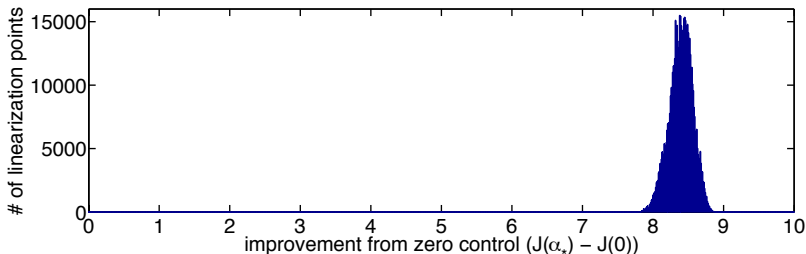
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Robustness with respect to the linearization point

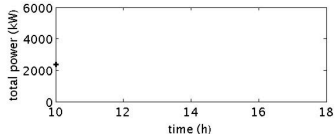
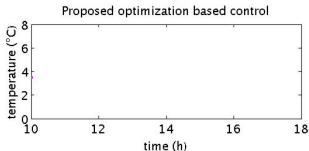
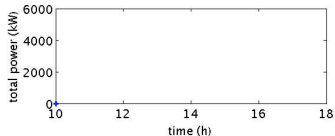
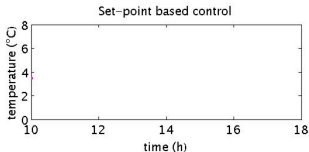


Energy efficiency and peak load reduction

(per refrigerator)	energy	peak demand charge	reserve	arbitrage
Set-point based	143MWh/yr	\$720/yr		
Proposed	137MWh/yr	\$338/yr		

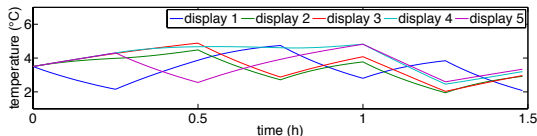
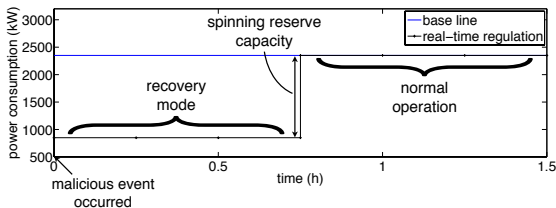
—display 1 —display 2 —display 3 —display 4 —display 5

synchronization [Sarabia et al., 2009]



Spinning reserve services to the electrical grids

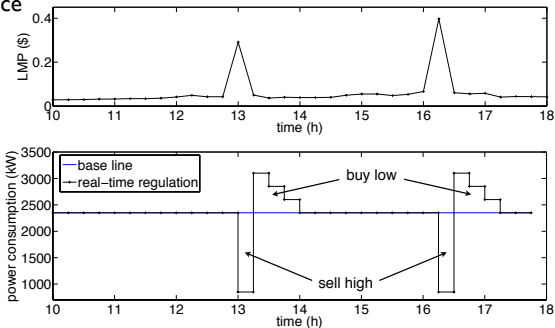
(per refrigerator)	energy	peak demand charge	reserve	arbitrage
Set-point based	143MWh/yr	\$720/yr	N/A	
Proposed	137MWh/yr	\$338/yr	15kW	



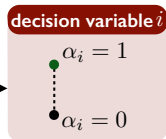
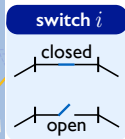
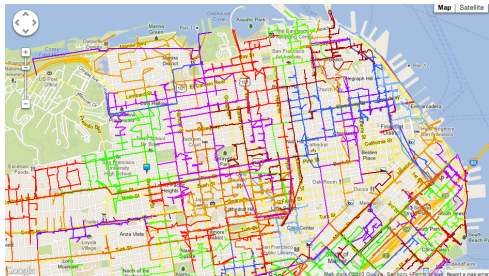
Energy arbitrage in wholesale electricity markets

(per refrigerator)	energy	peak demand charge	reserve	arbitrage
Set-point based	143MWh/yr	\$720/yr	N/A	N/A
Proposed	137MWh/yr	\$338/yr	15kW	\$3201/yr

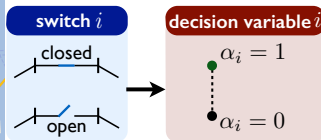
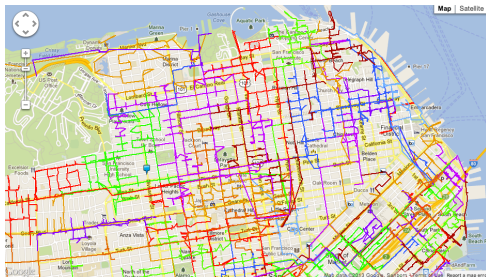
wholesale price



Power network topology optimization



Power network topology optimization



Power losses	33 nodes	94 nodes	118 nodes	880 nodes
Initial	203kW	532kW	1297kW	895kW
lower bound	123kW	463kW	820kW	463kW
proposed	161kW	471kW	898kW	484kW
saving	\$37K/yr	\$53K/yr	\$350K/yr	\$360K/yr

[Baran, Wu, 1989] [Chiou, Chung, Su, 2005] [Zhang, Fu, Zhang, 2007]

[REDS: repository of distribution systems, <http://venus.ece.ndsu.nodak.edu/~kavasseri/reds.html>]

Conclusion

- ▶ Goal:
real-time optimization of interdependent systems
- ▶ Contribution:
 1. scalability & efficiency
 2. performance guarantee
- ▶ Computation & validation:
 1. online computation
 2. 1000-dimensional problems in 1 sec.
- ▶ Future work:
 1. experiments with supermarket refrigerators
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– Towards sustainable CPS interfaced with human decision-makers

- ▶ **The Lab:**
supermarket refrigerators, air conditioners ('living' laboratory)
- ▶ **Viterbi School of Engineering:**
USC Dynamic Demand Response, USC Microgrids
- ▶ **Los Angeles Department of Water & Power**
- ▶ **Looking for highly motivated students!**

