University at Buffalo The State University of New York

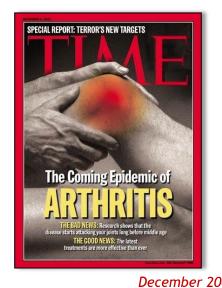
Cyber Physical System: Home-based Rehabilitation System for Knee Deficient Patients

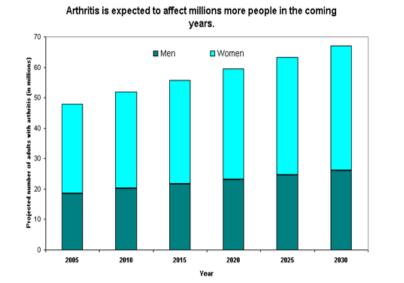
MOTIVATION

570

Osteo-Arthritis (OA) impacts 20 million people (7.35%) and 80,000 Anterior Cruciate Ligament (ACL) injuries occur in the USA per year

By 2030, nearly 67 million diagnosed with OA





Clinical gait analysis currently involves high-fidelity and expensive motion- and force - capture by skilled practitioners





Kinect Sensor & Wii Balance Board

Some concepts for interactive home-based diagnosis for knee deficit patients are under development





UWe evaluate potential of commercial-off-the-shelf DESIGN – KNEE EXOSKELETON (COTS) devices – Kinect, Wii balance board – as a viable assessment tool for home-based system.

ACKNOWLEDGEMENT

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PUBLICATIONS

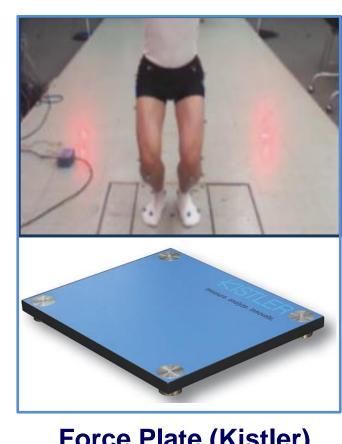
- S. Jun, X. Zhou, D. Ramsey, V. Krovi, Knee Exoskeleton Design with Parallel Coupled Compliant Plate (PCCP) Mechanism and Pennate Elastic Band (PEB) Spring, IEEE/RSJ International Conference on Intelligent Robots and Systems, Chicago, IL, September 14-18, 2014 (on processing).
- S. Jun, X. Zhou, D. Ramsey, V. Krovi, Quantitative Methodology for Knee Exoskeleton Design, ASME 2014 International Design Engineering Technical Conferences and Computers in Engineering Conference, Buffalo, NY, August 17-20 2014 (on processing).
- S.K. Jun, S. Kumar, X. Zhou, D. Ramsey and V. Krovi, Automation for Individualization of Kinect-based Quantitative Progressive Exercise Regimen, IEEE International Conference on Automation Science and Engineering, Madison WI, August 17-21 2013.
- S.K. Jun, X. Zhou, D. Ramsey and V. Krovi, Kinetostatic Design-Refinement of Articulated Knee Braces, ASME 2013 International Design Engineering Technical Conferences and Computers in Engineering Conference, Portland Oregon, August 4-7 2013.
- S.K. Jun, X. Zhou, D. Ramsey and V. Krovi, A Comparative Study of Human Motion Capture and Analysis Tools, Digital Human Modeling Symposium, Ann Arbor MI, June 11-13 2013.

Principal Investigator/Professor Dr. Venkat N. Krovi vkrovi@buffalo.edu http://www.eng.buffalo.edu/~vkrovi/ Dr. Daniel K. Ramsey dkramsey@buffalo.edu http://goo.gl/Pcgs5

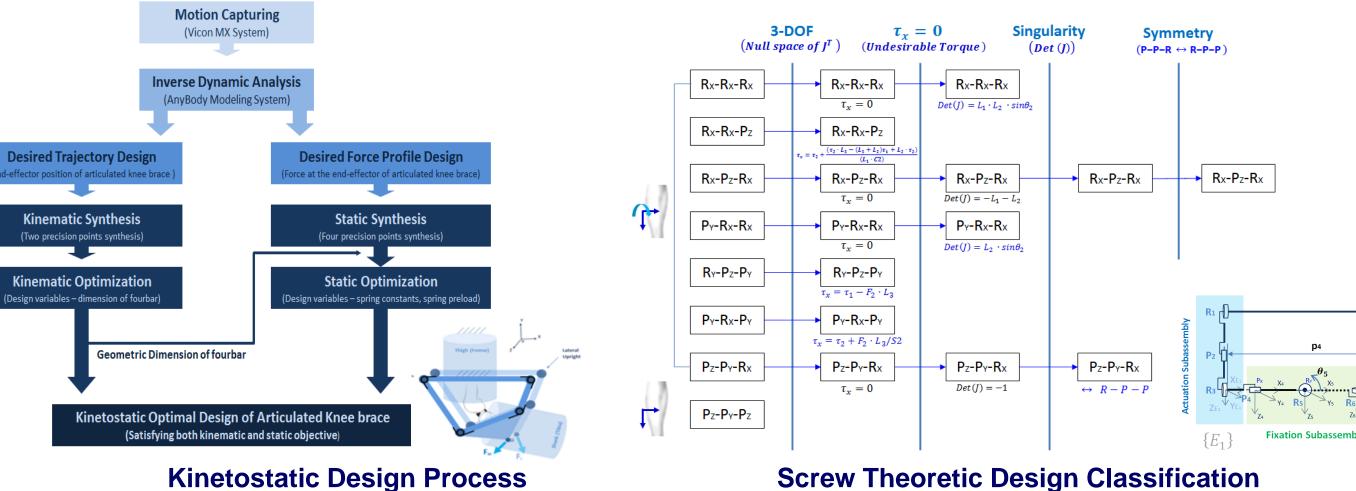












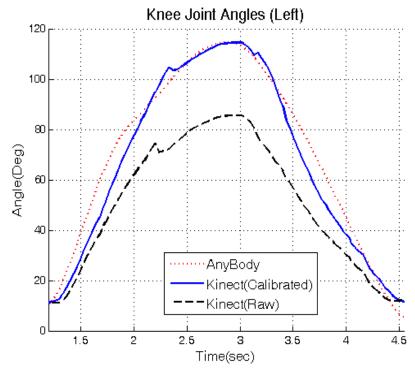


Sliding Part

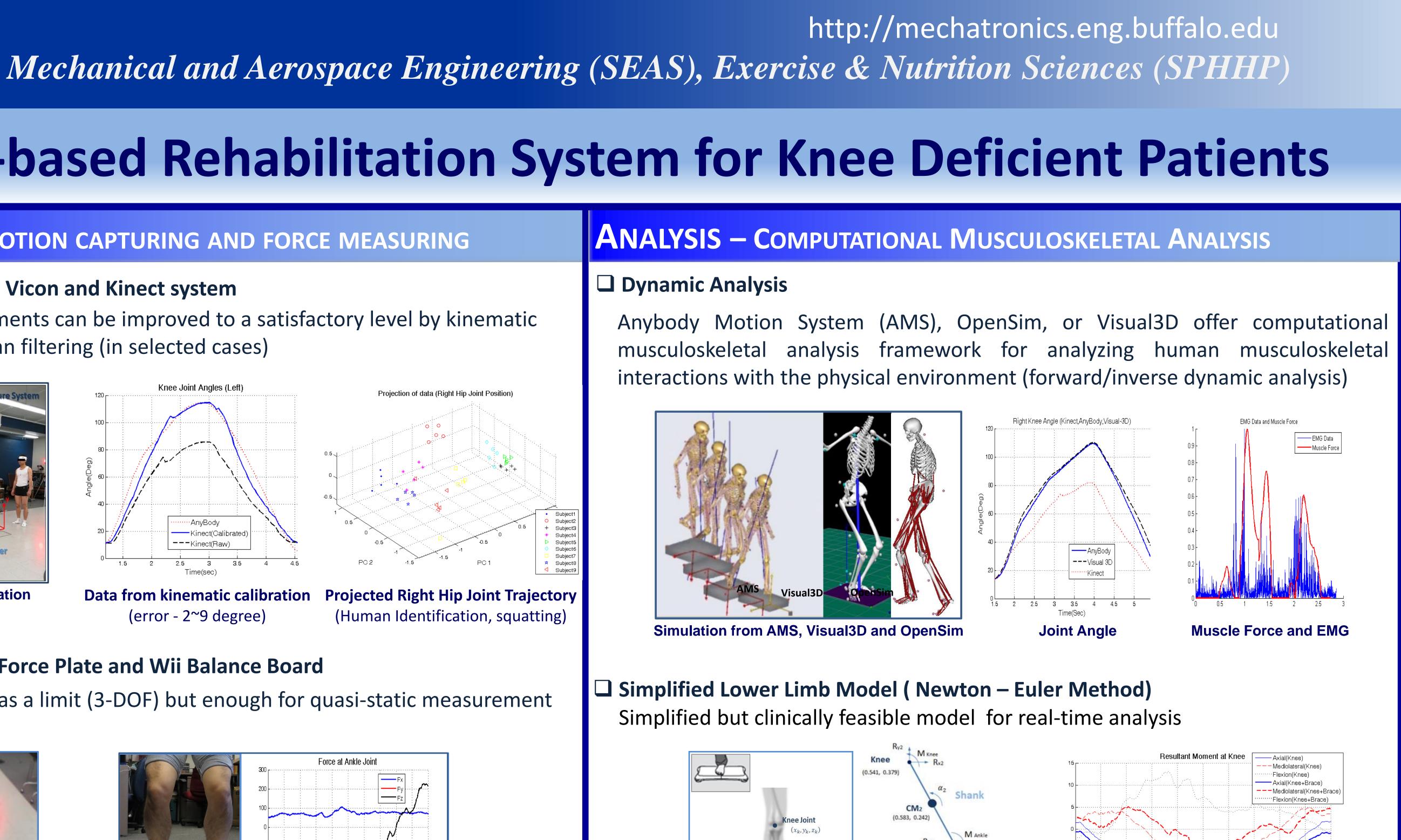
MEASURING – MOTION CAPTURING AND FORCE MEASURING

 Motion capture from Vicon and Kinect system Raw Kinect measurements can be improved to a satisfactory level by kinematic calibration and Kalman filtering (in selected cases)

MoCap System Configuration

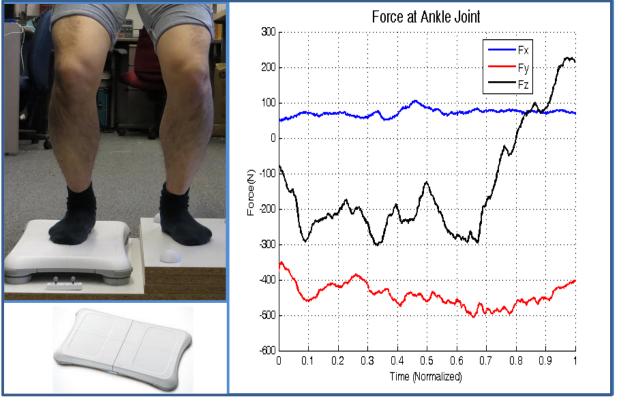


(error - 2~9 degree)



Force Measure from Force Plate and Wii Balance Board Will balance board has a limit (3-DOF) but enough for quasi-static measurement

Force Plate (Kistler)

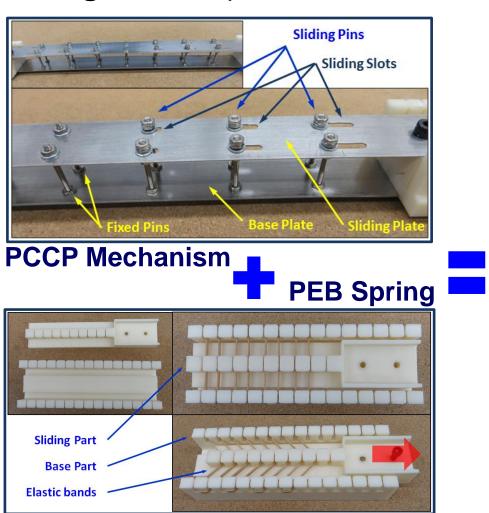


Wii Balance Board Setup and Force at Ankle Joint

Kinetostatic Optimization & Screw Theoretic Analysis Quantitative and systematic design process for knee exoskeleton

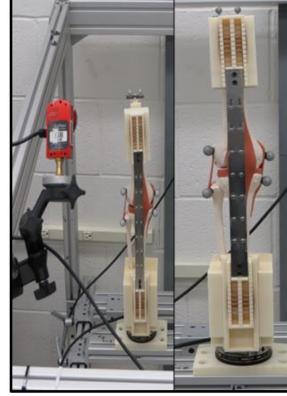
Compliant/Selectively Stiff/Lightweight Knee Exoskeleton

Parallel Coupled Compliant Plate (PCCP) Mechanism and Pennate Elastic Band (PEB) Spring (Extreme stiffness at excessive joint angle, assistive load at normal motion range, light weight – 143g, 0.32lbs)



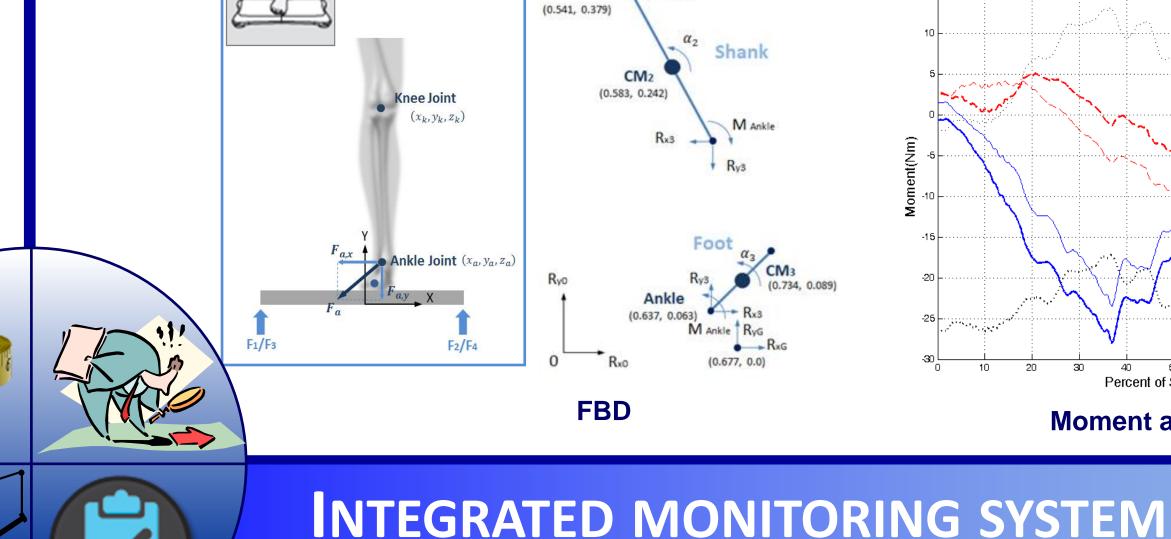


PCCP/PEB Knee Exoskeleton



Performance Test

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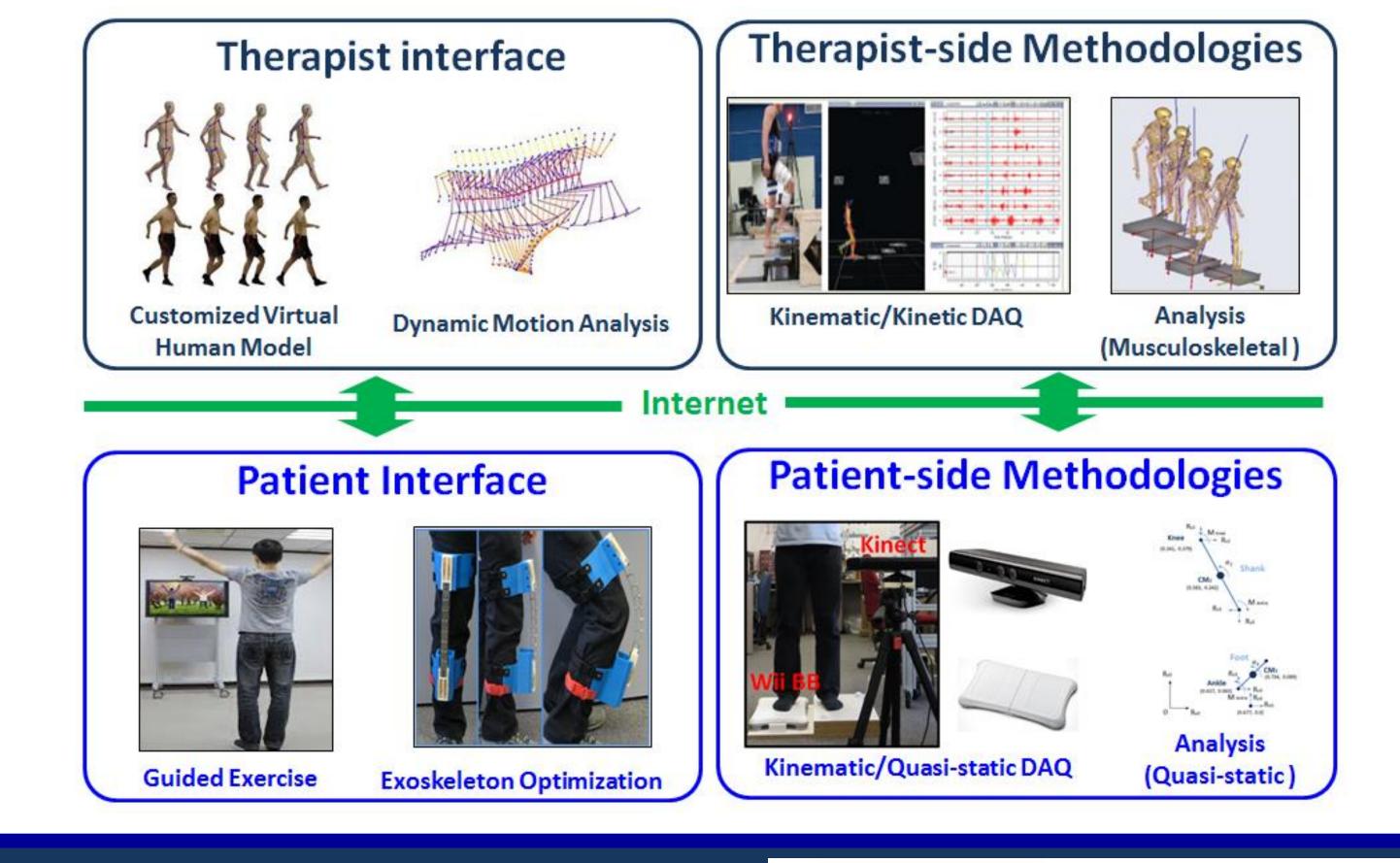


Remotely Adjustable Smart Knee Exoskeleton

Triple convergence of miniaturization of sensing/actuation coupled with advances in computing and communication creates a class of smart, lightweight, wearable and yet adaptive, versatile and reprogrammable rehabilitative devices

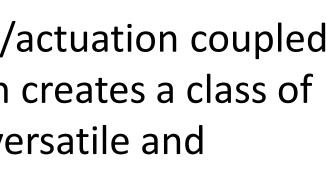
Cyber Physical Framework

Home-based rehabilitation programs are realized by launching of smart embedded products such as Kinect and Wii Balance System





Percent of Squat Cycle Moment at Knee Joint



Automation

Robotics

022 Furnas, State University of New York at Buffalo, Buffalo, NY 14260

Mechatronics Lab