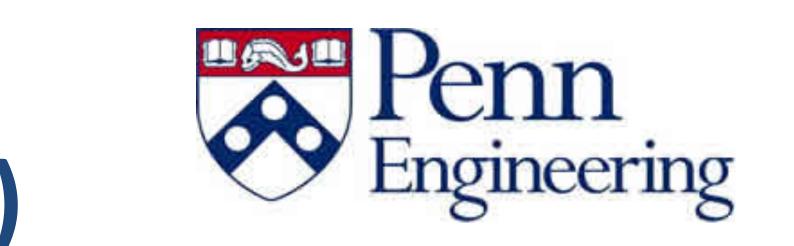
CPS: Synergy: Collaborative Research: Trustworthy Composition of Dynamic App-Centric Architectures for Medical Application Platforms (NSF CNS-1239543/1239324)

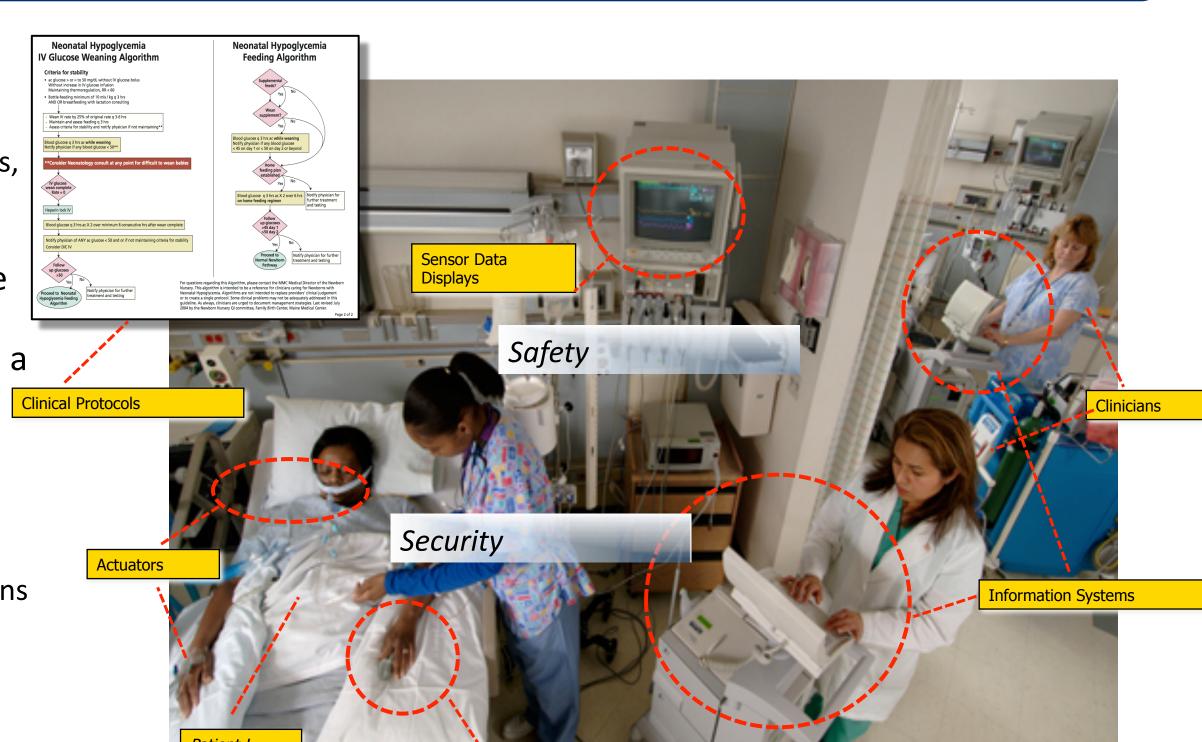


CPS PRINCIPAL INVESTIGATOR MEETING

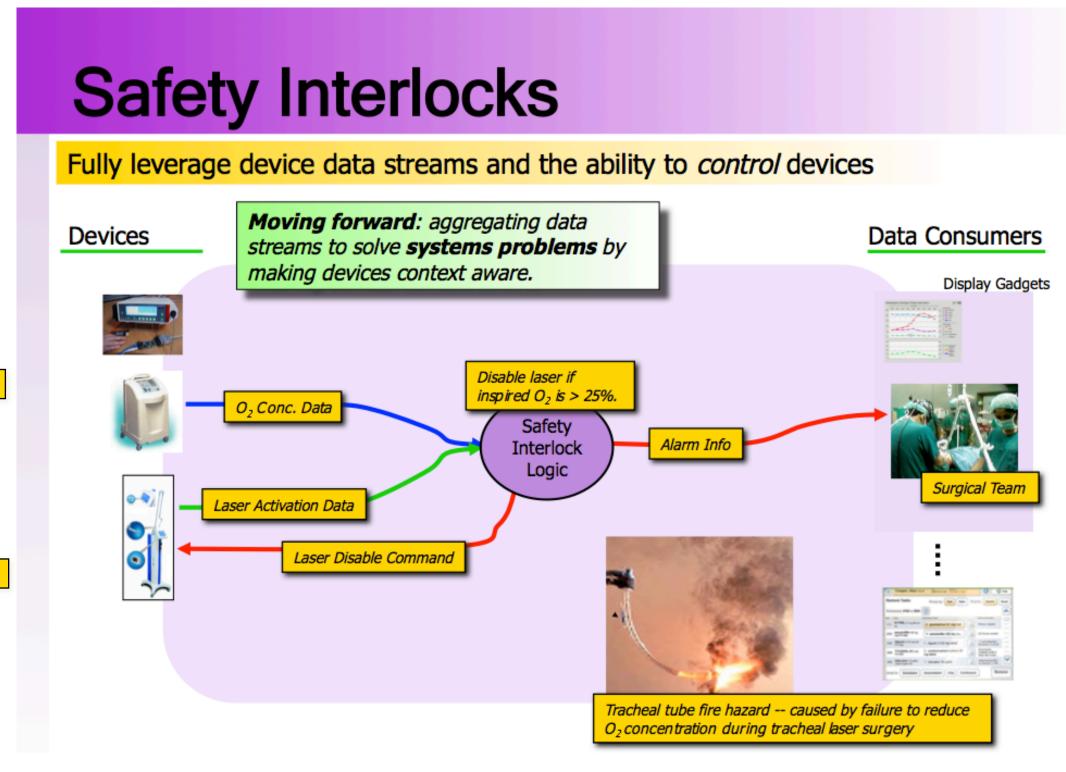
Lead PI: John Hatcliff (KSU – hatcliff@ksu.edu), PI: Insup Lee (U Penn)

Lack of "System of Systems" Support

- Delivering modern medical care involves complex cyber-physical systems...
- many medical devices, electronic medical records, clinicians/care-givers ...all working together to achieve a goal
- Although most modern medical devices have some form of connectivity, they are not integrated so that they can work together as a
- devices are "unaware of their context", e.g., details of patient parameters, history, current
- procedures they may impact/distort readings data from multiple devices is not combined to produce more meaningful information to clinicians
- actions of multiple devices cannot be automatically coordinated to achieve greater safety and efficiency



What Could be Achieved if Devices formed a System of Systems (SoS)?



MDCF Platform

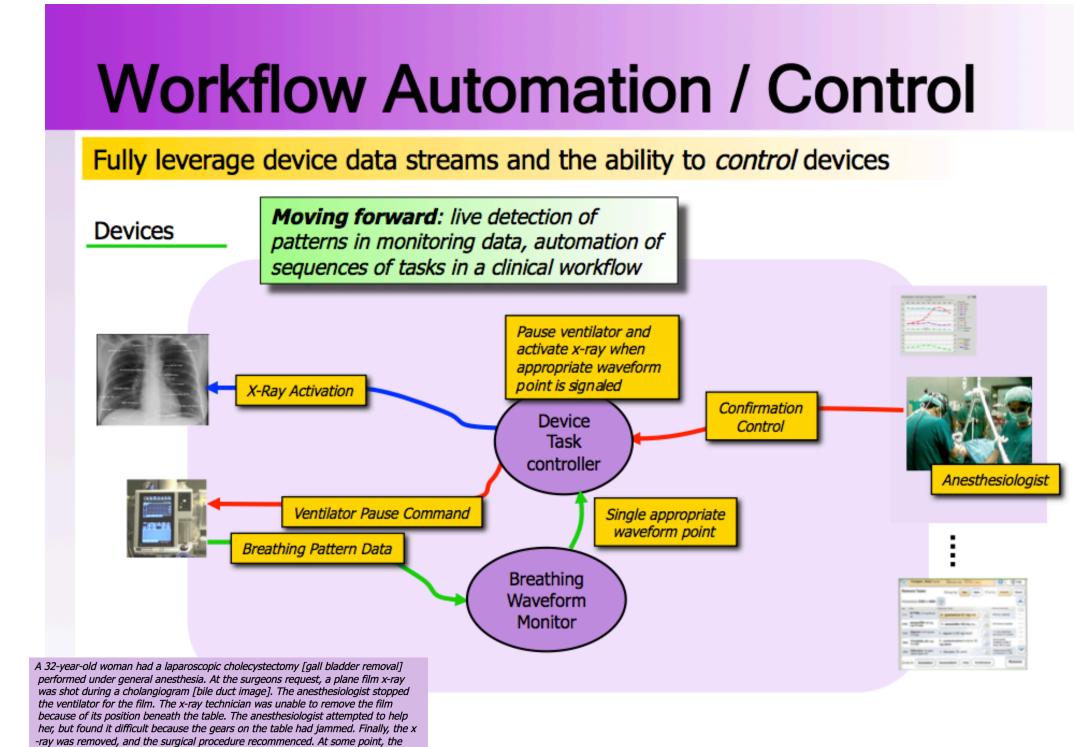
Verification

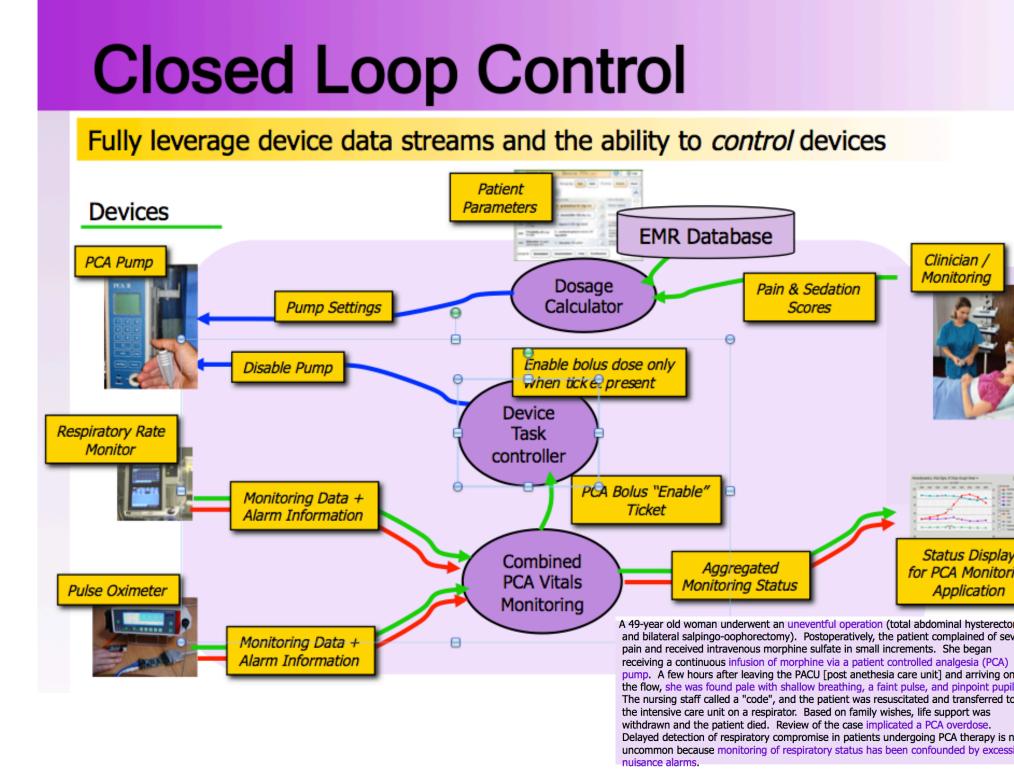
Device configuration

admission control

Device connection

protocols





There is no means to integrate devices and information systems and coordinate their actions as a cyber-physical system of systems

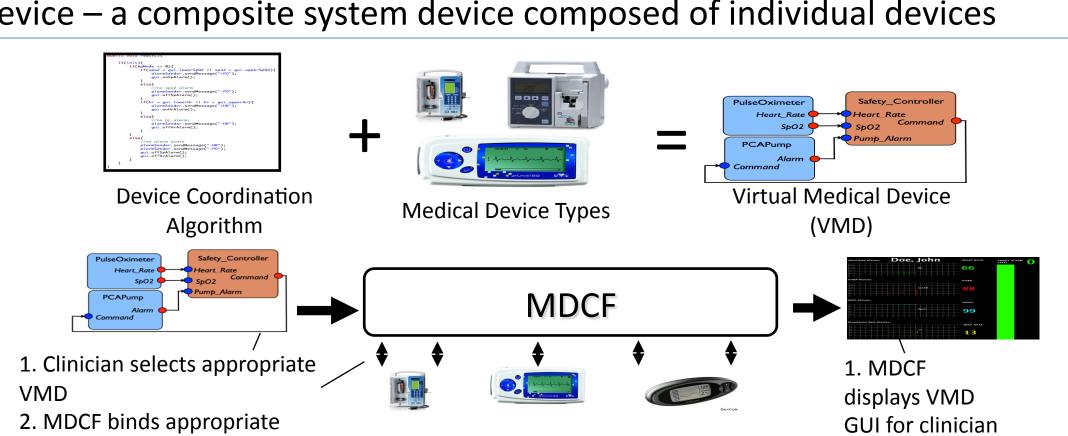
Medical Application Platforms (MAPs)

The Medical Device Coordination Framework (MDCF)

- Our project is developing an open source Medical Device Coordination Framework – a medical application platform (MAP) for integrating medical devices into systems
- The MDCF provides..

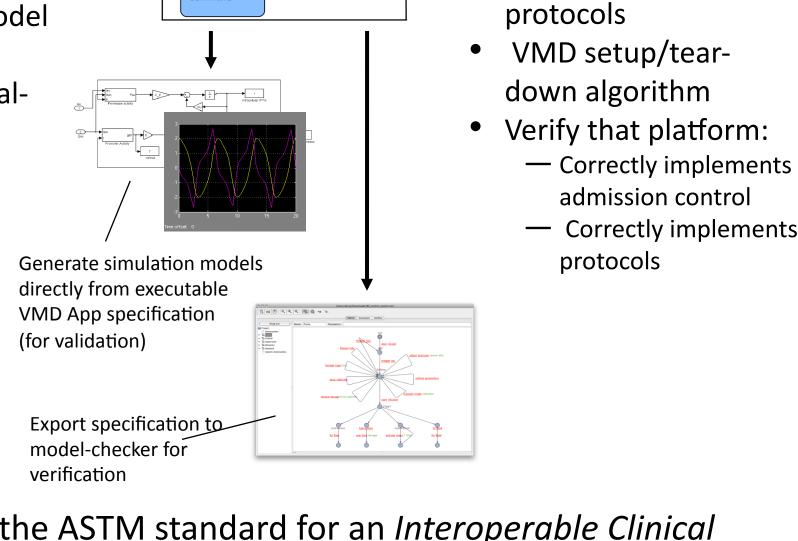
devices into VMD instance

- Publish-subscribe real-time middleware for integrating devices
- A component-based application (app) environment for developing and running algorithms that coordinate the device data flows and actions
- Together the platform, app, and connected devices form a Virtual Medical Device – a composite system device composed of individual devices



Real-time support Via MIDAS Middleware

- Hard real-time communication infrastructure Light-weight
- Pub/sub programming model Support for programming clinical-algorithms with realtime constraints
- Event driven Time triggered
- Admission control Guarantee performance specified by VMD App o prevent clinician from instantiating VMD



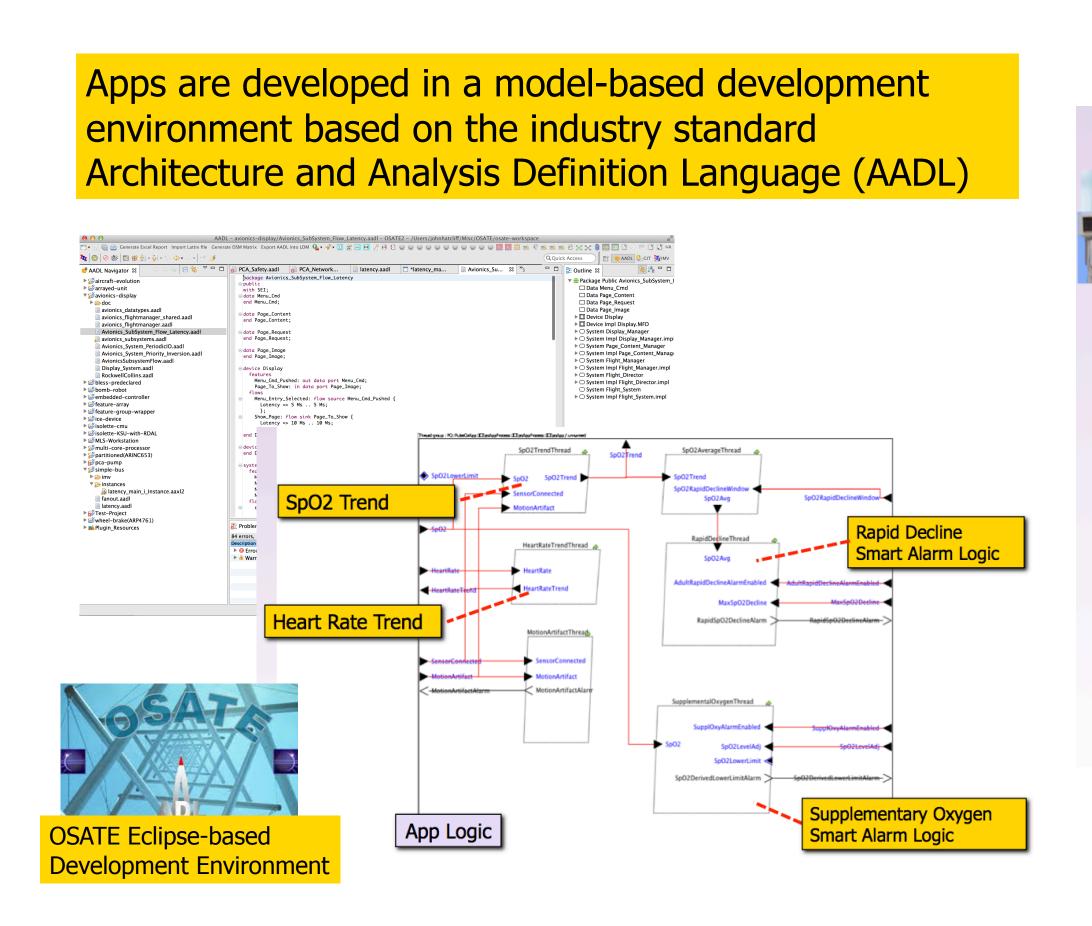
Research Issues

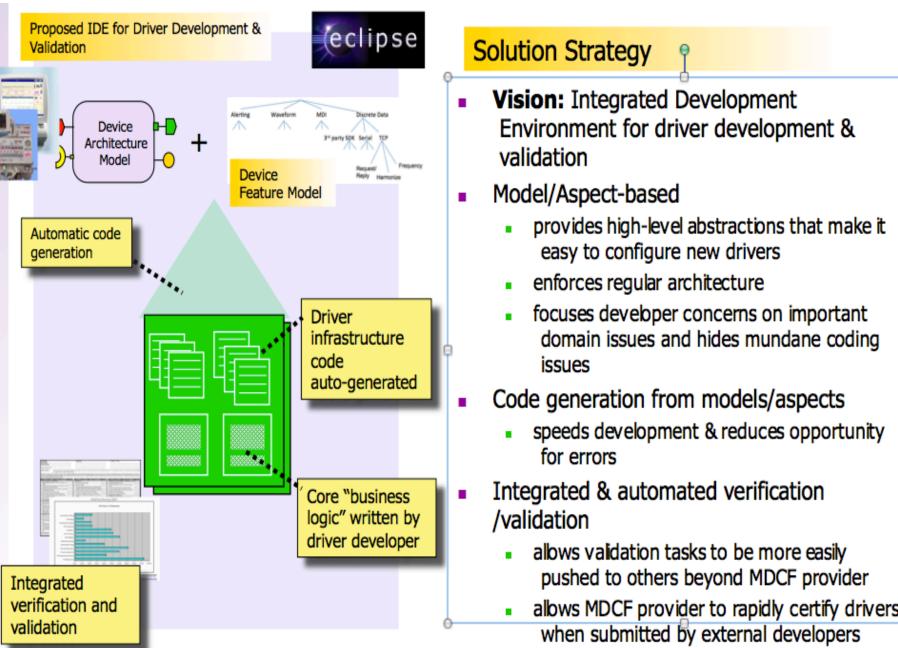
VMD App

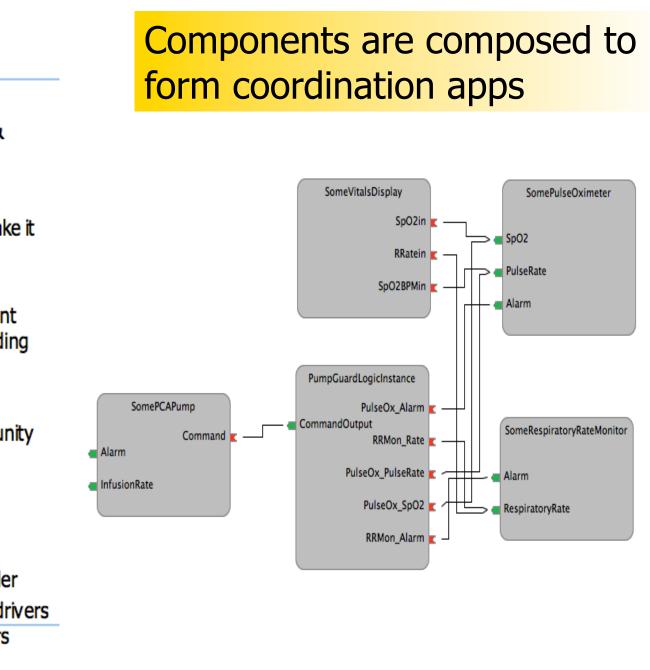
Validation & Verification

The MDCF aligns with the ASTM standard for an Interoperable Clinical Environment (ICE) developed by the CIMIT MDPnP project.

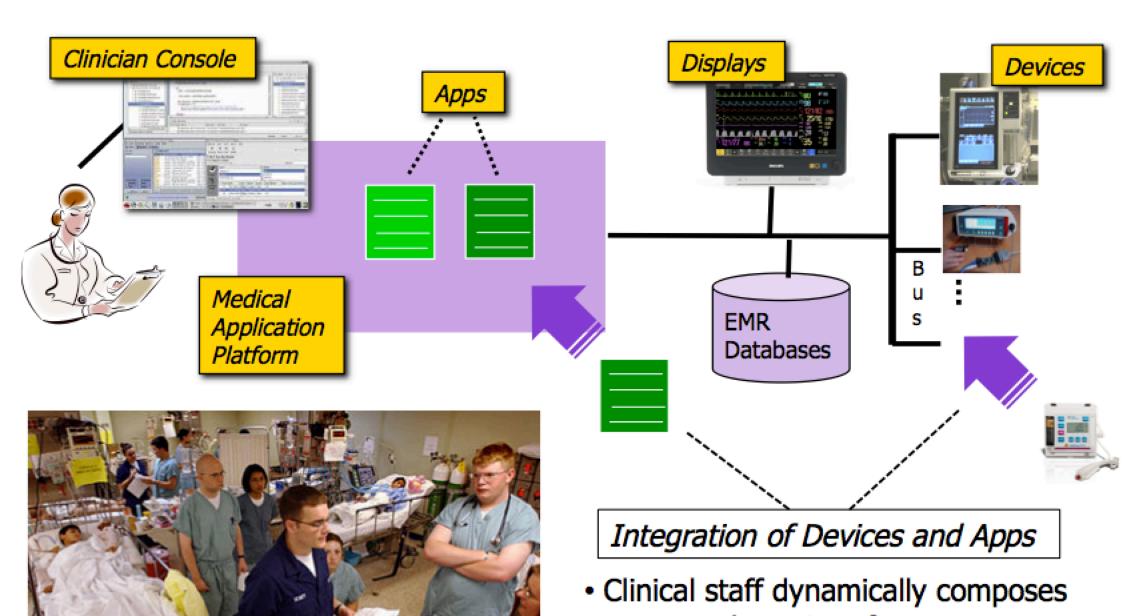
Component-based Development for Coordination Apps





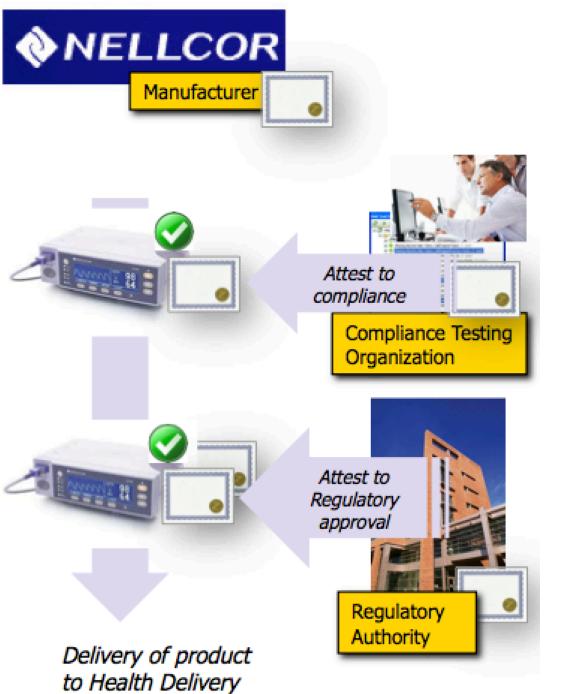


Authentication Framework for Trusted Composition



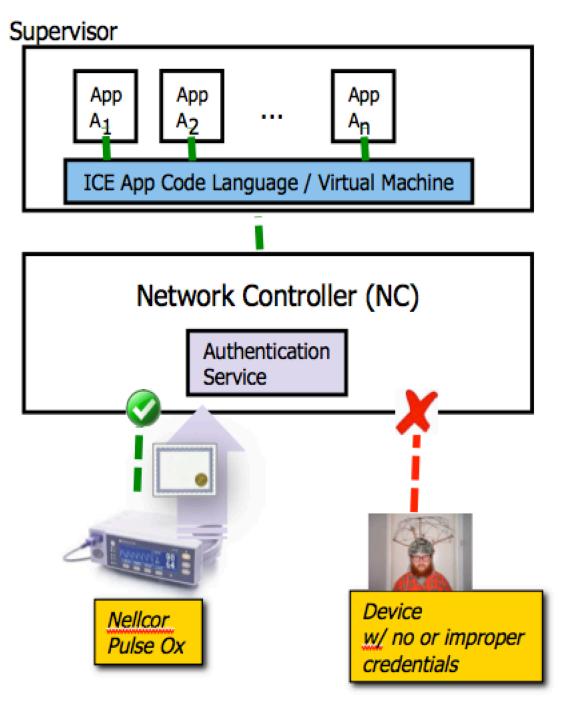
- system at the point of care
- How can we know that we can trust those devices have received appropriate safety evaluations and regulatory review?

Solution (Part 1): At critical steps in development/ certification, components are given digital certificates that attest to their safety and compliance with

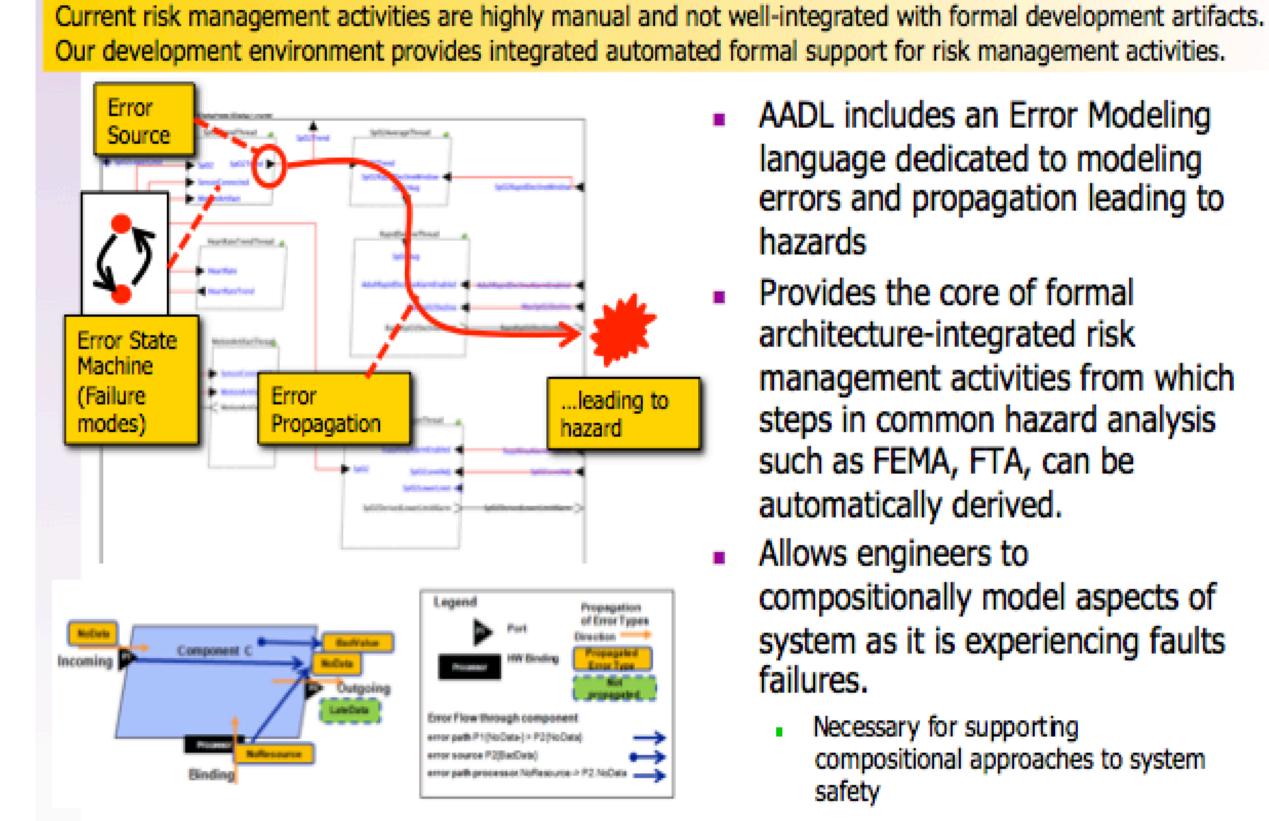


Organization

Solution (Part 2): When components are integrated, platform automatically checks that components have the appropriate digital

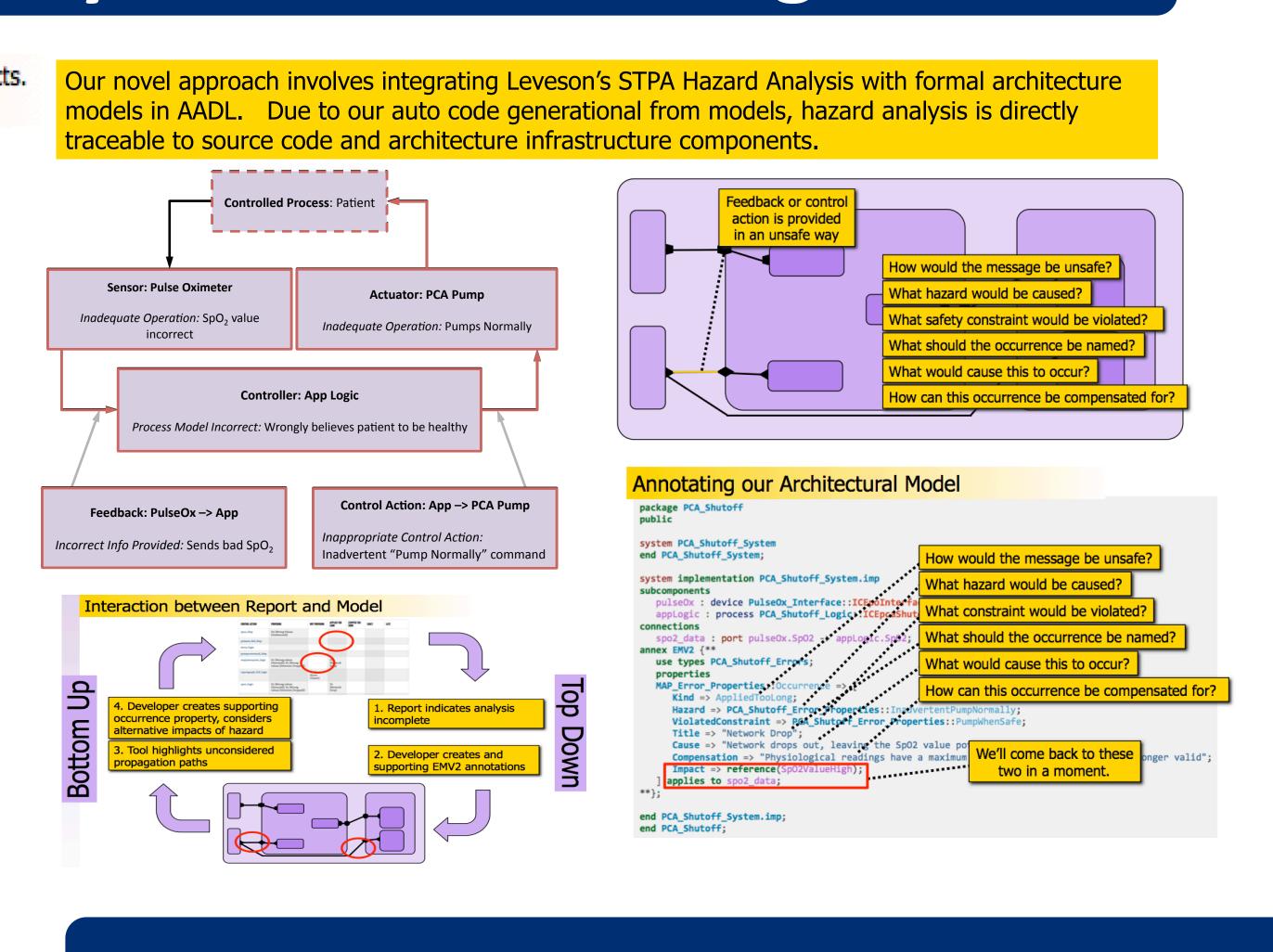


Component-wise Hazard Analysis and Risk Management

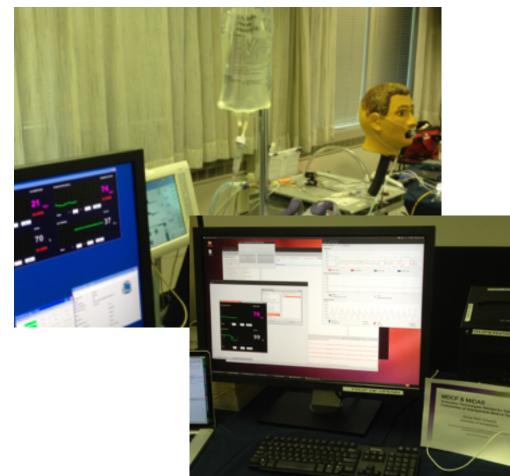


 AADL includes an Error Modeling language dedicated to modeling errors and propagation leading to hazards

- Provides the core of formal architecture-integrated risk management activities from which steps in common hazard analysis such as FEMA, FTA, can be automatically derived.
- Allows engineers to compositionally model aspects of system as it is experiencing faults
- Necessary for supporting compositional approaches to system



Industry Collaboration



Demo for NIH with CIMIT, Anakena Solutions, DocBox



J Penn Ph.D. student Andrew King explains demo scenario to FDA engineer Paul Jones

Standards & Regulatory Policy

PIs are members of the AAMI / UL 2800 standard committee tasked with writing a family of standards for safety/security of medical device interoperability

- Safety/security requirements of architectures for Medical Application Platforms (MAPs)
- Framework for compositional certifications of MAPs
- Guidelines for evaluating compliance to requirements
- We are actively engaged with FDA engineers to develop sciencebased inputs for forming regulatory policy for interoperable medical systems
- Safety evaluation eco-system for medical device interoperability platforms
- Example hazard analyses, mock 510(k) regulatory submissions for apps and other MDCF components
- Guidelines for development of third-party certification regime

Educational Material

The MDCF is open source and is designed to support a variety of interesting class projects and graduate research projects

- A collection of mock (software simulated) medical devices including blood pressure monitor, pulse oximeter, infusion pump, electrocardio-gram (ECG)
- A collection of example apps illustrating how to use the MDCF app development environment
- Illustrations of how to interface with real medical devices
- Suggested student projects

- Detailed requirements and development artifacts for Patient-Controlled Analgesic (PCA) Pump
- Lectures on safety-critical system development – requirements, hazard analysis, assurance cases, etc.

Team

Kansas State University

John Hatcliff Robby Eugene Vasserman Steve Warren Venkatesh Ranganath

Yu Jin Kim **Brian Larson** Sam Procter Kim Fowler

Collaborators

Center for Integration of Medicine and Innovative Technology (CIMIT)

Dr. Julian Goldman David Arney, Jeff Plourde

FDA & Underwriters Lab

Paul L. Jones (FDA) Sandy Weininger (FDA) Anura Fernando (UL)

University of Pennsylvania

Insup Lee

Oleg Sokolsky

Andrew King