Effect of Custom Cruise Control on Traffic Energy Use

Work Research Group

Gracie Gumm and Maya Kumar

PI: Dr. Daniel Work

Mentor: Matthew Nice







CIRCLES Consortium

- Congestion Impacts Reduction via CAVin-the-loop Lagrangian Energy Smoothing
- Interuniversity research group aiming to reduce traffic instabilities through deep reinforcement learning [1]



















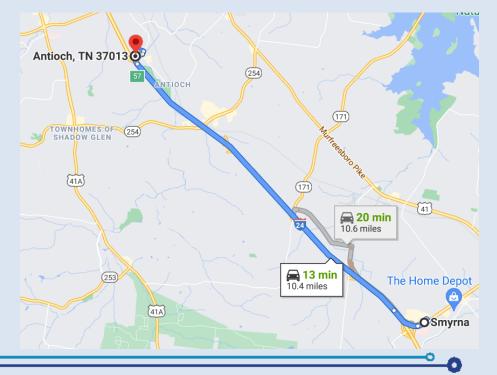


Background Research

 Current algorithms are being developed from baseline data collected from morning and afternoon rush-hour drives on I-24

Collected data from March - May 2021

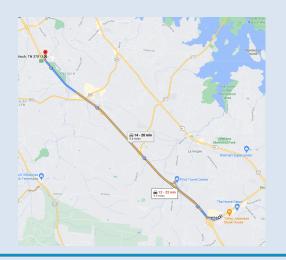
44 drives conducted

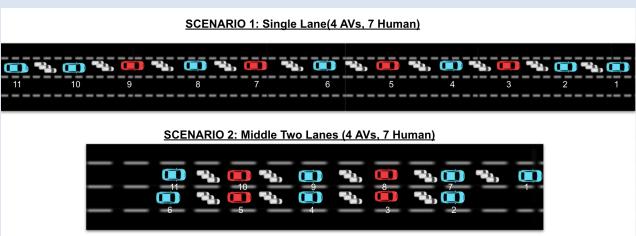




Upcoming Experiment

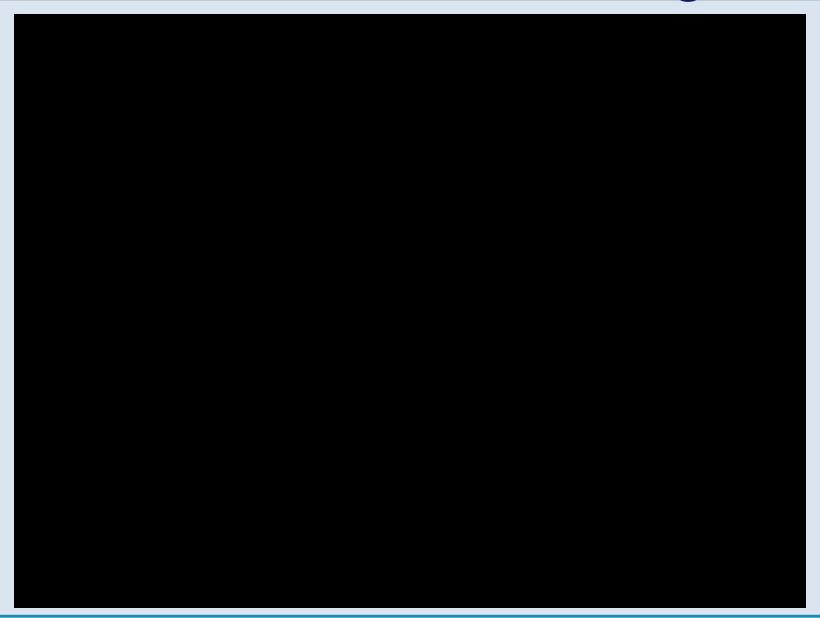
- 11 car test on I-24 from Aug. 2-6
- 4 vehicles with autonomous velocity control and 7 manually driven cars
- Testing various velocity controllers and their effect on fuel consumption in various scenarios
 - Controllers developed by CIRCLES team







I-24 Dashcam Footage



Logistical Preparation

Driver recruitment and training

7 drivers from Vanderbilt

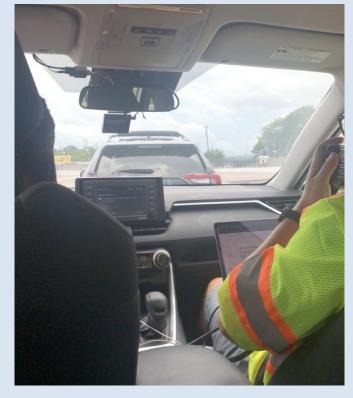
1 from University of Arizona

2 from UC Berkeley

IRB submission

Consent forms, driver directions, etc.

Hotel booking
Practice drives
Nashville Fairground
Speedway





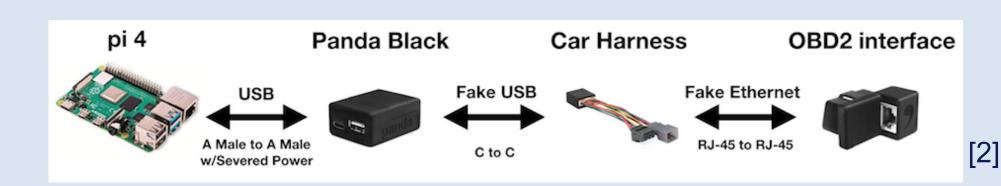
Experimental Preparation

 Instrumented vehicles using COMMA.Al hardware to collect CAN data

Analyzed I-24 driving data using Strym
Python package developed by CIRCLES
researchers to synchronously visualize
CAN data using provided APIs

Installed advanced GPS devices to calculate error on I-24 MOTION camera network



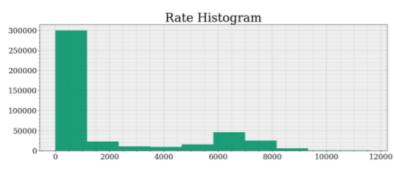


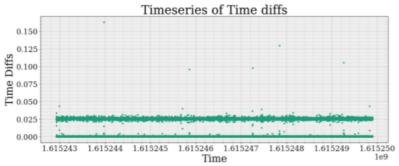


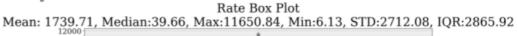
strymread

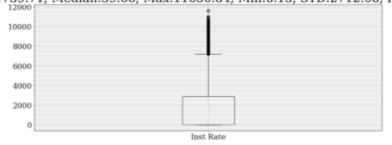
[5]:		MessageID	Counts_Bus_0	Counts_Bus_1	Counts_Bus_2	Counts_Bus_128	Counts_Bus_130	TotalCount
	36	36	537535	0	0	0	537536	1075071
	37	37	537535	0	0	0	537535	1075070
	166	166	537536	0	0	0	537536	1075072
	170	170	537536	0	0	0	537536	1075072

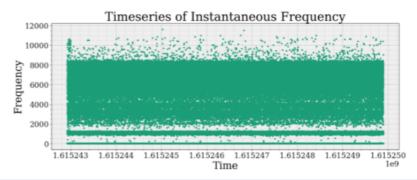
Message Rate Analysis: Timeseries



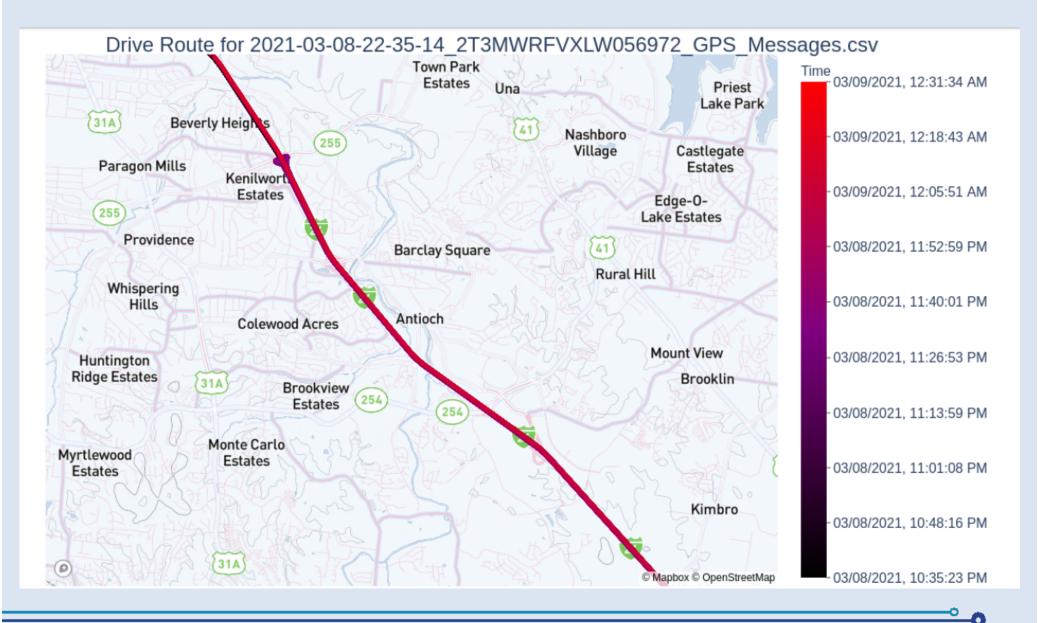








strymmap





Future Research

- Summer 2022:
 - 100 car traffic smoothing experiment
 - Extension of I-24 highway sensing infrastructure Testing various custom velocity controllers



Challenges and Lessons

Learned

- The smaller logistics regarding travelling and work spaces are just as critical as the larger details, such as installing hardware
 Booking a rental space for staging area
- Getting Raspberry Pis connected to battery packs to automatically upload data to Cyverse after the vehicle is turned off
- Observed challenges involved in taking an idea from theoretical to execution
- Issues seen now, if not resolved well, will be amplified in 100 car testing next





Work Cited

- [1] "CIRCLES." https://circles-consortium.github.io/ (accessed Jul. 19, 2021).
- [2] "libpandac: Hardware tutorial." https://jmscslgroup.github.io/libpanda/ (accessed Jul. 19, 2021).
- [3] D. Gloudemans, *DerekGloudemans/I24-MOTION*examples. 2021. Accessed: Jul. 19, 2021. [Online]. Available: https://github.com/DerekGloudemans/I24-MOTION-examples

