Robotics Perception and Manipulation via Full-Spectral Wireless Sensing

Yasaman Ghasempour (Princeton University) and Fadel Adib (MIT)

Key Problems & Objective Current robotic manipulation systems rely only on cameras and haptic gloves to Inefficient and challenging to complete complex tasks that may require perception **Thrust 1: Enabling Sub-THz Imaging & Inference** ensing and Imagin Control **Thrust 2: Full Spectrum Perception & Reasoning** hrust 3: Robotic Control via Mult **Spectral Sensing & Learning**

- "see" and "feel" the environment
- and reasoning outside of the immediate FoV and contact zone

Goal: Designing and building an end-to-end system for intelligent multi-spectral sensing, learning, and reasoning to enable NLOS and contact-less perception for enhanced robotic manipulation and control



Enabling NLOS Perception via Multi-Spectral Imaging

- mmWave signals can traverse occlusions, enabling them to see occluded objects Existing models for robotic perception & manipulation are not trained on mmWave
- images
- Developing a new perception pipeline for mmWave-based reasoning 1) Collect Multi-Spectral Dataset







Massachusetts Institute of Technology

Terahertz Perception for Robotics

- Exploiting sub-THz frequencies for Robotics for the first time
 - Surface roughness estimation
 - Material inference
 - High-resolution imaging
- Developing a framework for the coefficient of friction estimation by integrating THz perception with applications in grasping & locomotion
- AgriTera: Non-invasive Fruit Ripeness Sensing using THz sensors at distribution lines and smart factories



Scientific Impacts

- Unlocking new robotic perception and manipulation capabilities
- Introducing a fundamentally new perception modality for industrial robotics
- Learning synergies between sensing control to optimize end-to-end CPS tasks
- Impacting a broad CPS domain –from grasping to locomotion and target identification and retrial in unstructured and occluded settings
- Enhancing manipulation efficiency through non-contact and NLOS perception and reasoning





- Multi-spectral fusion for industrial robotics, warehousing, smart home
- public education and engagement
- Training students and workforce developments
- communities and showcasing our demos to industry partners
- K-12 student engagement through summer workshops