Cognitive Autonomy for Human CPS: From Novices to Experts NSF CPS Frontier

Meeko Oishi, Sriram Sankaranarayanan, Ufuk Topcu, Inseok Hwang, Neera Jain, Tahira Reid Smith, Brandon Pitts, Tryphenia Peele-Eady, Lizandra Godwin

Analysis, design, and control to make autonomous cyber-physical systems highly responsive to human cognitive state.

Cognitive Autonomy

- 1. Is robust to uncertainty in the environment and in the human's actions
- 2. Assures desired human-CPS properties
- Prevents loss of attention and over-reliance 3.
- Responds to the physical, computation, and 4. human cognitive state
- Provides guidance / takes control as needed, and 5. communicates appropriately with the human
- Anticipates and prevents willful misuse 6.

Key innovations and new contributions

- Inference of learning stages for self-confidence and • trust calibration
- Generative AI for formative feedback on psychomotor • learning tasks
- Identification of mode changes in human-in-the-loop ٠ data
- Adaptive function allocation in for human-autonomy teaming in uncertain environments
- Bounded rationality in Markov games

Leader's return under inference with a boundedly rational follower Stackelberg re









Human cognitive state dynamics are required for effective analysis and control of human CPS.



Impact on CPS Research

- Computationally tractable, data-driven models, for individual human state, actions, and priorities
- Offline verification + online predictive monitoring
- Control of physical and cognitive system state
- Model-based, multi-modal, transparent . communication

Broader impacts

- Prevention of "misuse, disuse, and abuse" of ٠ automation
- Human-centric algorithms and tools at the intersection of controls and learning
- Methods to accommodate human heterogeneity ٠ and variability

Summer Intensive Research Internship (SIRI)

- Culturally responsive undergraduate research
- Targets underrepresented students in New Mexico to work with Purdue faculty
- Characterization of environments for student success and belonging







Psychophysiolo gical sensing for selfconfidence and trust calibration in a learning task

Inferring learning stages via kernel embeddinas

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