CPS: Frontier: Collaborative Research: COALESCE: COntext Aware LEarning for Sustainable CybEragricultural systems

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Introduction

The COALESCE project seeks to transform CPS capabilities in agricultural system that encompasses sensing, modeling, and actuation to enable farmers to respond to crop stressors with lower cost, greater agility, and significantly lower environmental impact than current practices.

Objectives

- Embed biophysics in machine learning for individualized crop modeling
- To apply multi-modal information fusion and robust learning for Individualized sensing
- To implement data-driven, multi-scale planning and reasoning
- develop individualized sensing and actuation via То autonomous robots with dexterous manipulators

Technical Approach

- Extraction and fusion of cross-modal features for robust perception
- Incorporate biophysical constraints in ML models
- Reinforcement learning for supervisory decision support
- Learning-based control for actuators



Broader Impact

- CPS innovations transferable for diverse applications
- Knowledge dissemination Cyber-Physical Systems community, farmers, public

CALESCE

- Formal and informal education efforts for next-generation \bullet workforce and farming community
- Technology commercialization

2024 NSF Cyber-Physical Systems Principal Investigators' Meeting Project website: https://coalesce.me.iastate.edu



- Farmernetes: Enhanced sensing, communication, and network
- Enhanced autonomy for ground robots in harsh environments
- Individualized actuation using dexterous robots
- Modeling for climate resilient Agriculture
- Data-efficient deep learning algorithms



Education & Outreach

- Lead PI Sarkar leading the Undergraduate minor on Cyber-Physical Systems at Iowa State that started in Fall 2021
- CPS adoption for farmers through the ISU and ISA extension and outreach network.
- Community building via MLCAS, AIAFS workshops
- Multi-institutional effort to involve women, African American, Hispanic, and Native American students in computing and engineering

Scientific Impact

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- Biological digital twin algorithms
- Efficient decision-making algorithms
- Scalable cyberinfrastructure frameworks
- Soft and dexterous robotic manipulators
- Multi-agent mobile robotics 'in the wild'

Solution – Year 3

THE

- Weed Classifier for 1000+ species (mobile app, on-robot)
- Satellite to UAV multimodal generative model
- Ag-Gym environment for designing policies for biotic stress mitigation



Impact Quantification (Goals)

- Reduction in chemical application by at least 30%
- Increase in crop yield by at least 10%
- Reduction in soil compaction by at least 30%

2 to 5 acres 5 to 10 acres 1 to 2 acres (Testbed) (Testbed) (Testbed) ISU/ISA ISU/UIUC/UA ISU

Award ID#: 1954556







