

# CAREER: Towards an Intermittent Learning Framework for Smart and Efficient Cyber-Physical Autonomy

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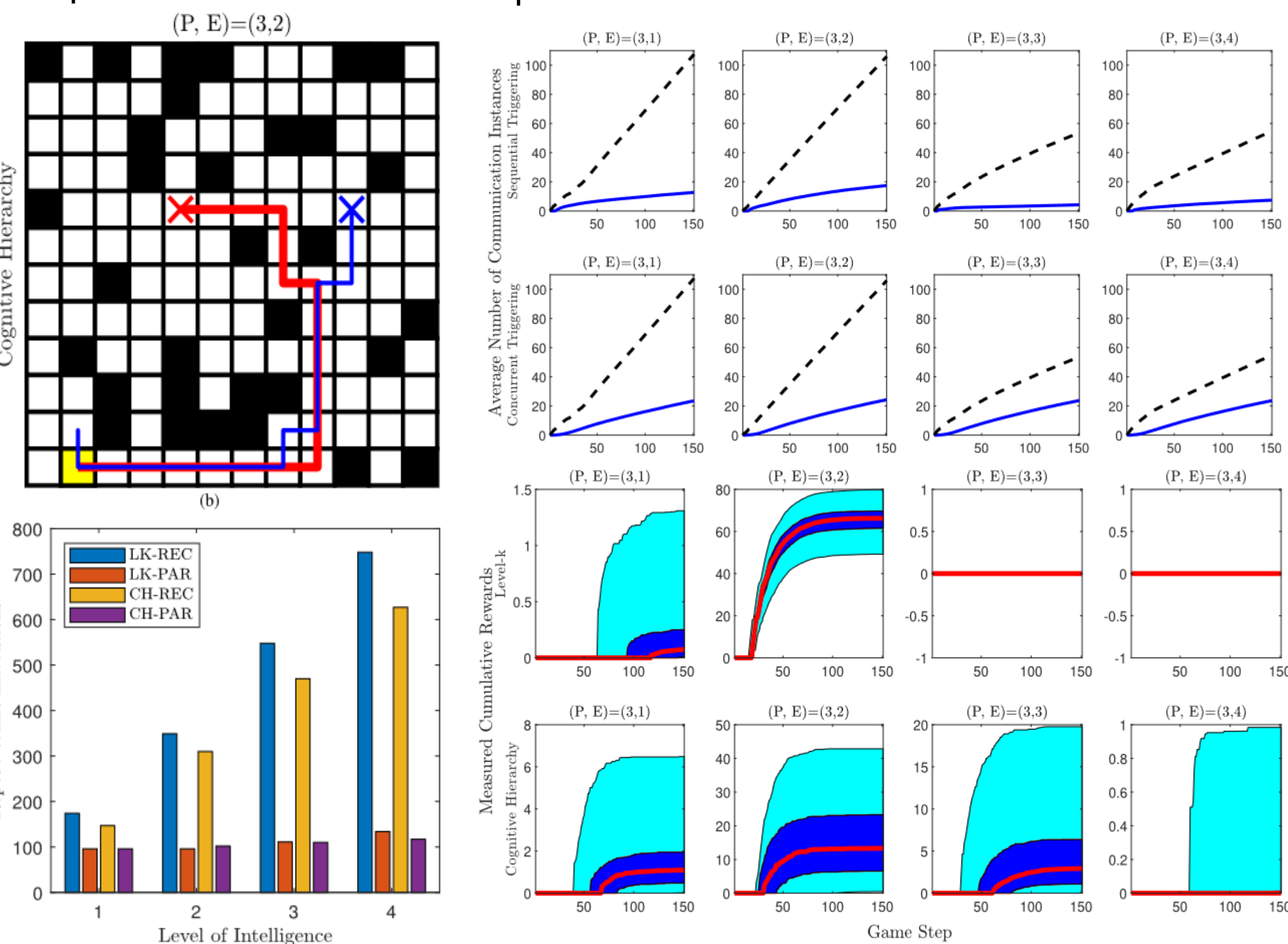
<http://kyriakos.ae.gatech.edu/NSFCareer.html>



## Recursive Reasoning With Intermittency for Nonequilibrium Learning in Stochastic Games

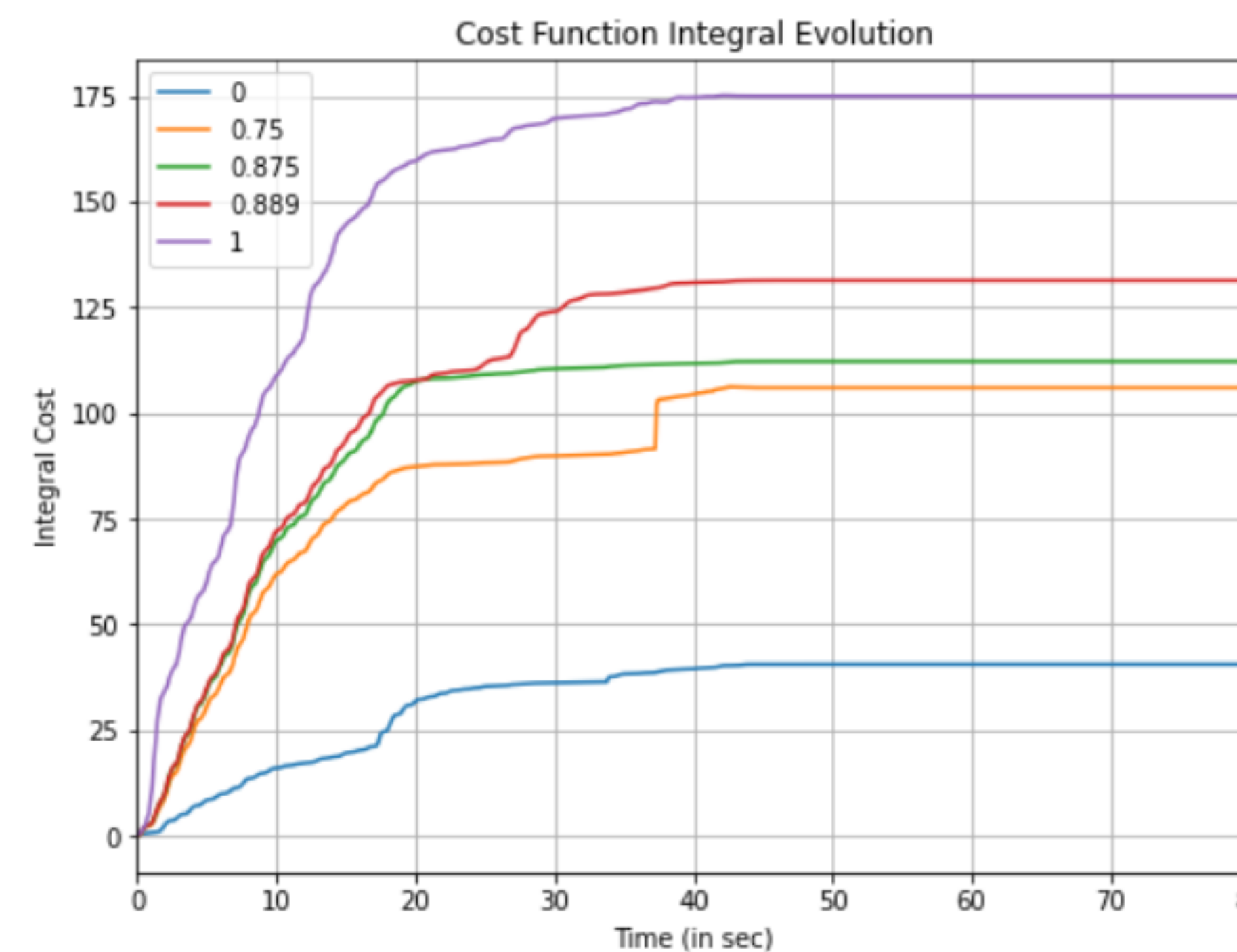
Modeling bounded rationality in stochastic games

- Ideas from behavioral psychology to model multi-agent behavior
- Alleviation of communication and computation burdens via intermittent policies and distributed implementation



## Self-Model-Free Learning versus Learning with External Rewards in Information Constrained Environments:

- Reinforcement learning framework for learning agents that experience loss of the reinforcement signals
- Trade-off scheme: reconstructs the reward using a goal network when the reinforcement signals are lost, utilizes true reinforcement signals when they are available.
- Stability of the equilibrium point is guaranteed despite fractional information loss in the reinforcement signals



## Challenge:

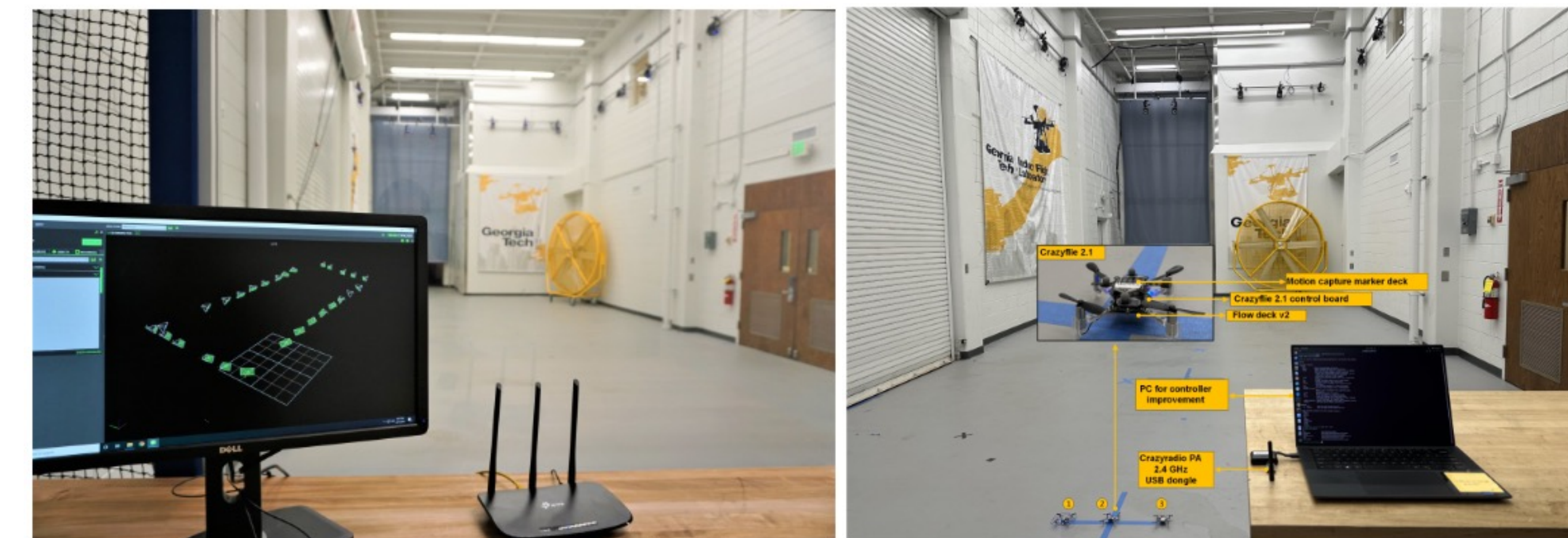
- Theoretical framework that will allow the efficient use of resources while adapting optimally to changing and adversarial environments
- Issues of smart autonomy under limited bandwidth usage, resilience and attack mitigation are investigated

## Scientific Impact:

- How can human predictive models be used to model multi-agent behavior in stochastic games, where policies incorporate intermittency?
- How can we select the most controllable and resilient actuators for a system with uncertain dynamics?
- How can we develop reinforcement learning algorithms that provably converge in the presence of partial information loss due to packet drops or DoS attacks?
- How robust are reinforcement learning algorithms to uncertainty in the data due to clock offsets, quantization, and intermittency?

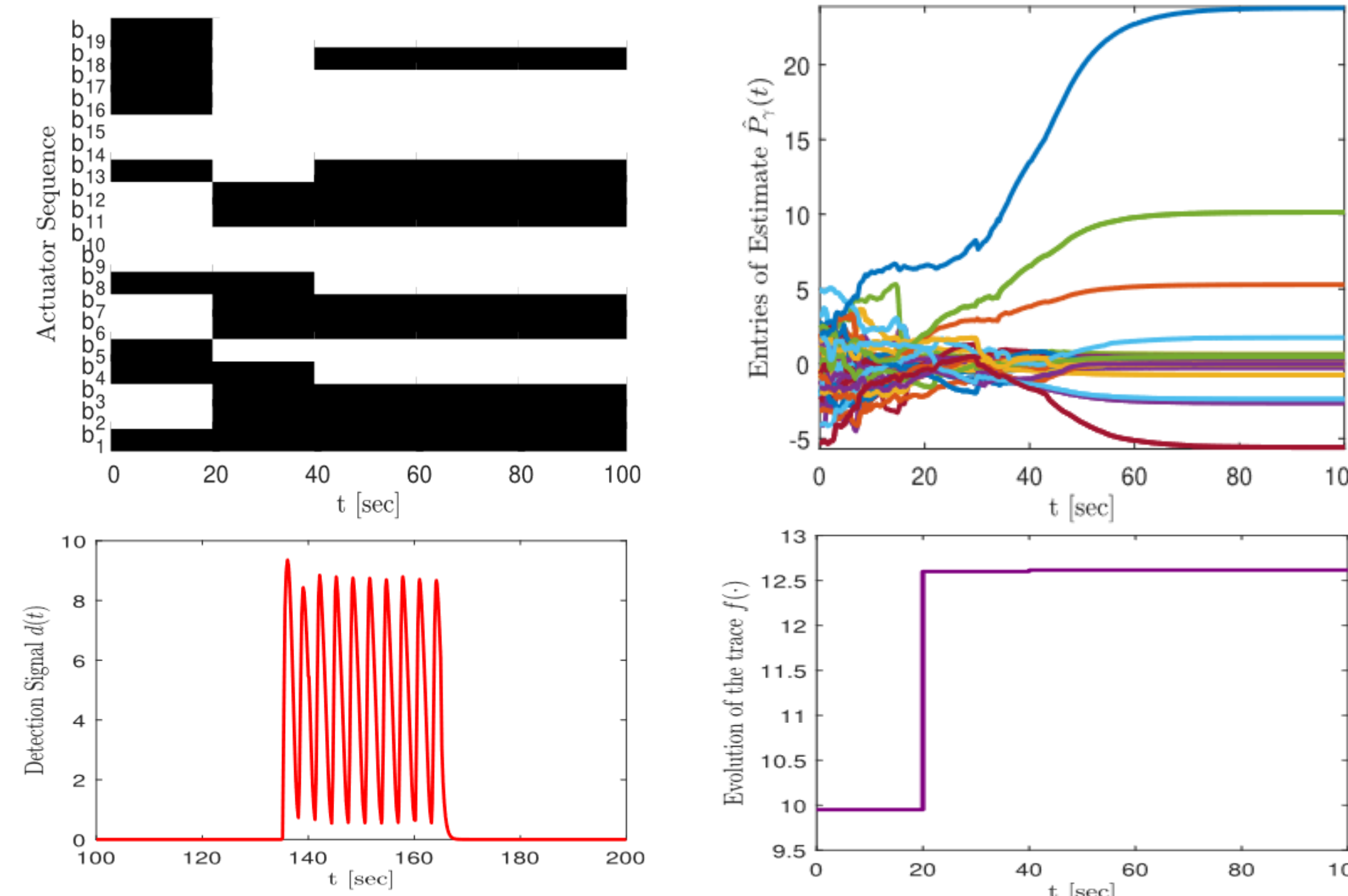
## Broader Impact:

- Deepen ties between the learning, control, game theory, and CPS communities and offer an engineering perspective to behavioral psychology
- Lead of a tutorial paper on game theory in the American Control Conference at San Diego, CA, 2023
- Experimental verification of the reinforcement learning rules that incorporate intermittency on nano quadrotors, at the flight facilities of Georgia Tech



## Data-Driven Actuator Selection for CPS

- Selecting the most controllable and resilient actuators for CPS, without knowledge of its dynamics
- Using techniques from the literature of reinforcement learning and approximate dynamic programming
- The data used for learning-based actuator selection can be recycled for the purpose of data-driven actuation attack detection



## Scholar work and outcomes for year 2023 (only):

- 4 book chapters
- 11 journal publications
- 15 peer reviewed conference papers
- See [kyriakos.ae.gatech.edu](http://kyriakos.ae.gatech.edu)

## Solution:

- Intermittent learning through novel sampling structures, based on behaviorism
- Non-equilibrium game theory to model bounded rationality decision making in the context of intermittency