

CPS: Small: Data-Driven Modeling and Control of Human-Cyber-Physical Systems with Extended-Reality-Assisted Interfaces

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https://www.nsf.gov/awardsearch/showAward?AWD_ID=2223035



Goal: Develop a holistic data-driven design framework of modeling, interaction, and control for Human-Cyber-Physical Systems (h-CPS).

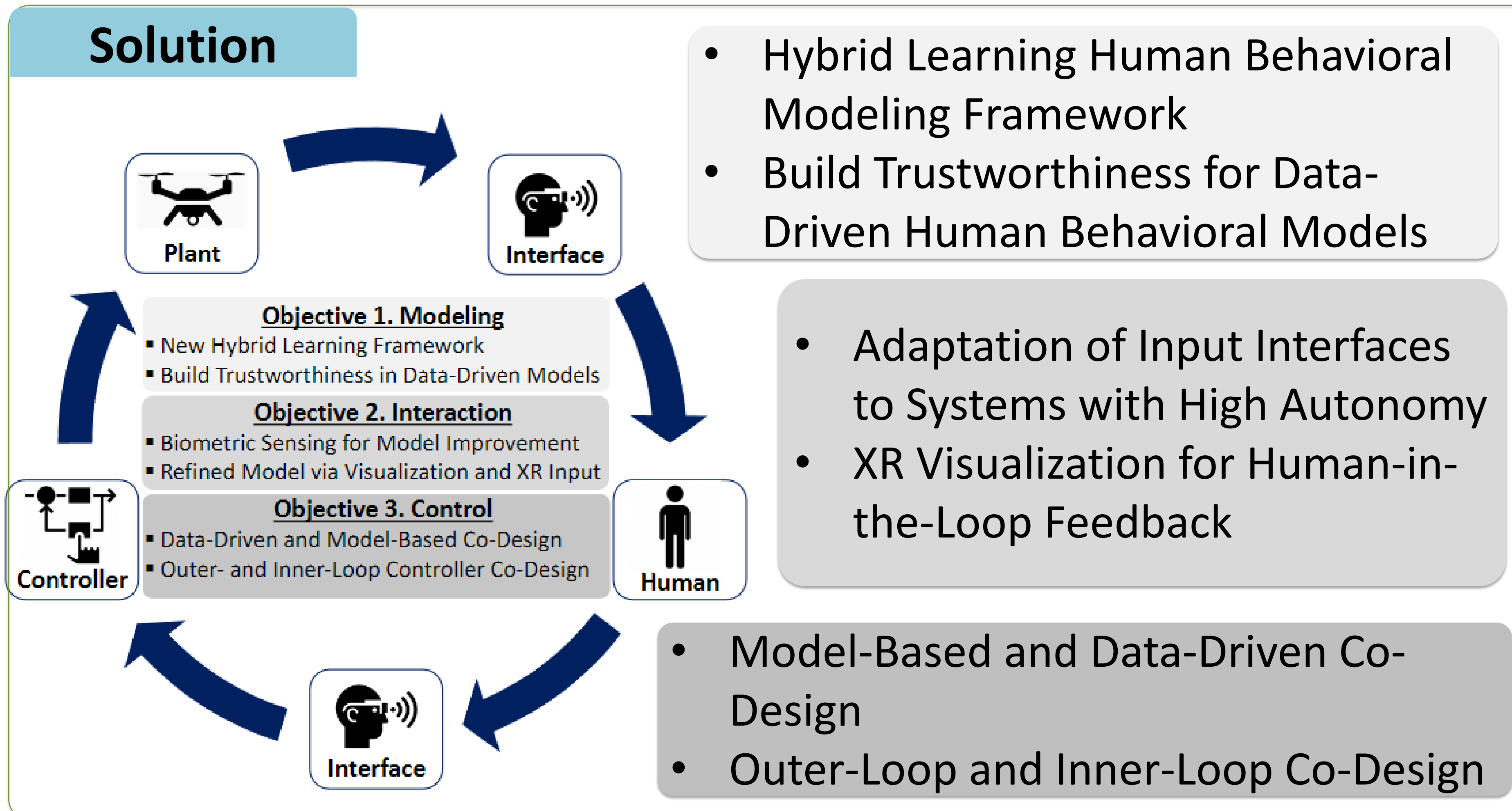
Challenges

- Modeling Complex Human Behaviors
- Effective Human-Machine Communication Interfaces
- Adaptable, Reliable, and High-Performance Control

Scientific Impacts

- New Hybrid Learning Architecture for Data-Driven Modeling of Human Behaviors
- XR-Assisted Human-Machine-Environment Interface
- Co-Design Control Framework for CPS with Human-in-the-Loop

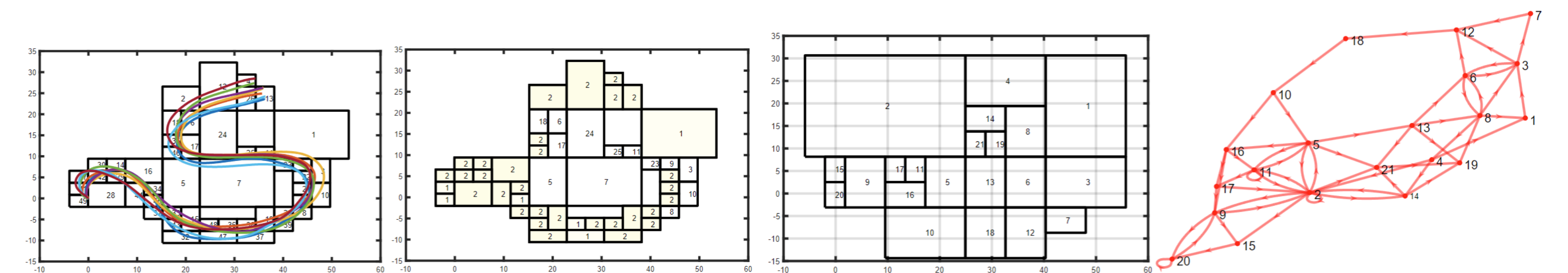
Solution



Project Progress

Modeling

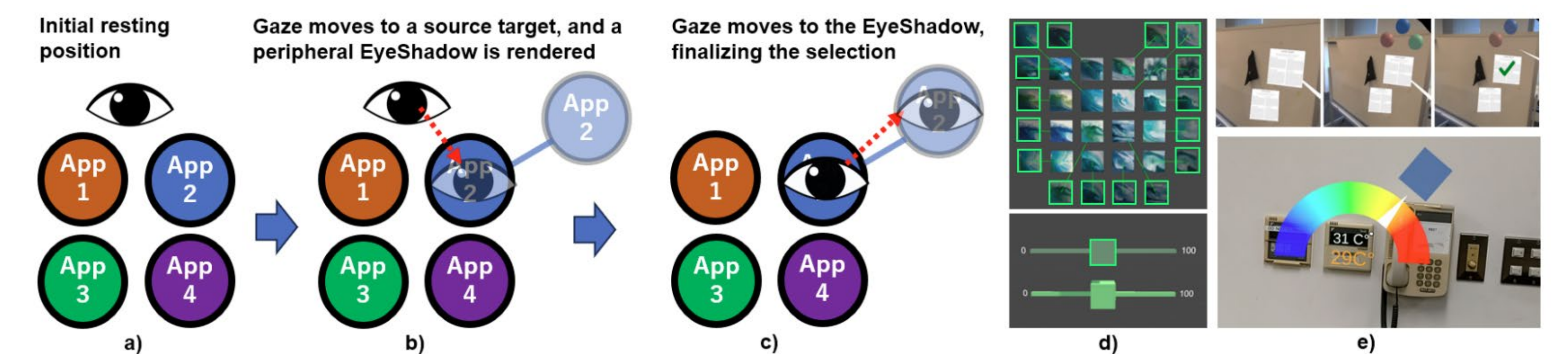
D³NN: Data-Driven Dual-level Neural Network Tool for Dynamical System Modeling and Abstraction



(a) S-Shape Samples and 49 Partitions Obtained. (b) 22 Cells Abstraction for \mathcal{H} of S-Shape Data Set. (c) 21 Cells are Obtained in High-Level Transition System Abstraction. (d) Transition Map based on \mathcal{T} of Low-level NHS Model \mathcal{H} .

Interaction

EyeShadows: Peripheral Virtual Copies for Rapid Gaze Selection and Interaction



Broader Impacts

Impact to Society

- Benefit a broad class of h-CPS applications to provide efficient and reliable modeling, interaction, and control tools.

Education and Outreach

- CPS Workforce Training and Education: One student won DoD scholarship.
- Curriculum Development: Game Design Club, CPS and Game Design Courses, etc.
- STEM Outreach: GenCyber Camp, High School Spotlight Event, etc.

