

# Collaborative Research: CPS: Medium: Spatio-Temporal Logics for Analyzing and Querying Perception Systems

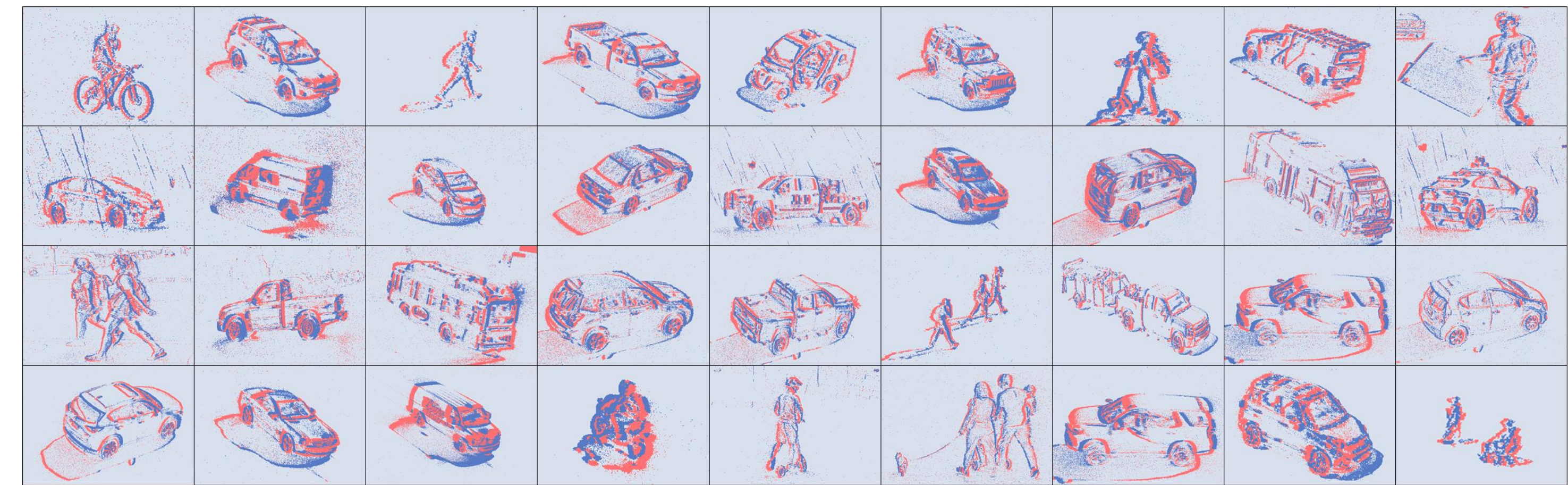
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## Abstract

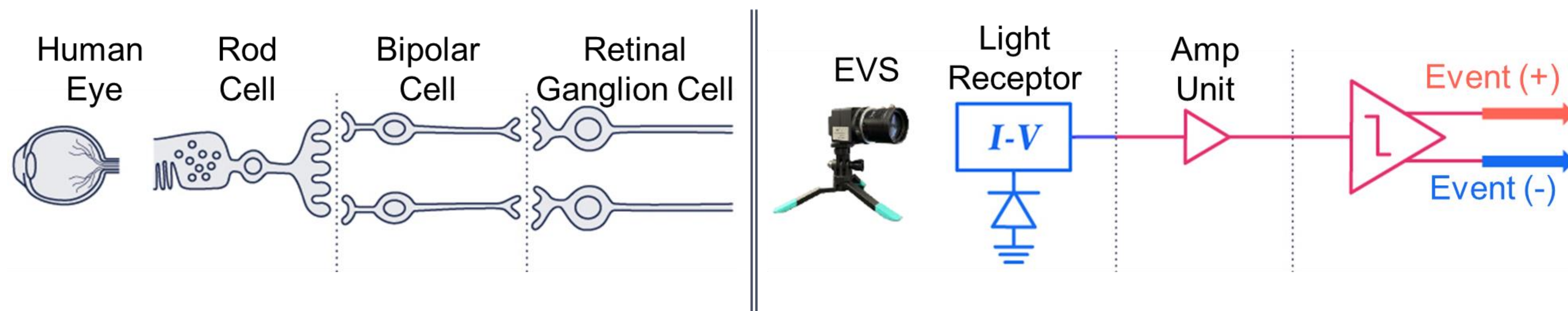
- Development of formal languages for evaluating the quality & robustness of perception sub-systems within ADS & ADAS.
- A novel spatio-temporal logic enabling temporal & spatial reasoning about streaming perception data.
- Educational curricula to train engineers & engage the public in understanding ADS challenges.
- Open-source software tools for testing perception systems & establishing standardized requirements languages.

### Neuromorphic Vision Unveiling Spatio-Temporal Traffic Insights: Enhancing ADAS Perception in High Dynamic Scenes

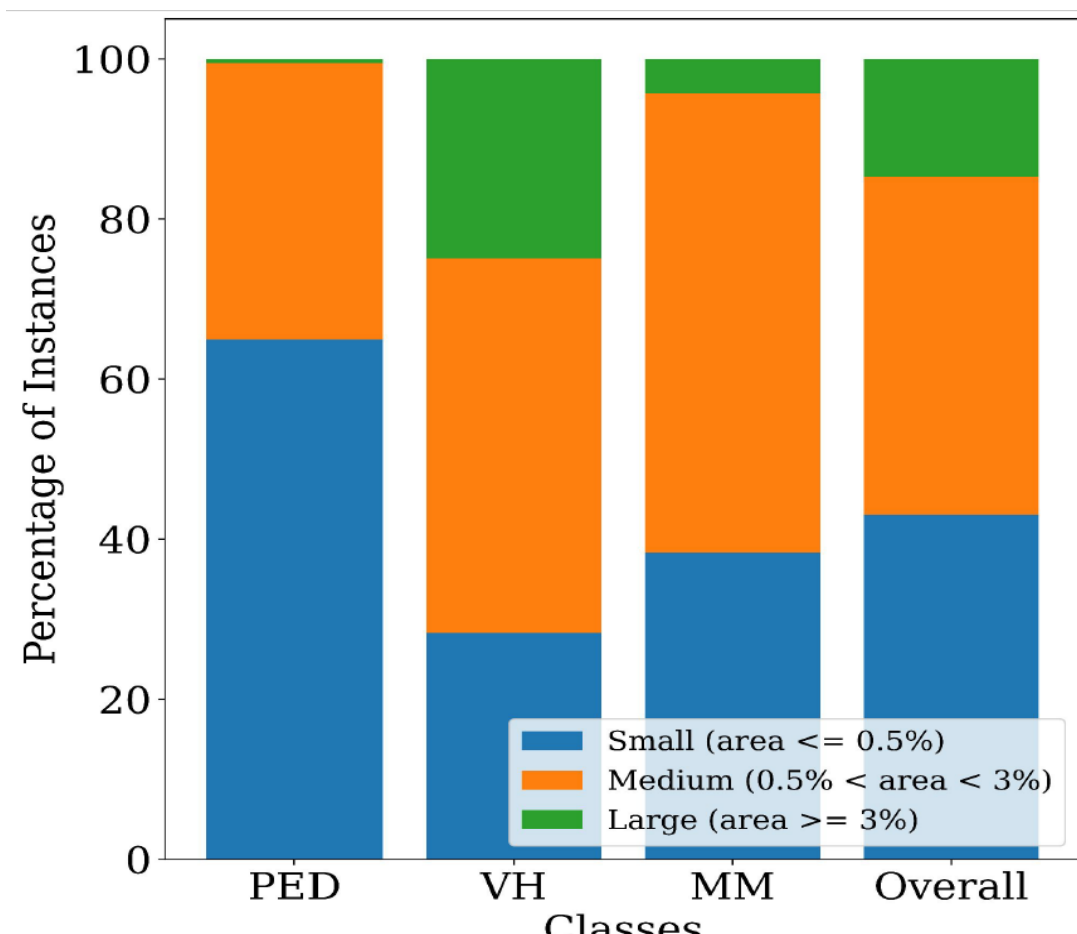
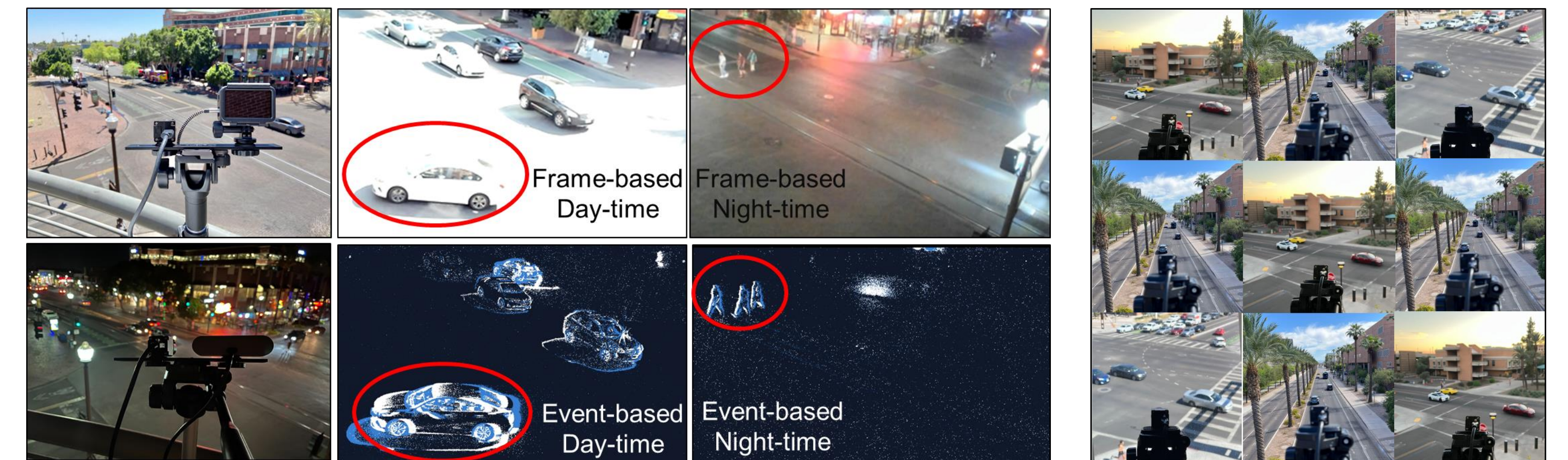
- Exploring the integration of neuromorphic vision systems with spatio-temporal reasoning for fixed traffic monitoring, leveraging event-based cameras' high temporal resolution & dynamic range
- eTraM\*** - the first fully event-based fixed traffic monitoring dataset, providing comprehensive insights into real-world traffic dynamics featuring 2M annotations across 8 distinct traffic participant classes across a variety of scenes & lighting scenarios.



## Event-based Vision Systems Capturing Movements like Human Eye



**1280x720px**  
Resolution  
**>10k fps**  
Time resolution equivalent  
**>120dB**  
Dynamic Range  
**0.08 Lux**  
Low light cutoff



Traffic Site	Lighting	RVT				RED				YOLO			
		PED	VH	MM	all	PED	VH	MM	all	PED	VH	MM	all
Intersections	Daytime	<b>0.460</b>	0.813	0.315	<b>0.722</b>	<b>0.395</b>	0.593	0.284	0.545	0.167	0.293	0.111	0.190
		0.430	0.733	0.070	0.627	0.347	0.590	0.055	<b>0.551</b>	<b>0.173</b>	0.290	0.004	0.156
		0.196	<b>0.938</b>	<b>0.586</b>	0.316	0.208	<b>0.875</b>	<b>0.695</b>	0.351	0.124	<b>0.559</b>	<b>0.204</b>	<b>0.296</b>
<b>Overall</b>		0.304	0.781	0.403	0.572	0.302	0.656	0.251	0.497	0.142	0.309	0.112	0.188
Intersections	Nighttime	0.161	0.465	-	0.262	0.149	0.425	-	0.242	0.071	0.375	-	0.149
		0.310	0.827	-	0.739	0.362	0.782	-	0.726	0.004	0.229	-	0.117
		<b>0.739</b>	<b>0.868</b>	0.097	<b>0.829</b>	<b>0.722</b>	<b>0.831</b>	0.145	<b>0.817</b>	<b>0.198</b>	<b>0.486</b>	0.030	<b>0.239</b>
<b>Overall</b>		0.317	0.674	0.064	0.523	0.303	0.660	0.083	0.504	0.123	0.322	0.013	0.153
<b>Overall</b>		0.309	0.717	0.313	0.539	0.303	0.649	0.197	0.491	0.134	0.314	0.086	0.178

## Broader Impact on Society - Who Will Care

- Policymakers, regulators, & automotive stakeholders will prioritize advancements in perception systems to enhance road safety & improve autonomous vehicle reliability.
- Improved ADS & ADAS technologies will offer enhanced mobility options for individuals with disabilities, contributing to societal inclusivity.
- Society will benefit from reduced accidents & fatalities on roads, leading to safer communities & improved quality of life.
- Manufacturers & suppliers will value perception systems that optimize the performance of autonomous vehicles

## Broader Impact - Education & Outreach

- Engineering students will gain essential skills through educational curricula focused on perception system development.
- Public awareness initiatives will highlight the importance of perception technologies in road safety & autonomous vehicle development.
- Summer internships for undergraduate women will promote diversity & encourage participation in autonomous vehicle research.
- Open-source datasets & software tools will facilitate collaboration & knowledge sharing among engineers & governmental agencies.

## Potential Impact

- Enhanced perception systems can significantly reduce accidents & fatalities, leading to human life & economic savings.
- Formal languages & metrics can streamline testing processes, expediting the deployment of safer autonomous vehicles.
- Integration of neuromorphic vision technology in traffic management can mitigate congestion, improving transportation efficiency.
- Inclusion initiatives can foster innovation & diversity in autonomous vehicle technology, benefiting society & advancing technology.

Award ID: 2038666



**eTraM**: Event-based Traffic Monitoring Dataset [CVPR 2024]

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