DroneOpticStudio: Dense Reconstruction of Moving Actors in the Wild

Goal: Dense 3D reconstruction of moving actors in natural environments with multiple flying cameras



NSF awards: 2024173 & 2022894, Project title: Dense 3D reconstruction of moving actors in natural environments with multiple flying cameras 2022 NRI & FRR Principal Investigators' Meeting April 19-21, 2022

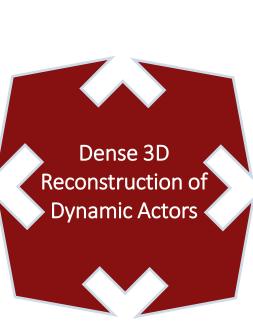


DroneOpticStudio: Impacts



Bio-mechanics of People & Animals







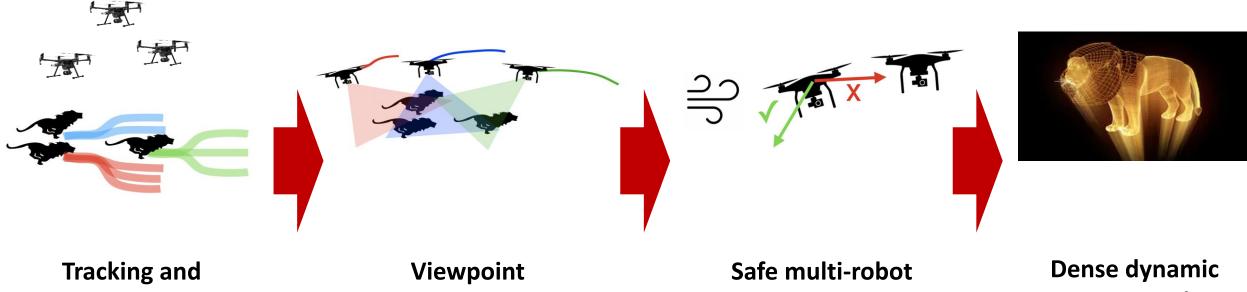
Cultural Preservation

Social Interactions





DroneOpticStudio: System



forecasting

planning

coordination

Reconstruction



Multi-Object Tracking in Crowds

Objective: Track multiple targets with occlusion, crossover and diverse motion pattern

Online and realtime tracking:

1. Association frequency is 300 FPS with a single CPU.

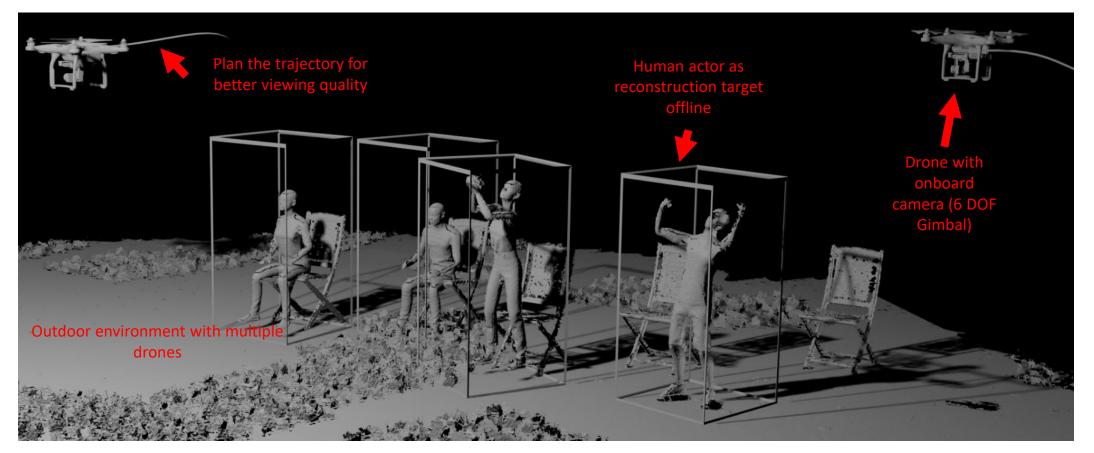
2. Robust to crowded scenes and camera view change.





View planning to improve Reconstruction quality

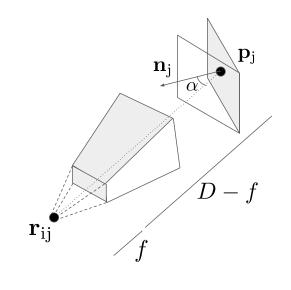
View planning to acquire high quality images for multi-drone scene reconstruction





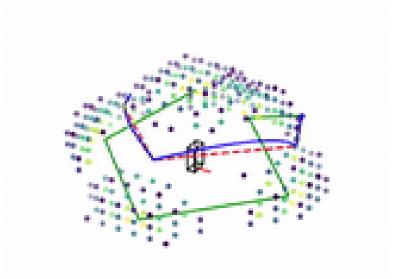
View planning to improve Reconstruction quality

Pixel-Per-Area (PPA) is introduced as a proxy metric. The resulting path planning problem is formulated as an instance of the **Traveling-Salesperson Problem with Neighborhoods (TSP-N)** problem



 $\mathbf{ppa} = \frac{\text{the projected area on the image plane}}{\text{its actual area.}}$

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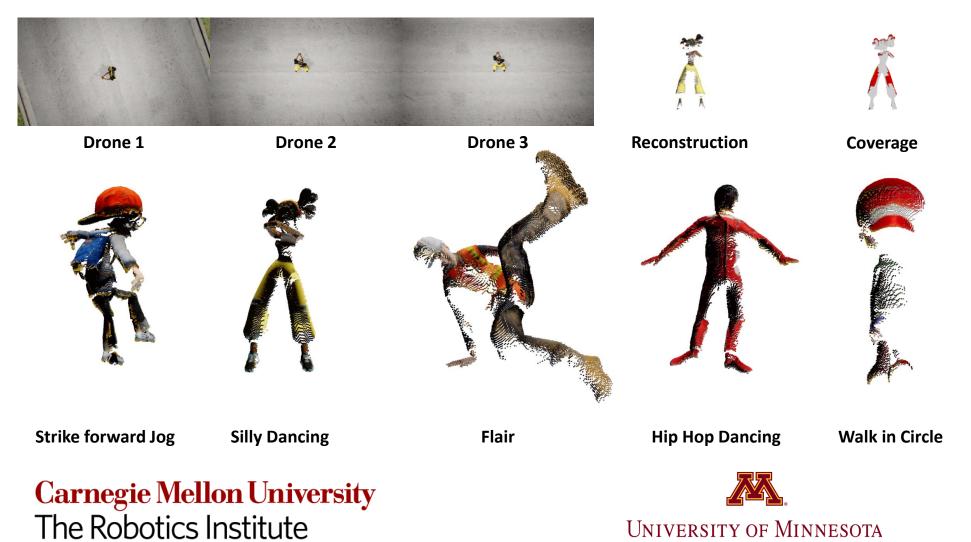


Define neighborhoods based on PPA values. The **visiting order** is shown in green, TSP-N path in red, and geodesic path in blue.



View planning to improve Reconstruction quality

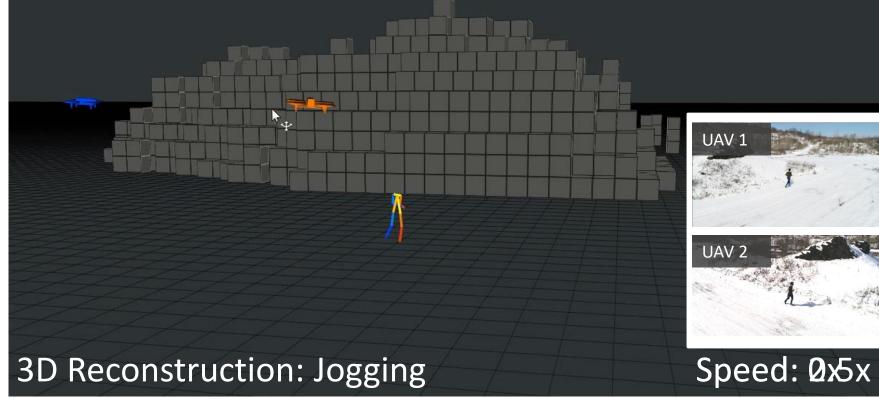
4D High fidelity reconstruction for dynamic actors



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Aerial collaboration for pose reconstruction

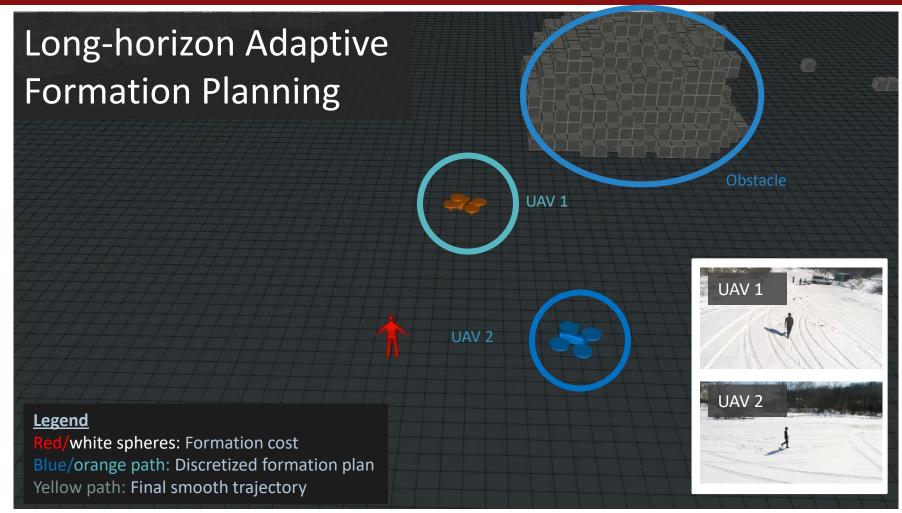
A multi-UAV system that reconstructs 3D human poses in unscripted scenarios



Cherie Ho, et al., 3D Human Reconstruction in the Wild with Collaborative Aerial Cameras, (IROS, 2021). Website: https://theairlab.org/multidrone/



Aerial collaboration for pose reconstruction



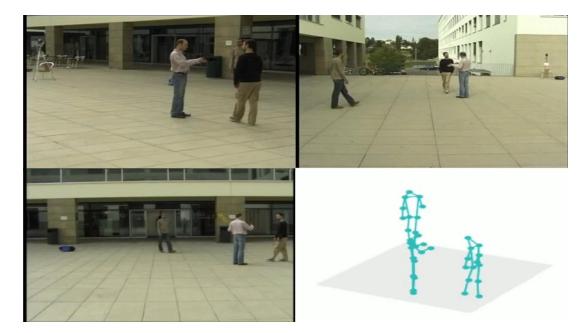
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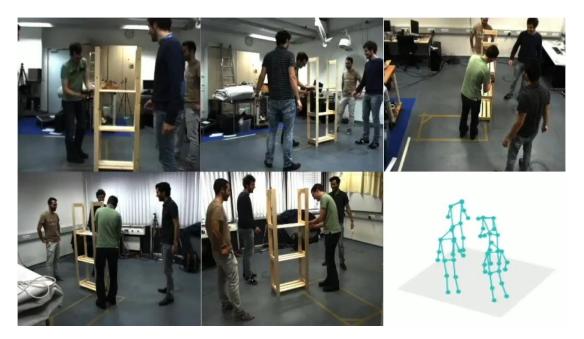


Multi-view multi-person 3D pose estimation

Campus



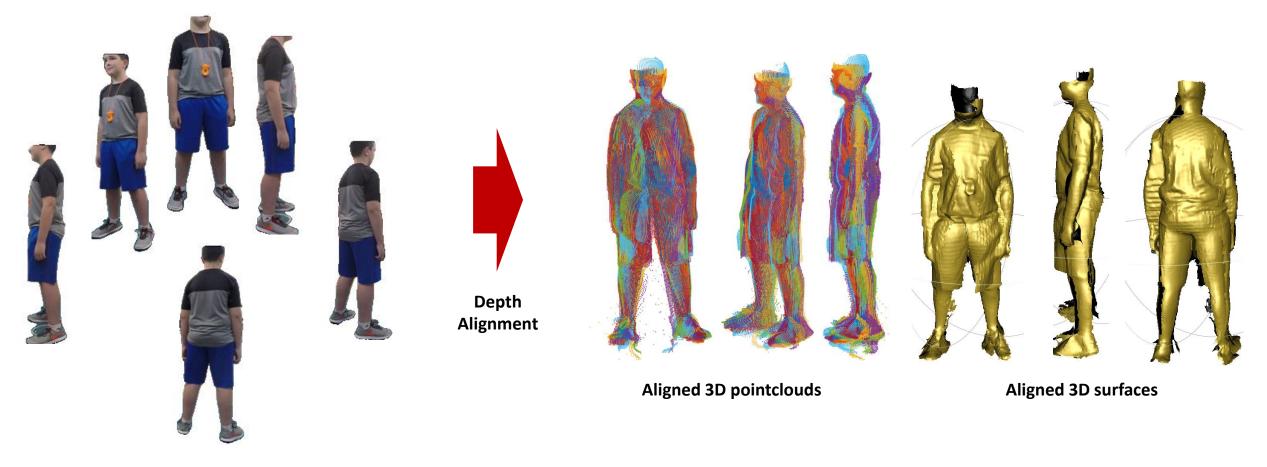






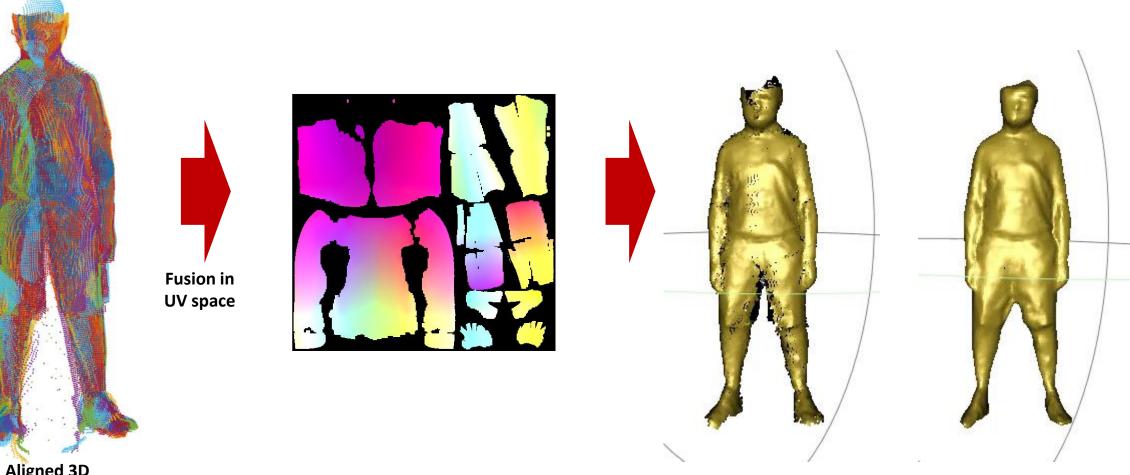
Dense reconstruction: Multiview HDNet

Problem: From multi-view image, predict the dense 3D reconstruction of human body





Dense reconstruction: Multiview HDNet



Aligned 3D pointclouds

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Fused geometry: pointcloud



Fused geometry: mesh



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Next steps

- Field experiments and data collection (multiple drones and actors)
- Emphasize multi-drone, multi-actor (tracking, planning, and reconstruction)
- Challenging scenarios (around trees and buildings with occlusions)



Above: Group members during trip to field test site



Principal Investigators and Organizations



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