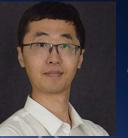
#2132923/2132773: NRI/Collaborative Research: Robotic Disassembly of High-Precision Electronics (Award Date: 02/01/2022)







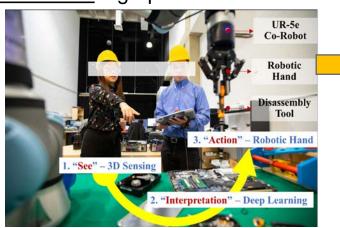


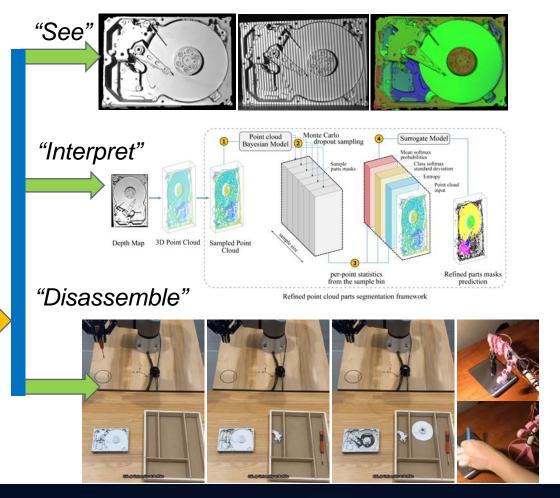
Minghui Zheng and Xiao Liang (University at Buffalo) & Beiwen Li (Iowa State University)

Challenges

- Increasing quantities of discarded high-precision electronics
- Many valuable components are not recycled due to high labor cost
- Disassembly requires high robotic dexterity and accuracy to accomplish

Solution: A novel robotic system that can accurately <u>see</u>, <u>interpret</u>, and <u>disassemble</u> high-precision electronics.





Scientific Impacts

- Addressing the mapping and Aldriven point cloud interpretation for complex surfaces
- Novel lightweight robotic hand design and high-precision manipulation algorithm for flexible disassembly

Broader Impacts

- Address labor shortages in the recycling industry.
- Reduce waste from discarded electronics.
- Promote environmental and manufacturing sustainability.
- Broaden participation, including participation by young people and underrepresented groups.