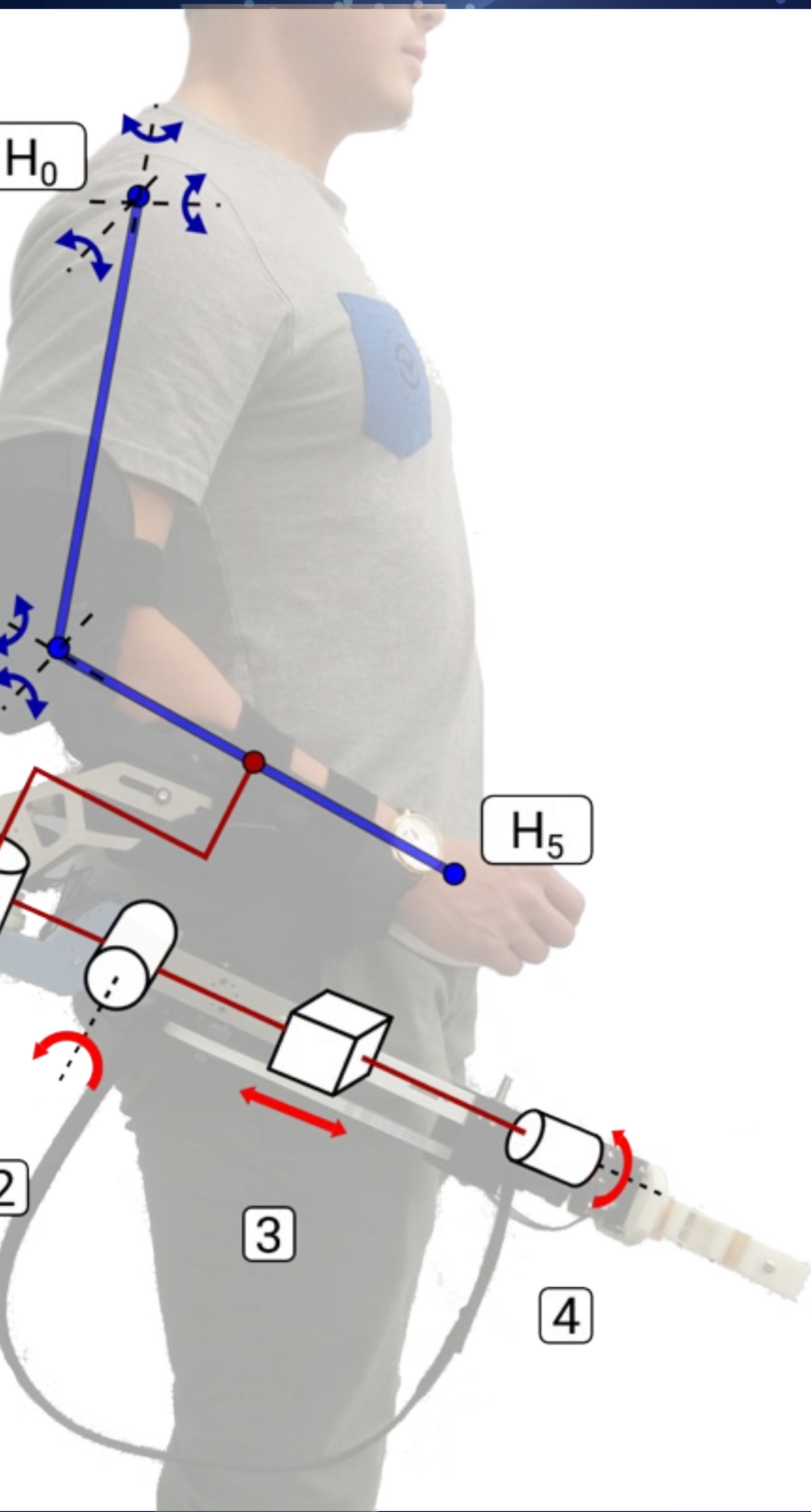
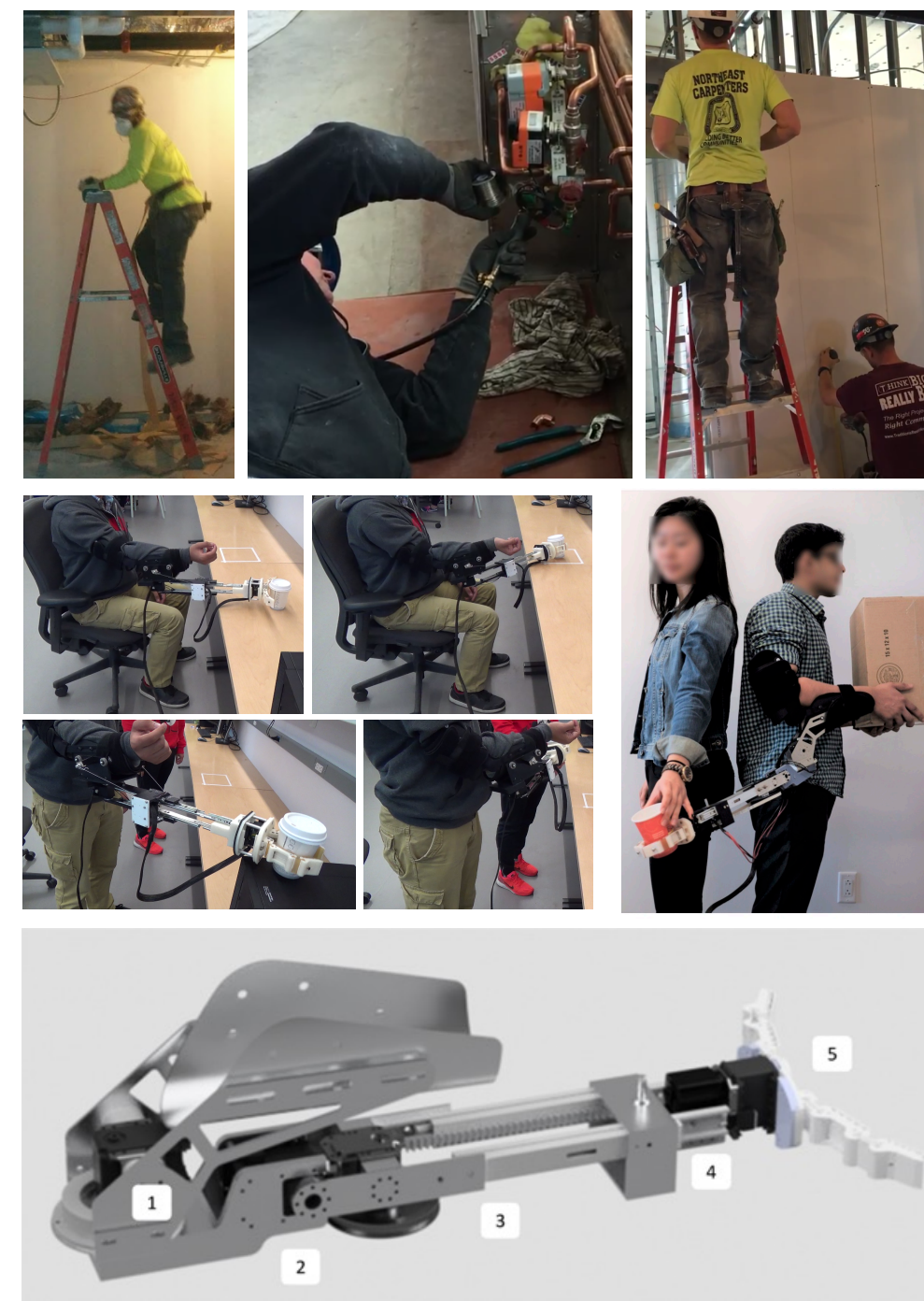




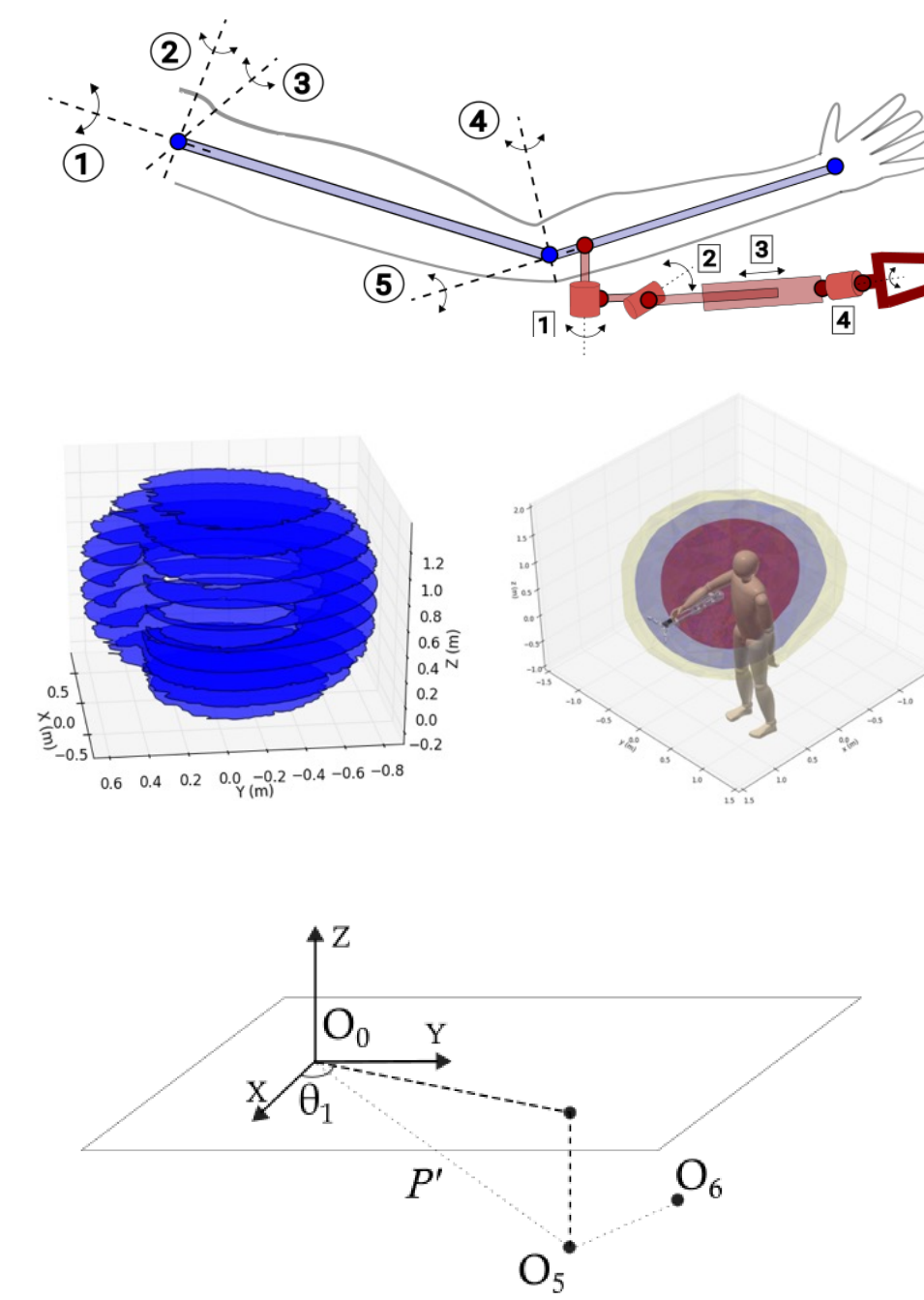
Project Summary



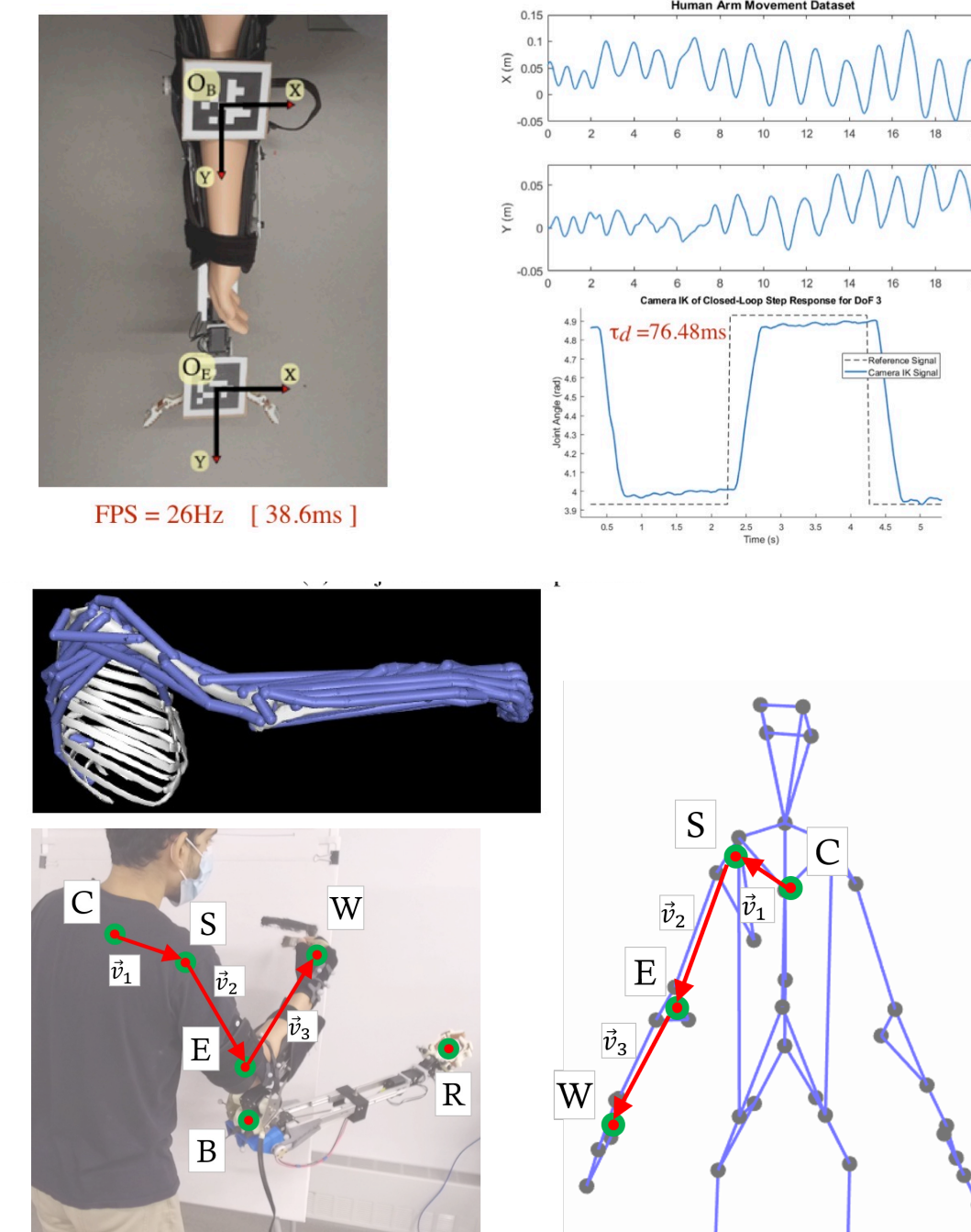
1. Design



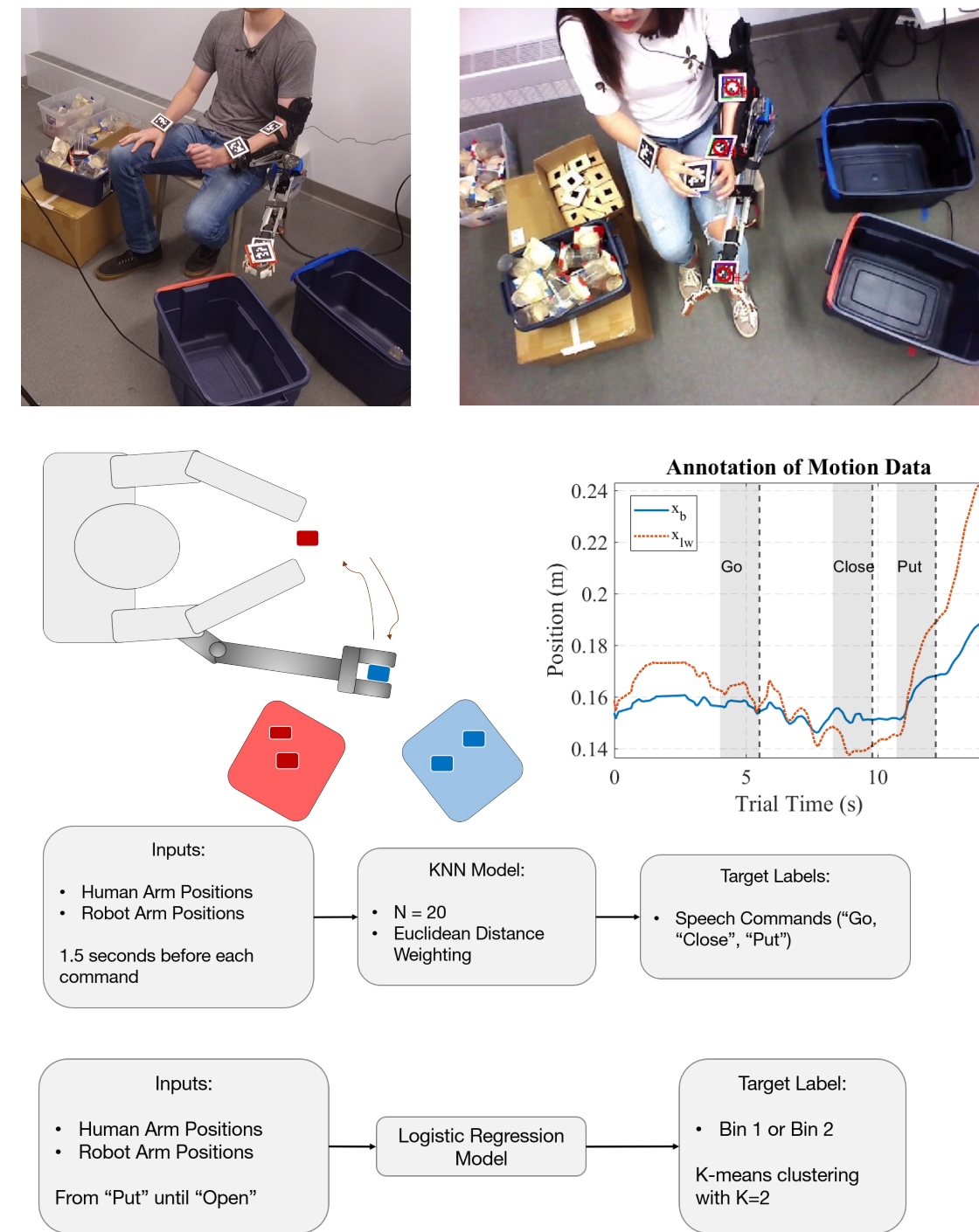
2. Kinematics and Dynamics



3. Biomechanics, Control, and Stabilization



4. Autonomy



Impact on Society

- More usable wearable robotics (WR)
- Safer and more ergonomics WR
- For manufacturing, logistics, and construction

Impact on Outreach and Education

- 1st Workshop on Supernumerary Robotic Limbs
- Position paper galvanizing the community.

