Adaptive Water Quality Sampling with Autonomous Vehicles with Applications to Nitrate Deposition

- Marin Kobilarov (JHU), Gaurav Sukhatme (USC), William Ball (JHU/CRC)
- Johns Hopkins University, Univ. of Southern California, Chesapeake Research Consortium
- marin@jhu.edu

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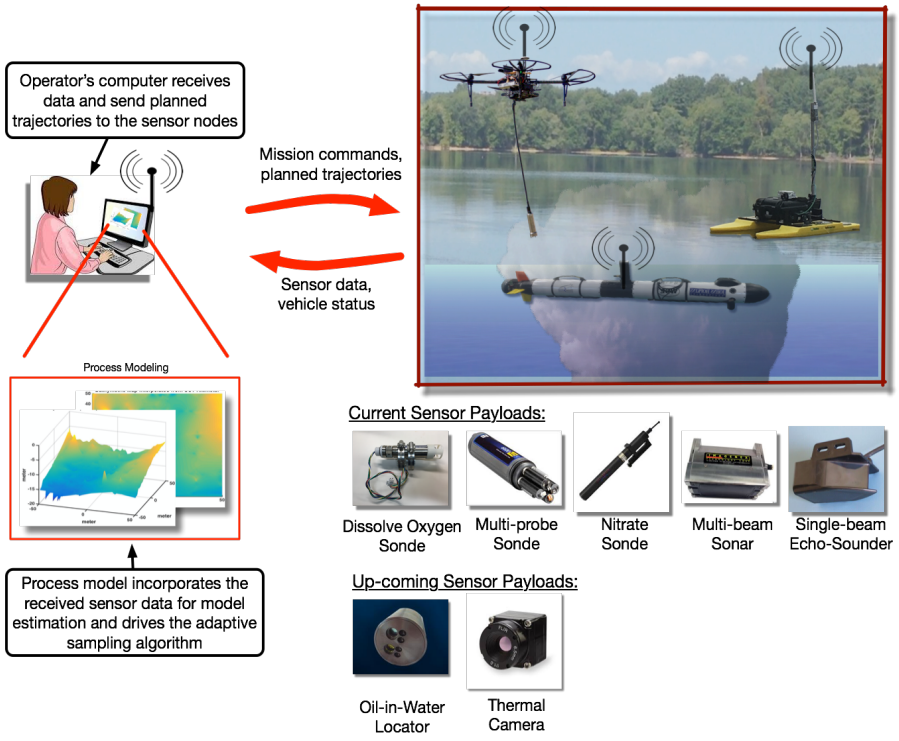
Description

Goals of This Project

•discover and understand processes affecting water quality

•water sampling and monitoring is currently very sparse and cannot capture key pollution factors

•leverage autonomous aquatic vehicles and human guidance for faster and more precise intelligent data gathering



Findings

•For the first time we demonstrated a system capable of real-time adaptive sampling in 3D, to track hypoxia in Chesapeake Bay