

Agile and Dynamic Interactions for Mobile Manipulation



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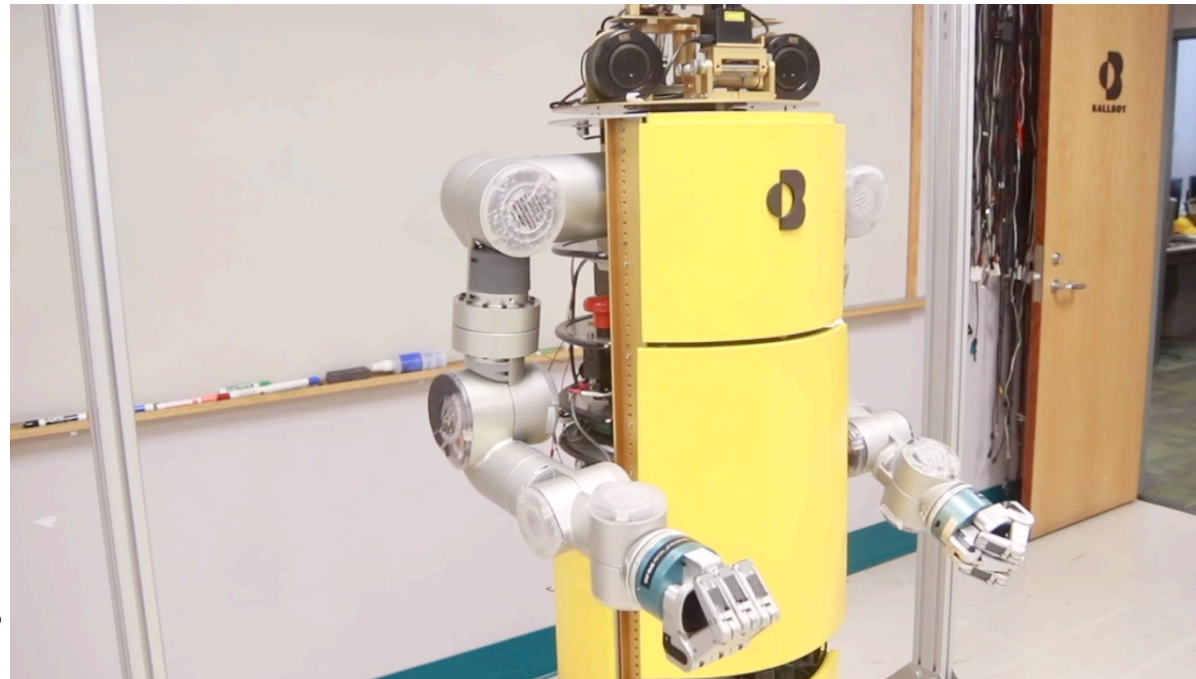
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Challenges

- Work safely with people in crowded environments
- Exploit dynamic interactions with robot's surroundings

Approach

- Human subject study
- Learn from observing humans
- Dynamic skills and reflexes



Integrative Tasks

