

Arbiter PUF Faults: Impact, Testing, and Diagnosis

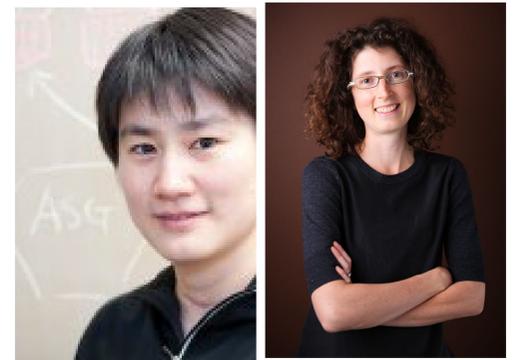
PUF = Physically Unclonable Function (hardware security primitive)

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Award # 1909547

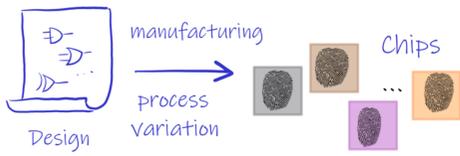
CIF: Small: Analytically Predicting Strong PUF Responses from Few Known CRPs

Y. Wei, T. Fox, V. Dumoulin, W. Rao and N. Devroye "Faults in Arbiter PUFs: Impact, Testing, and Diagnosis" Design, Automation and Test in Europe Conference (DATE), March 2022.



Physically Unclonable Functions (PUFs) in General

→ Hardware security primitives offering a unique "fingerprint" for each chip.



Physically Unclonable Function
 $c \in \{0, 1\}^n \rightarrow R(c) \in \{\pm 1\}$

Input: Challenge
 $c := \{c_1, c_2, \dots, c_n\} \in \{0, 1\}^n$

Output: Response
 $R(c) \in \{\pm 1\}$

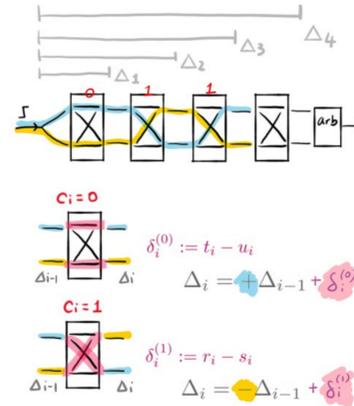
Strong PUFs
 ▶ Hardware cost: $O(n)$
 ▶ Truth table size: $O(2^n)$



PUFs: Same design + manufacturing process variation = unique function per chip.

Math Model for APUF

→ Recursive notation of $\Delta_n(c)$ as a function of selected $\delta_i^{(x)}$ delay differences.



Challenge
 $c := \{c_1, c_2, \dots, c_n\} \in \{0, 1\}^n$

Delay difference elements:
 $\delta_i^{(0)} := t_i - u_i$ (selected if $c_i = 0$)
 $\delta_i^{(1)} := r_i - s_i$ (selected if $c_i = 1$)

Recursive accumulated delay difference:
 $\Delta_i(c) = \begin{cases} +\Delta_{i-1}(c) + \delta_i^{(0)}, & c_i = 0 \\ -\Delta_{i-1}(c) + \delta_i^{(1)}, & c_i = 1 \end{cases}$

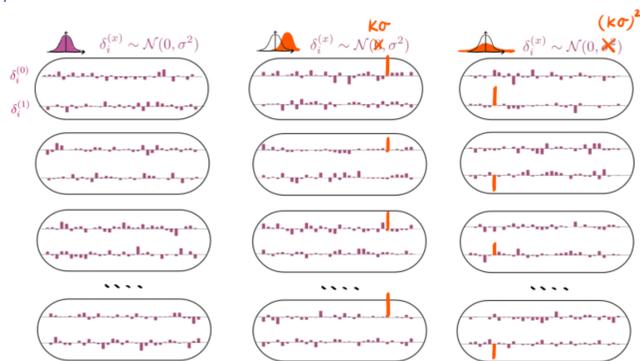
Response
 $R(c) := \text{sign}(\Delta_n(c)) \in \{\pm 1\}$

Challenge: how to find "abnormal" elements?

Why? Abnormal elements affect bias and uniqueness!

Fault Models for APUF Production

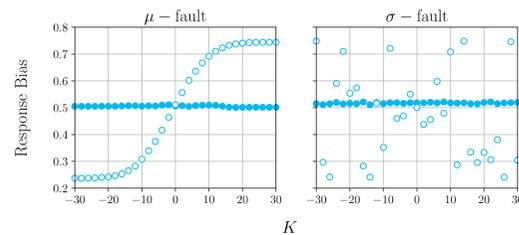
→ μ -fault & σ -fault



Normal δ
 $\delta_i^{(x)} \sim \mathcal{N}(0, \sigma^2)$

Abnormal δ with μ -fault
 $\delta_j^{(y)} \sim \mathcal{N}(K\sigma, \sigma^2)$

Abnormal δ with σ -fault
 $\delta_j^{(y)} \sim \mathcal{N}(0, (K\sigma)^2)$

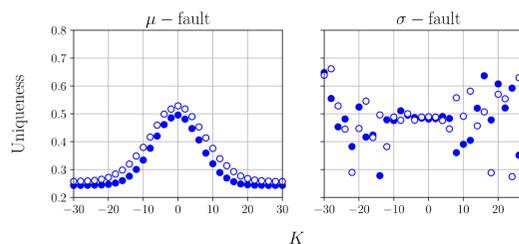


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● : at stage $i \neq n$
 ○ : at stage $i = n$



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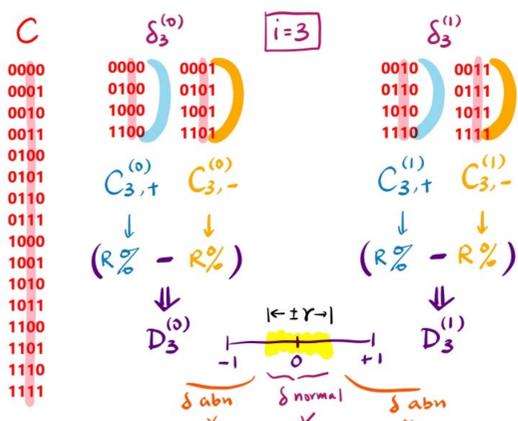
Abnormal δ with σ -fault
 $\delta_j^{(y)} \sim \mathcal{N}(0, (K\sigma)^2)$

● : at stage $i \neq n$
 ○ : at stage $i = n$

Solution: find challenge sets that pinpoint faults

Main Algorithm for Testing and Diagnosis

→ Iteration $i = 3$: form target sets for $\delta_3^{(x)}$, find response biases, use difference scores to evaluate $\delta_3^{(x)}$.



Difference Score
 $D_i^{(x)} := B(C_{i,+}^{(x)}) - B(C_{i,-}^{(x)}) \in [-1, 1]$

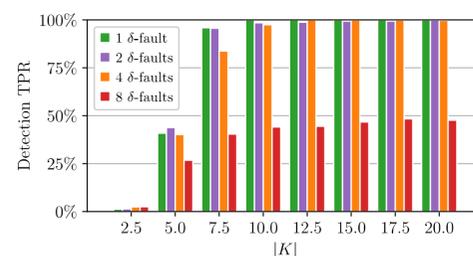
Criteria: choose $\gamma \in [0, 1]$

- ▶ $D_i^{(x)} > \gamma \implies \delta_i^{(x)} > T$
- ▶ $|D_i^{(x)}| < \gamma \implies |\delta_i^{(x)}| \leq T$
- ▶ $D_i^{(x)} < -\gamma \implies \delta_i^{(x)} < -T$

Looping through $i = 1$ to n
 Split $C \rightarrow C_{i,+}^{(0)}, C_{i,-}^{(0)}, C_{i,+}^{(1)}, C_{i,-}^{(1)}$
 Collect $B(C_{i,+}^{(x)})$
 Compute $D_i^{(x)}$
 Diagnose $\delta_i^{(x)}$

Results of Testing: Can bad APUFs be detected?

→ Yes, by the proposed algorithm: ~100% detected for up to 4 abnormal δ s per 64-bit APUF with $K > 10$.



True Positive: TP
 # of bad APUFs correctly detected

False Negative: FN
 # of bad APUFs incorrectly identified as good

True Positive Rate: $TPR = \frac{TP}{TP + FN}$
 % of bad APUFs detected

Setting: A total of 1000 64-bit bad APUFs with 1, 2, 4, or 8 δ -faults, varying fault intensity K , and randomly selected fault position.

Broader Impact (impact on society – who will care)

- simple, effective tool for manufacturers of PUFs
- Native APUF fault model

Broader Impact (education and outreach)

- ECE 464: Testing and Reliability of Digital System course at UIC
- Women in Engineering Summer Program: Devroye participates yearly as speaker.

Broader Impact and Broader Participation (quantify potential impact)

- Supported 4 excellent REUs, one is co-author on published paper
- Inter-disciplinary project hardware security, testing, and statistics / information theory

