Assistive Robots For Blind Travelers

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Human-robot interaction for robots assisting blind travelers navigate unfamiliar urban and built environments

Enable robots and blind travelers to interact in meaningful ways to enhance the safety and independence of urban navigation for all



Approach

Robots live in the building:

- Helps with maps, localization, & batteries
- More appropriate cost model & wider impact

In the context of assistive robots for blind travelers:

- Accessible interfaces for assistive robots
- Assistive interaction between humans and robots
- Effective cooperation between a variety of humanrobot and robot teams

Stakeholders and community partners



Research + Continuous Engagement

Include B/LV adults in our research to inform and evaluate progress

- How to describe a robot?
- What are the right analogs?
- Landmarks and navigation

STEM outreach, industry contact, and press visits

















Kiosk Robot (Rathu Baxter)

Zhi Tan (PhD)

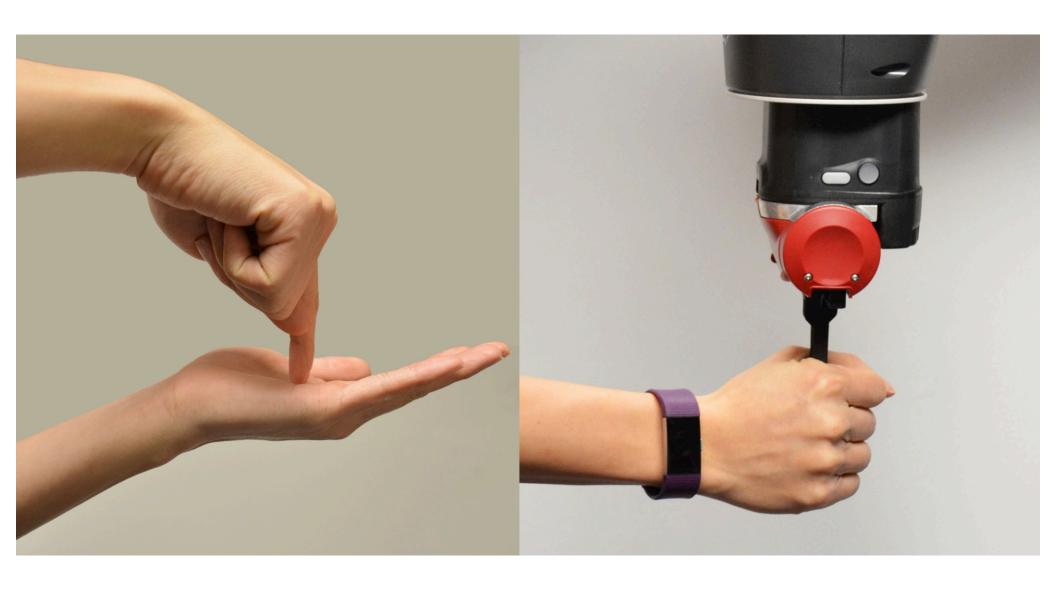
Kiosk robot, 24/7 information Spatial information



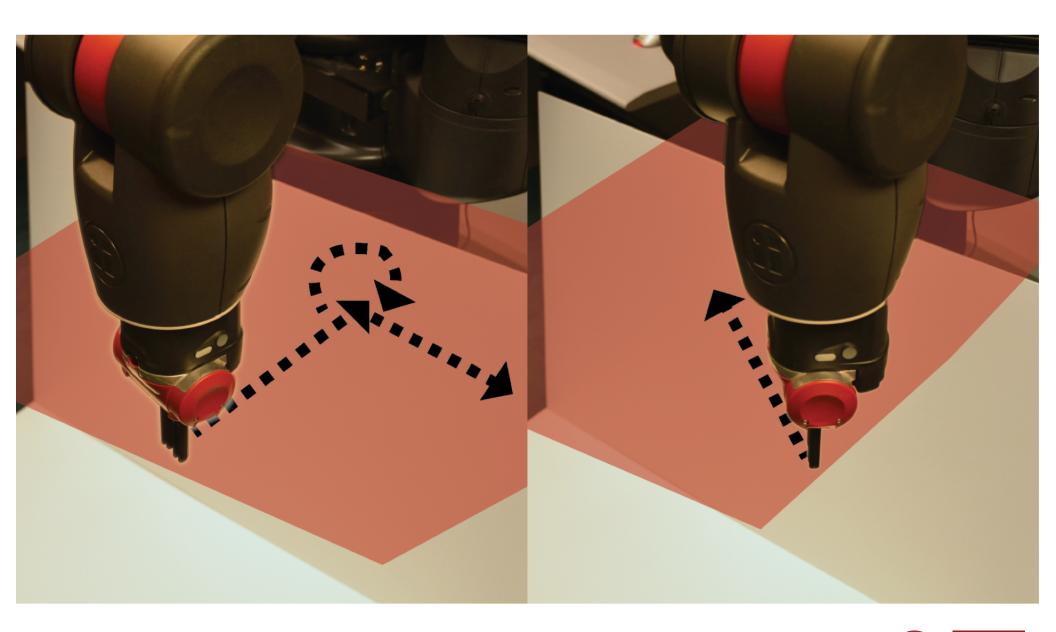




Map Instruction from O&M Specialists









Guide Robot (Podi)

Amal Nanavati & Joe Connolly

Undergrads

System integration

Appropriate coupled motion

- Drop-offs
- Rounding corners





Personal Haptic Guidance (Sphero)

Zhi Tan (PhD)
Tan et al 2018 RO-MAN

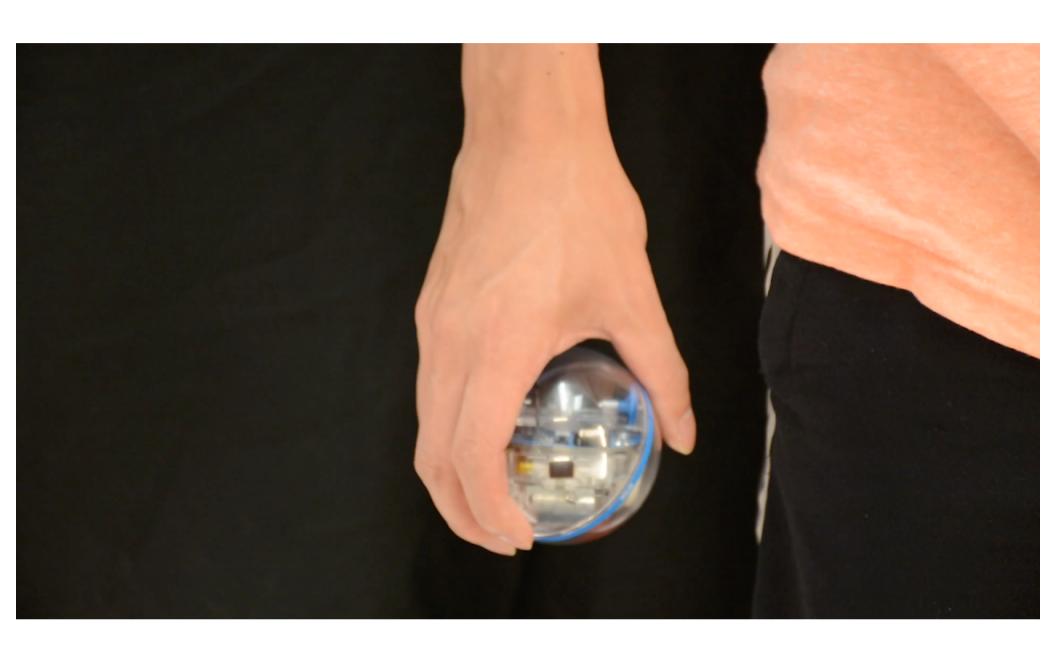
Prior methods

- Custom hardware
- Single vibration

Low cost, commodity robot Easy to replace Designed for kids: durable



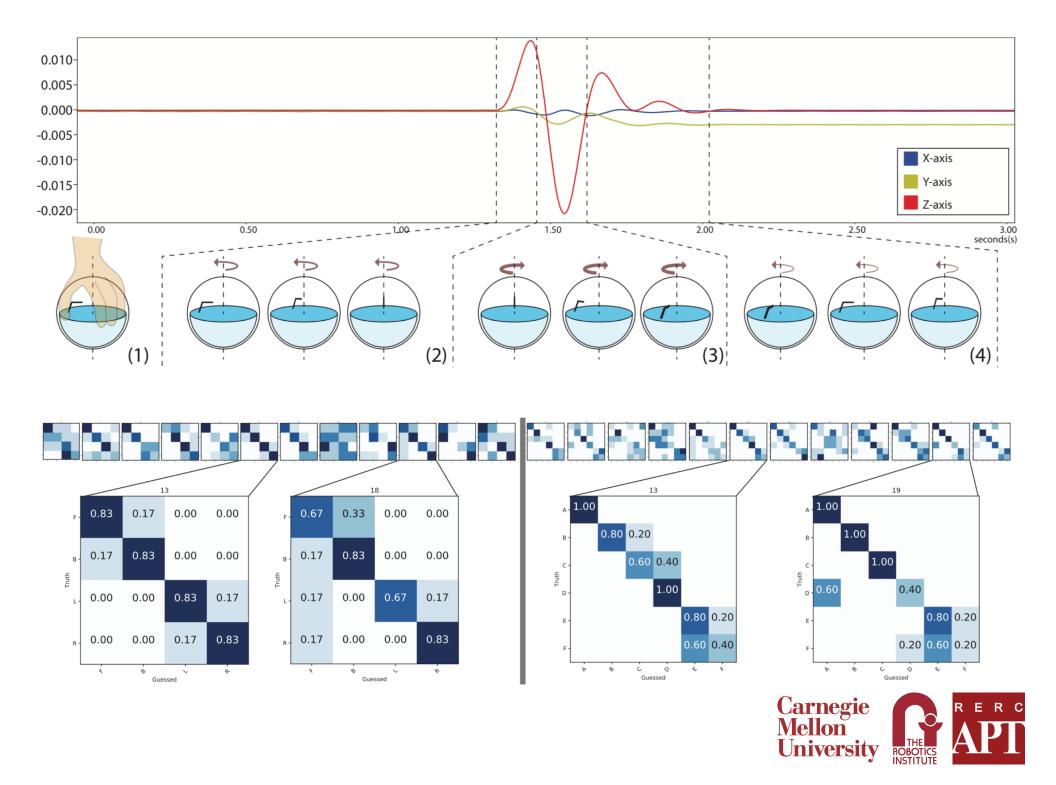












Robot Abuse

Tan, et al 2018 HRI

People abuse robots

How to encourage bystander intervention?

Brscić et al 2015 HRI









Can Robot Encourage Intervention?

Participant witnesses another person (confederate) abuse the robot

Robot responds with:

- Nothing
- Shutdown
- Emotion

Between subjects





Yes (partially)

People are willing to help the robot if the robot is being abused

The **shutdown response** was the most promising response among the responses we tested in preventing bullying behavior



Current Work

Systems level questions

Dovetail into follow-on project

- DRRP on Robotics and Automation for Inclusive Transportation
- National Institute on Disability, Independent Living, and Rehabilitation Research (NIDILRR, 90DPGE0003)
- Map integration opportunities with NavCog app
- www.cs.cmu.edu/~astein/rait



Team

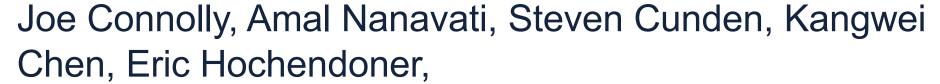
Current team:

Xiang Zhi Tan, Allan Wang

Alumni:

Byung-Cheol Min (Perdue)

Ermine Teves (Apple)



Aditi Kulkarni, Praneetha Sistla, Ankita Arvind, Vivek Nair, Lucy Pei, Suryansh Saxena, Lynn Urbina

Visitors:

Alvaro Castro-Gonzalez (University Carlos III de Madrid)

Victoria Plaza (Universidad de Málaga)





