

CPS Frontiers Panel

2022 CPS PI Meeting

Tuesday, November 8, 2022

Meeko Oishi

Professor, Electrical and Computer Engineering

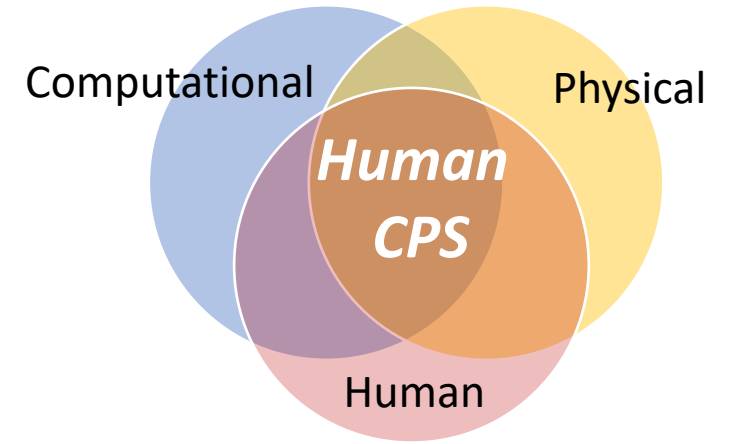
University of New Mexico

oishi@unm.edu

Cognitive Autonomy for Human CPS

State of the art

- Users are responsible for becoming skilled through specialized training
- System behavior does not adapt to human cognitive workload, attention, trust, or priorities

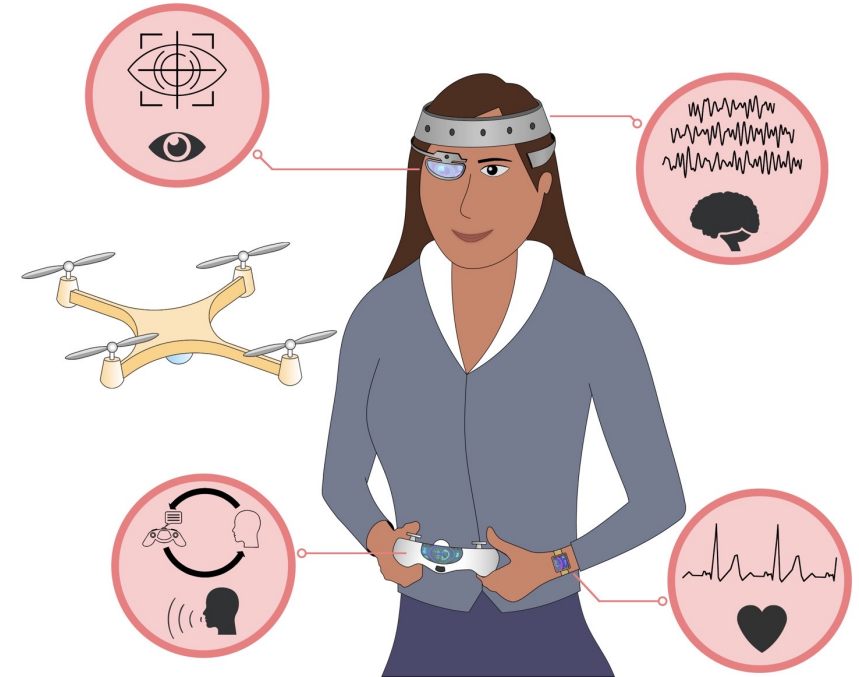


How can we design human CPS to be highly responsive to the human, yet amenable to formal guarantees?

Vision

Develop scientific and engineering principles so that cognitive autonomous systems can:

- Estimate workload, skill level, trust in real time
- Learn individual priorities and preferences
- Infer potential blind spots
- Anticipate and prevent “bad” behaviors
- Provide reasoned guidance post-hoc, and multi-modal communication in run-time
- Enable safe, effective, and reliable performance for *any* human skill level



Human cognitive state dynamics are required for effective control of human CPS.

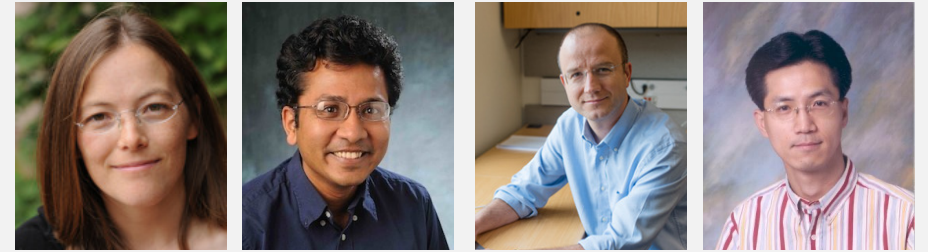
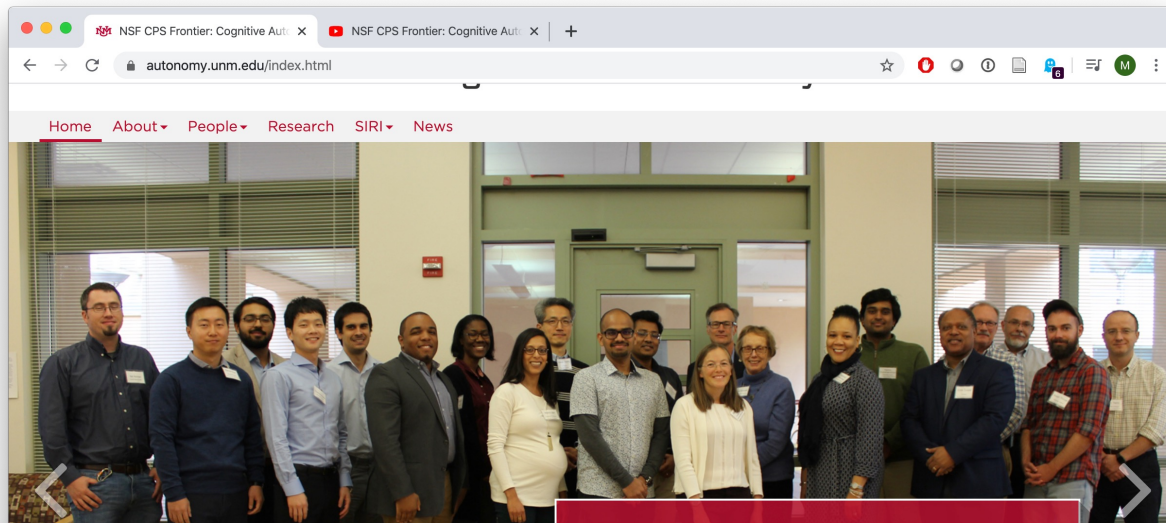
Cognitive Autonomy for Human CPS



- *Control theory*
- *Autonomous systems*
- *Human factors*
- *Human-centered design*



<http://autonomy.unm.edu>



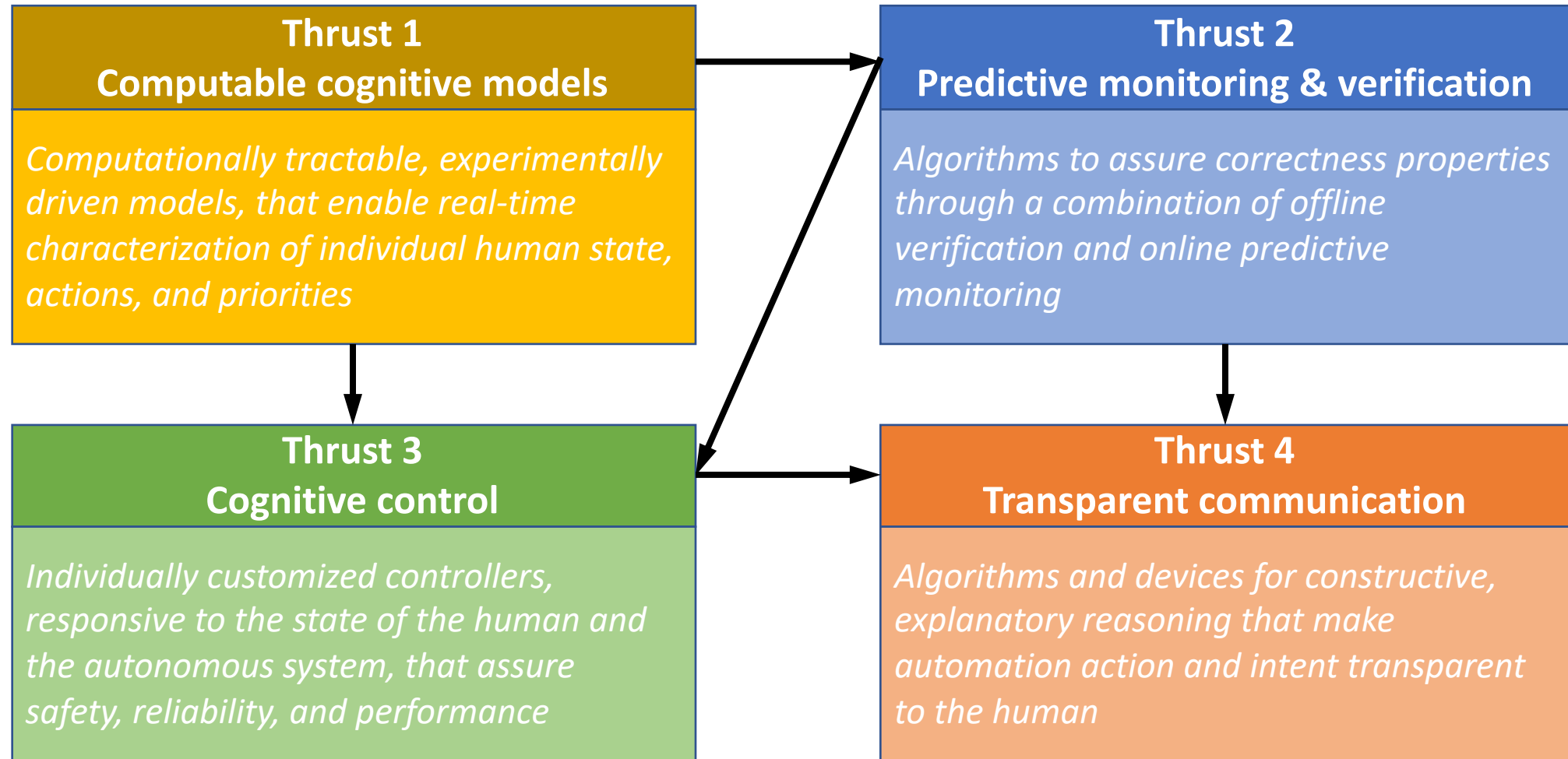
Meeko Oishi Sriram Sankaranarayanan Ufuk Topcu Inseok Hwang



Neera Jain Tahira Reid Smith Brandon Pitts Tryphenia Peele-Eady

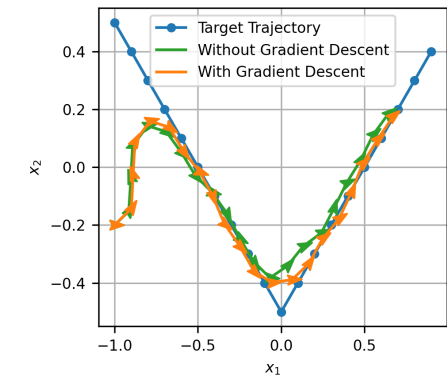
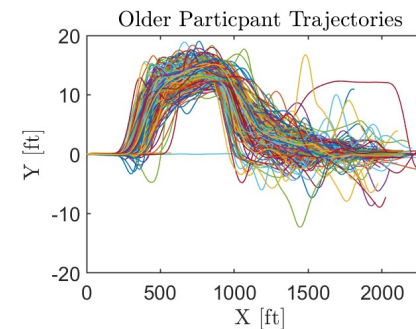
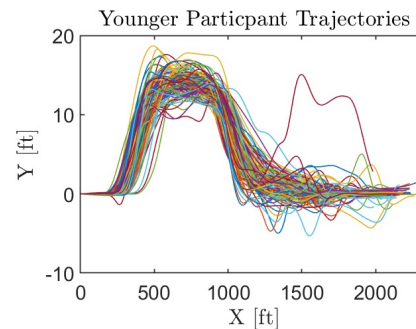
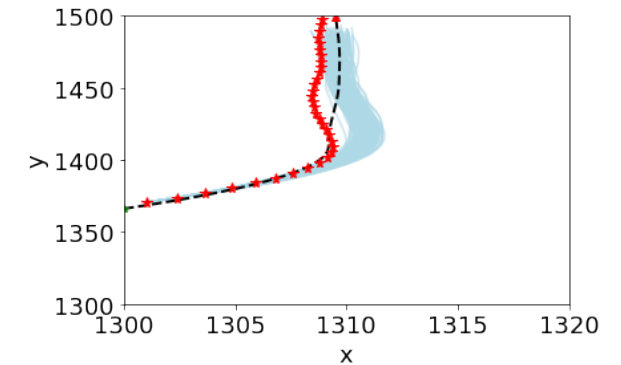


Potential Impacts and Key Outcomes



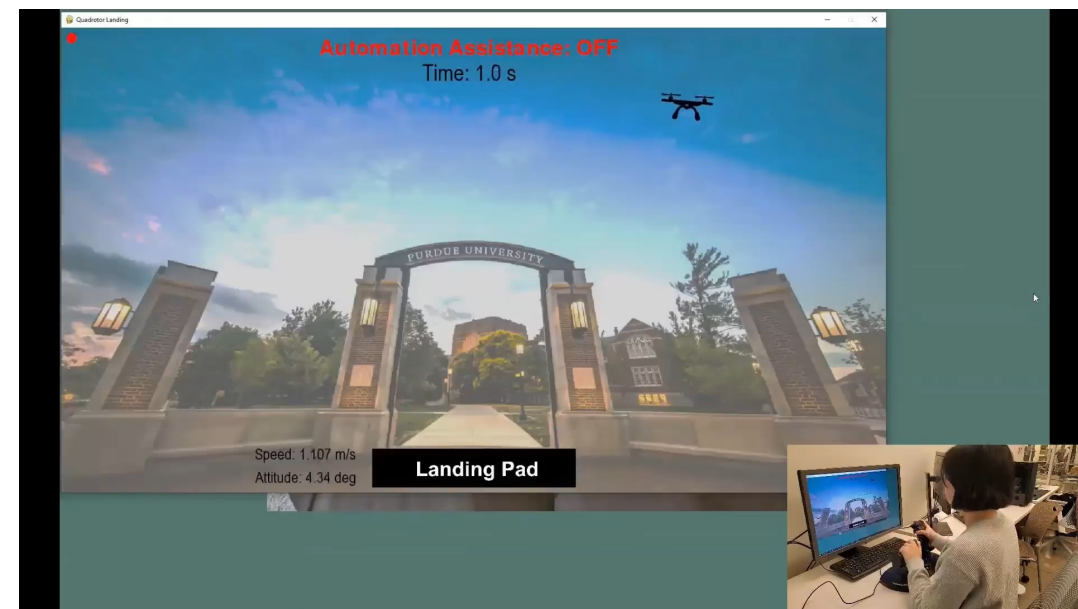
Potential Impacts and Key Outcomes

- Integration of data-driven and model-based methods is important for capturing the breadth and complexity of naturalistic human action
 - Risk fields for predictive models of probabilistic human action in an advanced driving simulator
 - Conditional distribution embeddings characterize relative impact of tactile alerts in a collision avoidance maneuver.
- Carefully designed human subject experiments are required for design and validation
 - Conditional distribution embeddings for dynamics-aware, stochastic optimal control



Potential Impacts and Key Outcomes

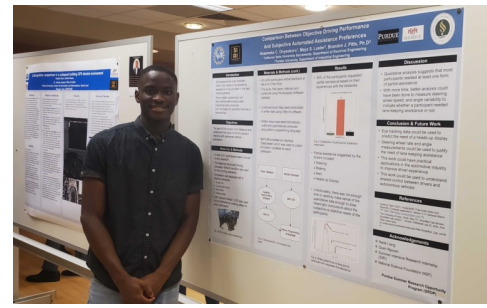
- Exploiting psychophysiological sensing for feedback can dramatically impact performance
 - Stochastic IRL for shared controller synthesis under human learning
- Cognitive state feedback (via trust and self-confidence) can accelerate human learning
 - Calibration of self-confidence enables pilot performance and accelerates improvements in task performance.



SIRI: Summer Intensive Research Institute

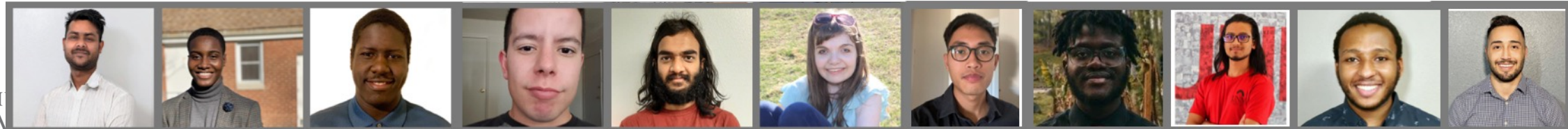
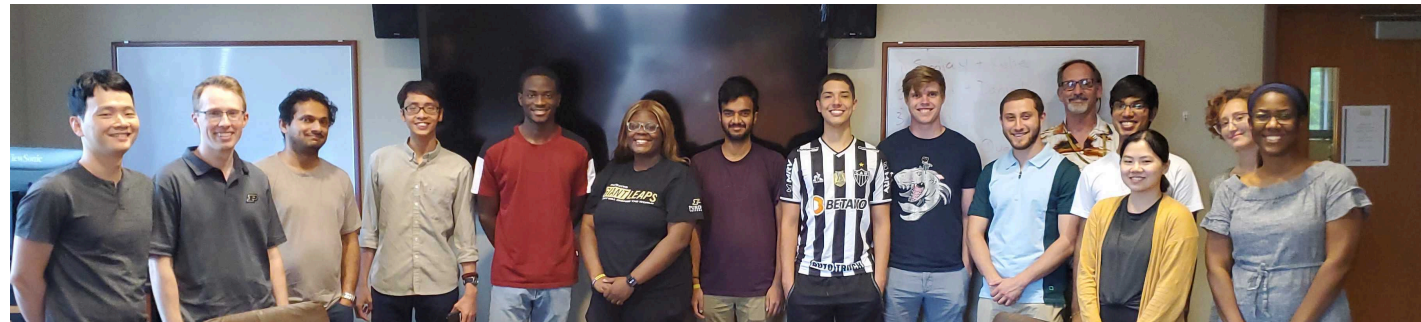
Culturally responsive undergraduate research program

- Collaboration between UNM and Purdue
- Goals
 - Encourage underrepresented students to pursue CPS
 - Develop professional competencies
 - Provide opportunities for students to connect their research experience with their cultural background
- Research to characterize transitions to belonging



NM Engineering Student Success

PURDUE UNIVERSITY Summer Research Opportunities Program (SROP)



Challenges and Strategies

- Disciplinary boundaries and conceptual differences
 - Presumed knowledge (jargon) and concepts
 - Cross-cutting sub-groups within the project
- Experiment design for prediction and control
 - Creating sufficiently rich environments
 - Generalizability of experiments



Opportunities and Rewards

- Time and space to work with depth on meaningful problems
- Establish new collaborations, cement existing ones
- Student opportunities
 - Student exchange
 - Internships
- Larger impact
- Broadening participation and creating pipelines

COGNITIVE AUTONOMY FOR HUMAN CPS: TURNING NOVICES INTO EXPERTS



Meeko Oishi



Sriram
Sankaranarayanan



Ufuk Topcu



Inseok Hwang



Neera Jain



Tahira Reid
Smith



Brandon Pitts



Tryphenia
Peele-Eady