

Collaborative Research: NRI: Ocean-Powered Robots for Autonomous Offshore Aquaculture

Project Overview and Year 2 Development

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Motivation

Offshore Aquaculture

- The fastest-growing source of animal protein since 1990
- Yields 10-100 times the fish production (compared w. inshore)
- **United States** remains a minor aquaculture producer (ranked **16th** in 2018)



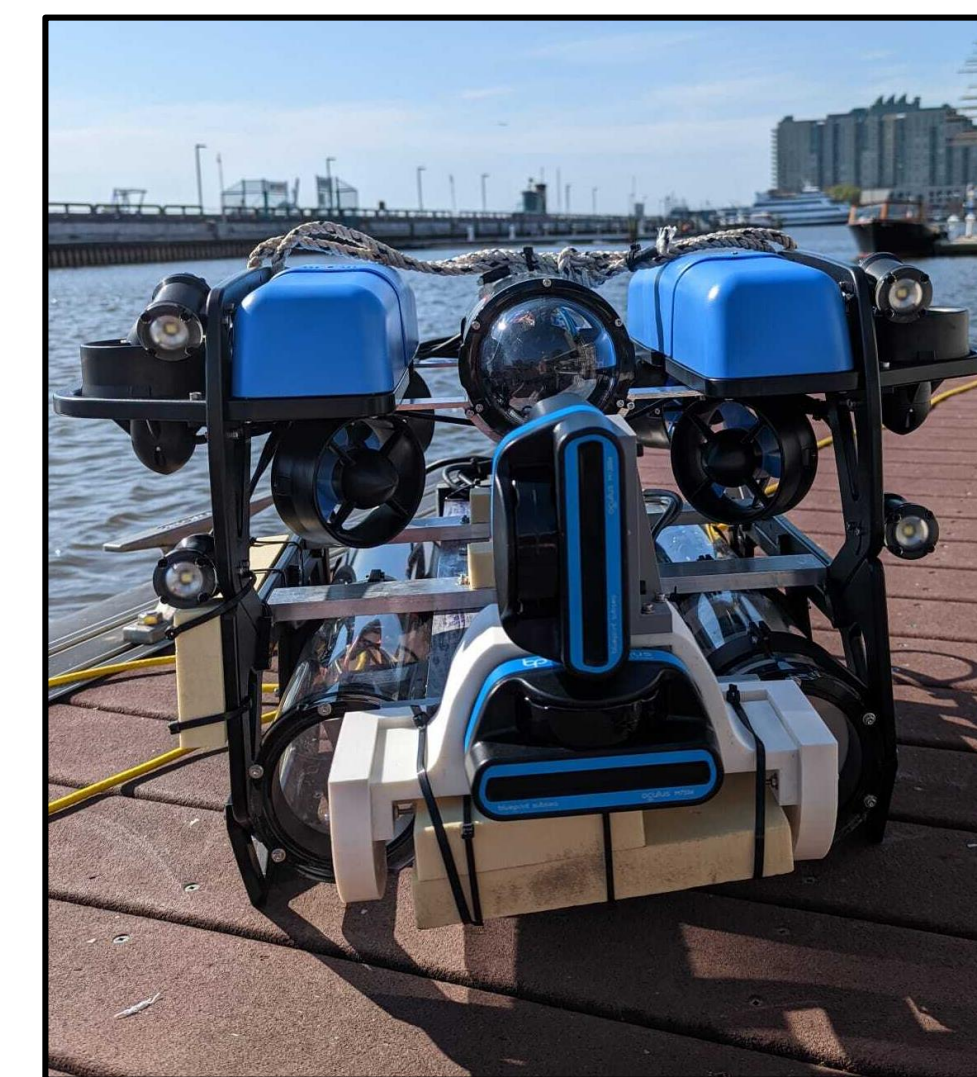
Issues Identified in Offshore Aquaculture

- Labor-intensive and high-risk tasks (Cleaning; Dead fish removal)
- Offshore environment is subject to high waves and aggressive sea creatures

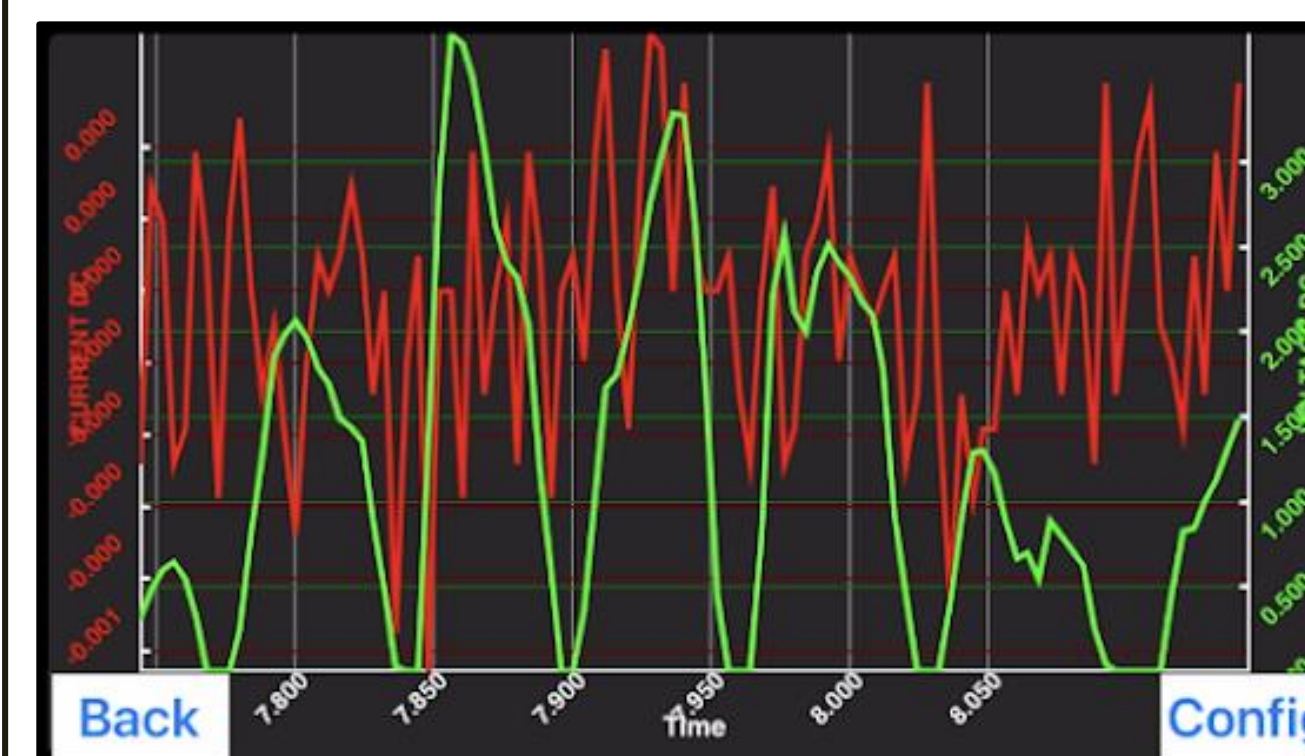
Limitations of Existing Technologies

- **Power Supply:** Battery or Diesel-powered at surface, limited electricity production
- **Cleaning Performance:** high-pressure water blasting introduces waste into fish pens
- **Dead Fish Removal by Divers:** Daily cleaning by human divers, unnecessary human danger
- **Lack of Autonomy:** Skilled operation and careful monitoring are necessary

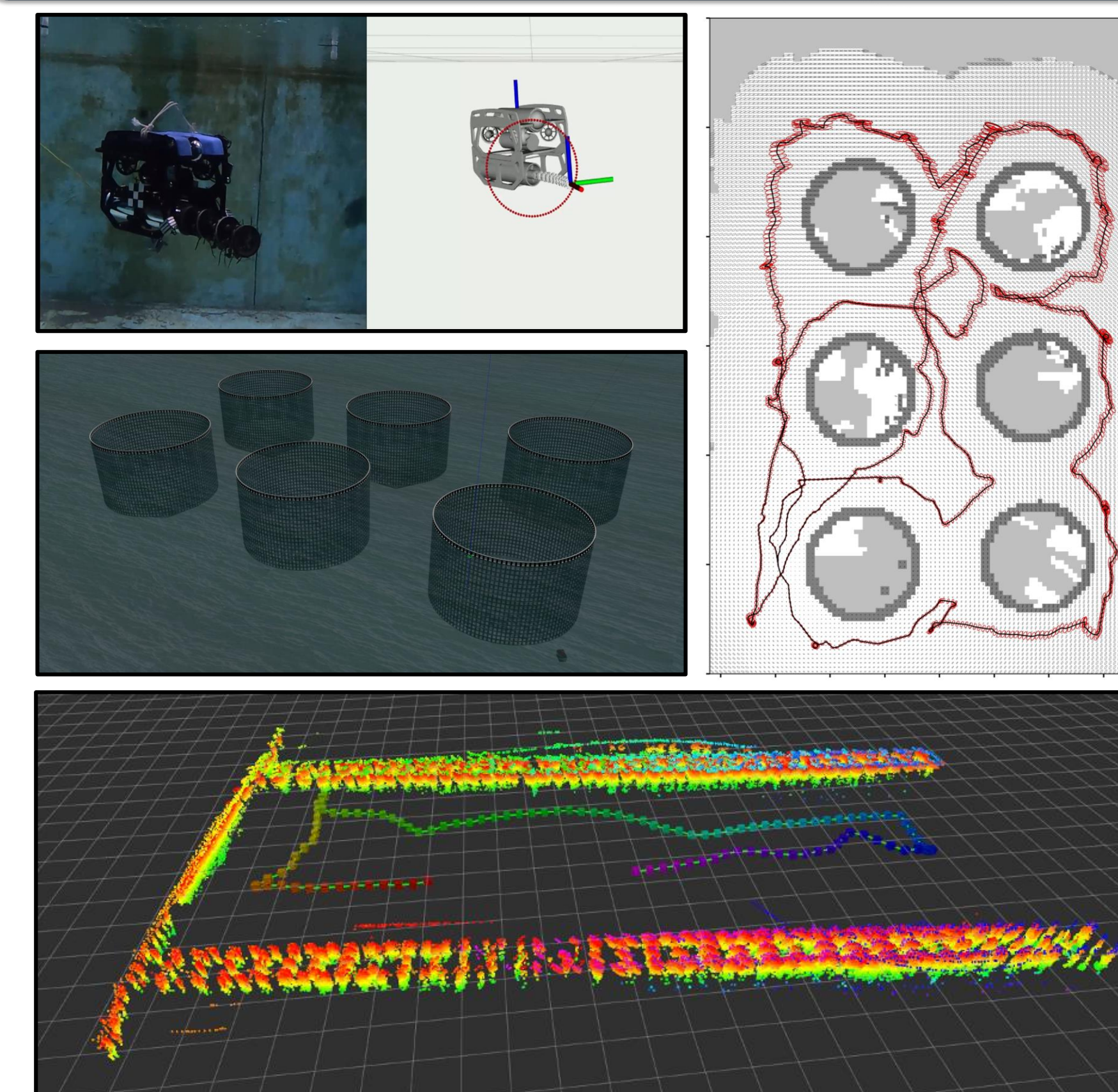
Developed Hardware Platforms



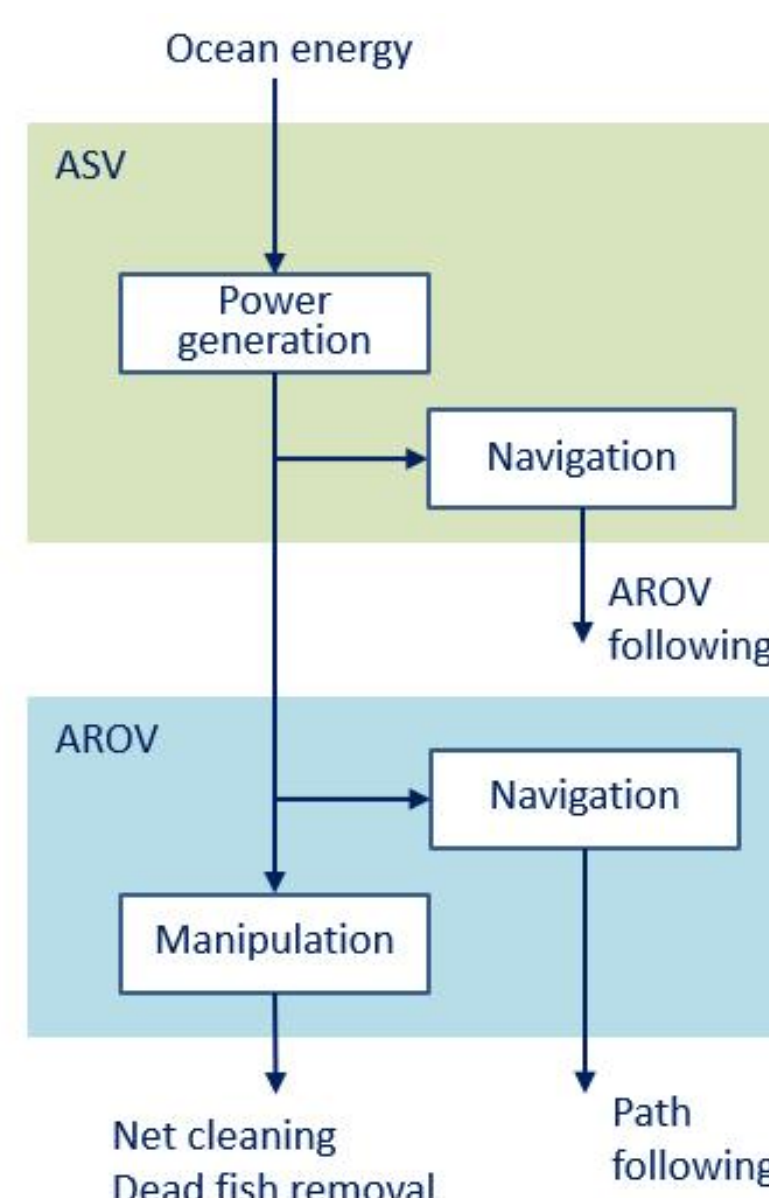
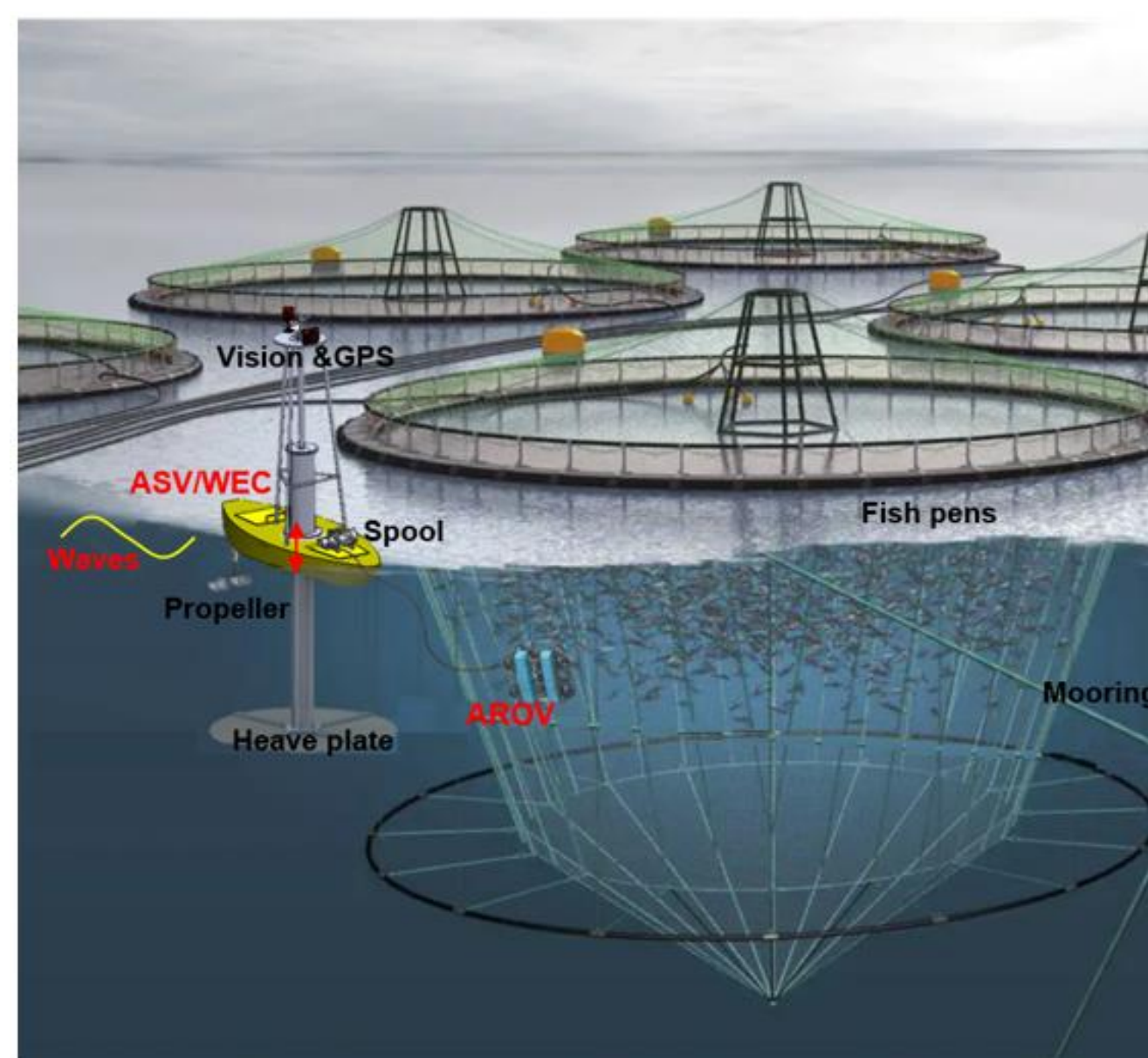
Wave Energy Converter



Autonomous ROV (AROV)



Proposed Solution



Autonomous Surface Vehicle (ASV) with Wave Energy Converter (WEC) – Harvests energy

Autonomous Remotely Operated Vehicle (AROV) – Consumes energy and does cleaning / dead fish removal