

NRI: FND: Customizable Haptic Co-Robots For Training Emergency Surgical Procedures

NSF #2102250

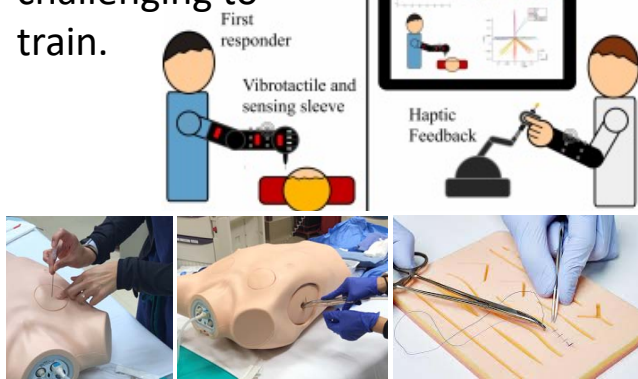
Ann Majewicz Fey, UT Austin

Caroline Park, UT Southwestern Medical Center

Edoardo Battaglia, University of Utah

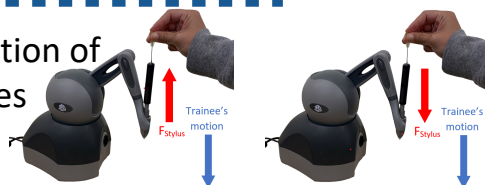
SCIENTIFIC CHALLENGE

Trauma skills require complex spatial coordination, a delicate sense of touch, and ability to work under intense time pressure – all are skills that are challenging to train.



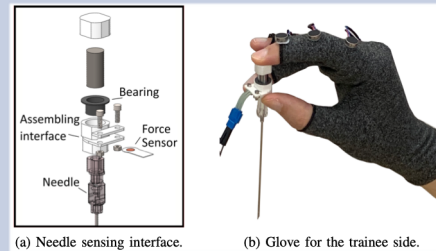
A1.2: Mentor Perception of Trainee Applied Forces

HAPTICS '22



SOLUTION: HAPTIC TELEMENTORING SYSTEM

TRAINEE SIDE



SHARED HAPTICS

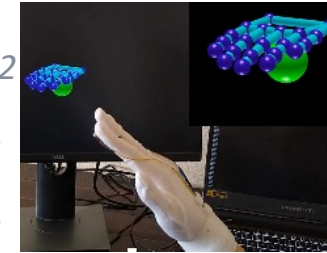
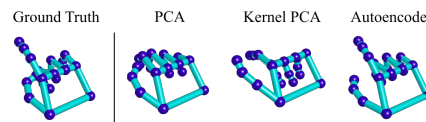
MENTOR SIDE



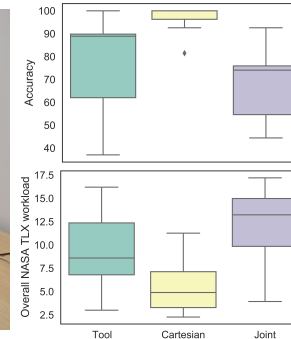
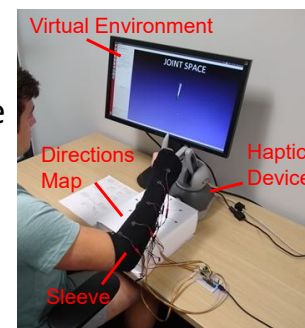
A1.1: Hand posture dimensionality reduction and reconstruction.

HAPTICS WIP '21 & ISMR '22

<https://github.com/ebattaglia/cHand>



A2: Intuitive Guidance for 3D Needle Insertion
HAPTICS '22



C1

	h	m	l
h	92.0%	8.0%	
m	5.3%	92.0%	2.7%
l		2.7%	97.3%

Graphics + Pushing

C2

	h	m	l
h	84.0%	14.7%	1.3%
m	26.7%	72.0%	1.3%
l		10.7%	89.3%

Graphics + Pulling

C3

	h	m	l
h	94.7%	5.3%	
m	9.3%	85.3%	5.3%
l		9.3%	90.7%

Graphics Only

SCIENTIFIC IMPACT

- Fundamental science of human movement guidance via haptics
- Design of co-robotics for medical applications

BROADER IMPACT

- Improving healthcare and quality of training of trauma skills.
- Team includes 2 REU students + 1 female URM graduate student.
- Engaging Engineering World Health Undergraduate Students in research