Cyber-Physical Sensing, Modeling, and Control with Augmented Reality for Smart Manufacturing Workforce Training and Operations Management

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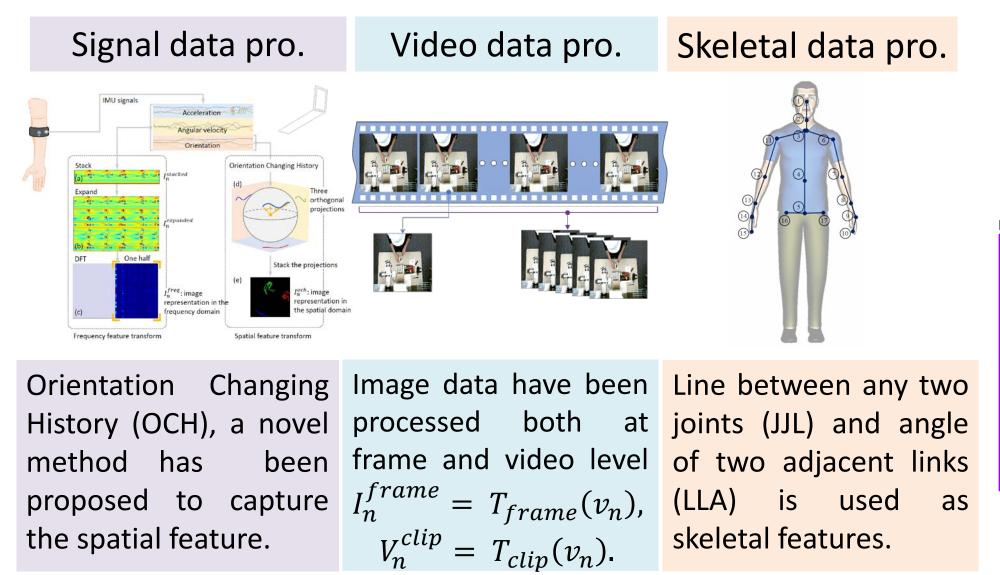
Key Focus

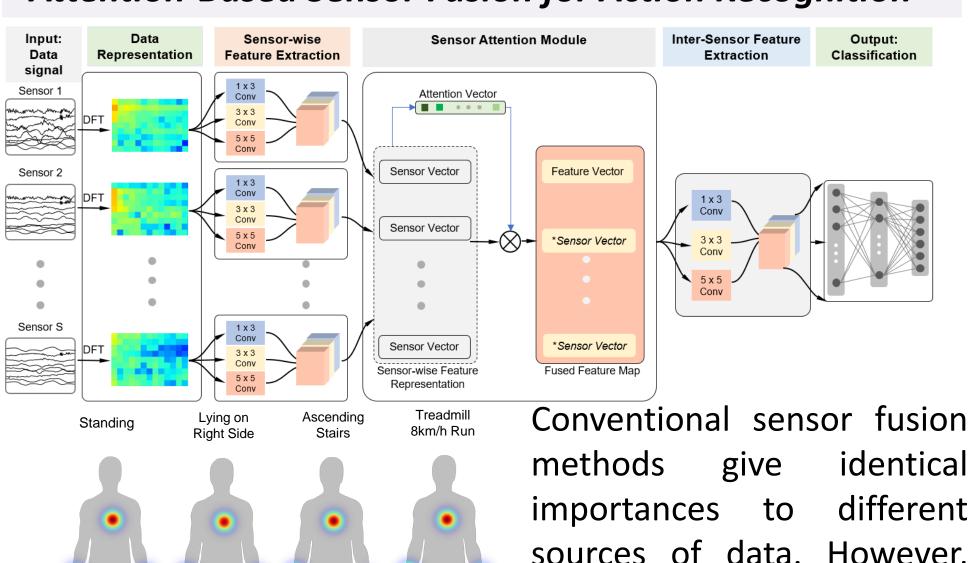
This project aims to develop a **worker-centered intelligent** manufacturing system to sense, understand, and optimize the learning and operations of manufacturing workers, so as to achieve significantly improved efficiency of worker operations ¹ behavioral training, effectiveness of management, and safety of front-line workers for smart manufacturing. While doing so, following fundamental challenges need to be addressed:

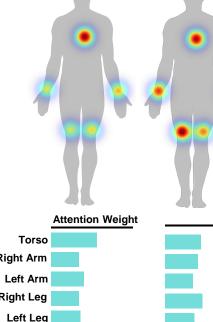
- Integration and fusion of multimodal sensor data
- Understand complex and intricate worker action
- Provide inclusive assistance in a real time manner and evaluate worker performance

1. Sensing and Data Acquisition ∕Ivo armbano

Webcam, Microsoft Kinect, and Leap Motion Controller have been used as ambient sensors to capture video data. These sensors have some issues with occlusion and cluttered background. To overcome this problem, Myo Armband, a wearable sensing device has also been used.



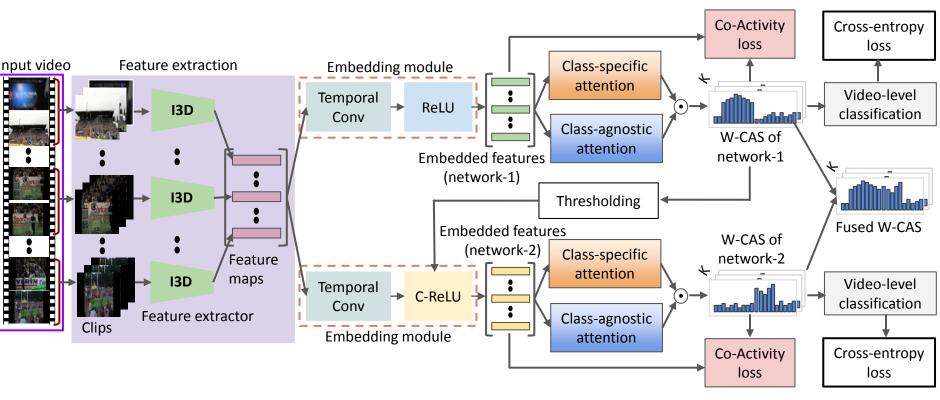




Action Completeness Modeling for Weakly Supervised **Temporal Action Localization**

Propose a novel end-toend weakly supervised Background interval framework that contains parallel action two classifiers to localize the complete action.

Action classifier-1 discovers the action instances in attention intervals, while the action instances in ambiguous intervals from action classifier-1 are discovered by the action classifier-2, based on the shared features.



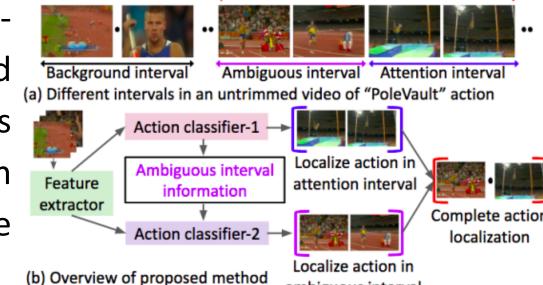
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2. Cognition

Attention-Based Sensor Fusion for Action Recognition

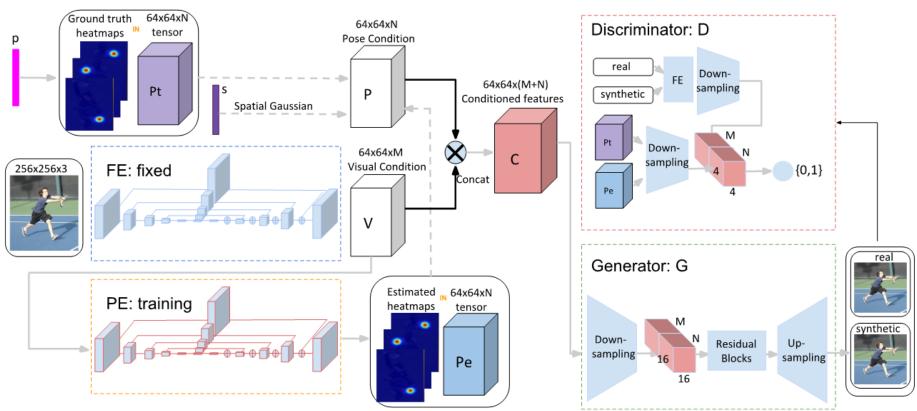
identical different sources of data. However, body parts do not contribute equally for one action. Thus, we propose attention based sensor fusion methods to learn the sensor importance automatically.

'PoleValut" action (complete action interva

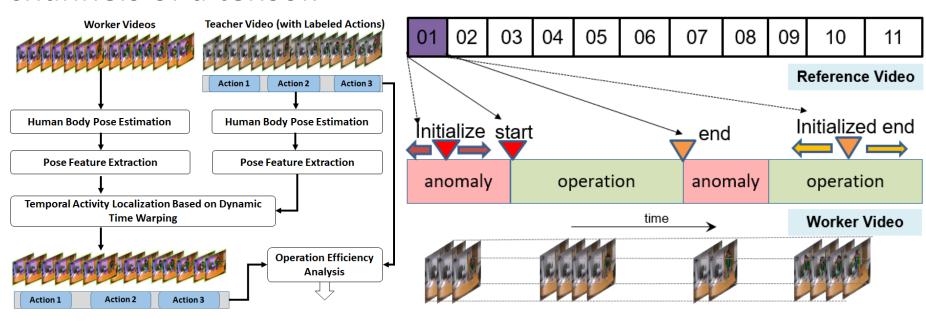


Worker Pose Tracking for Performance Evaluation

We aim to develop an automatic system to monitor and evaluate worker's efficiency for smart manufacturing based on human body pose tracking and temporal activity localization and segmentation.



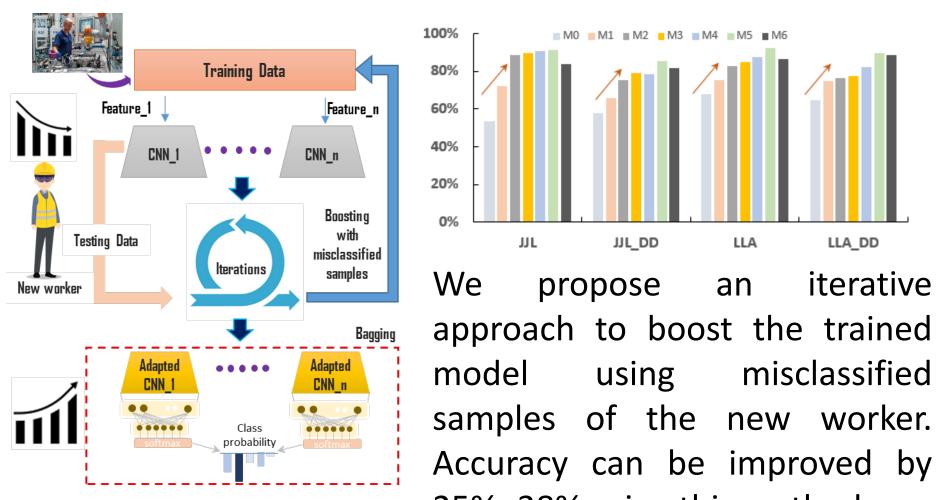
The overall framework of our proposed poseGAN for the human pose. It includes the following components: Generator(G), Discriminator (D), Feature Extractor (FE), and Pose Estimator (PE). M and N are the number of channels of a tensor.



Efficiency evaluation

Iteratively Improving Oncoming Worker Performance

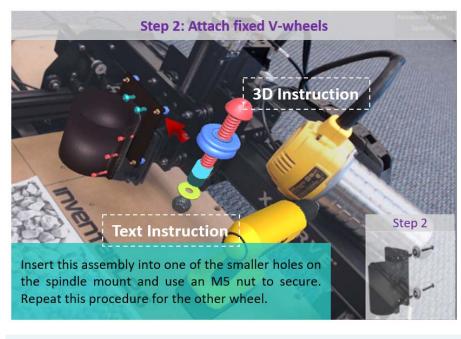
A trained AR model might perform poorly on new coming operators due to heterogeneous workforce behavior and anthropometric variation.



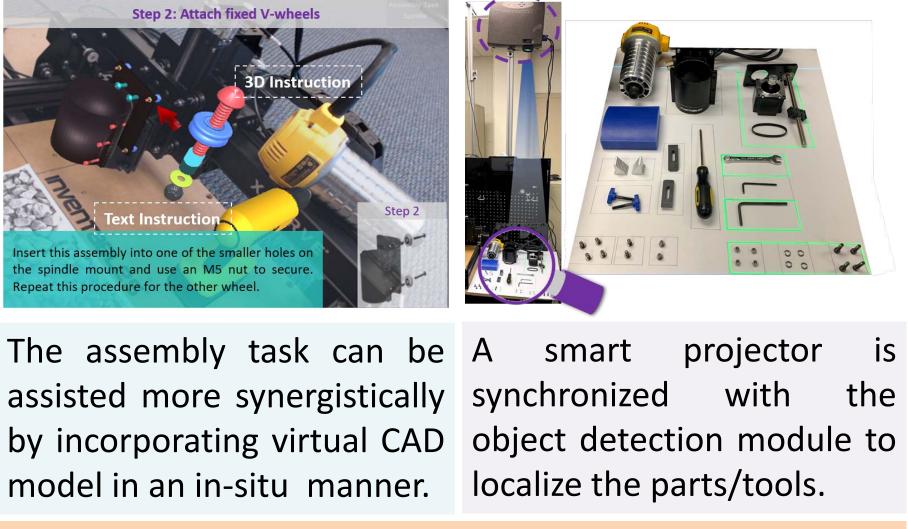
Temporal localization of actions

an iterative misclassified samples of the new worker. Accuracy can be improved by 25% -38% using this method.

3. Assistance

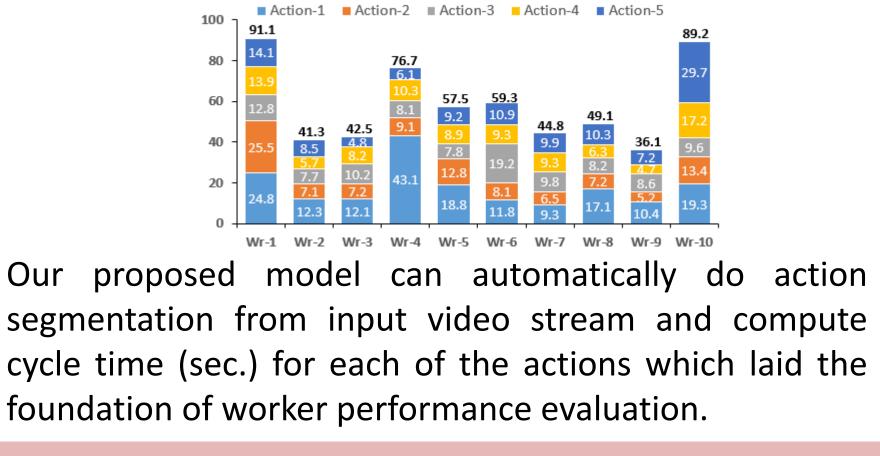


The assembly task can be assisted more synergistically synchronized model in an in-situ manner. localize the parts/tools.



4. Evaluation

Worker Performance Evaluation



foundation of worker performance evaluation.

Scientific Contribution

#1 To understand the hand activity, we propose a method for complex hand gesture recognition using CNN with multi-view augmentation and inference fusion. (1 journal paper and 1 [Best Paper Award] conference paper)

#2 To sense and understand the worker in a more comprehensive way, we propose a multi-modal approach for worker activity recognition using IMU signals and videos, where four different modalities are applied. (1 journal paper and 1 conference paper)

#3 To learn the importance of different sensors, we propose a novel attention-based approach to human activity recognition using multiple IMU sensors worn at different body locations. (1 journal paper)

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