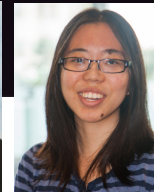
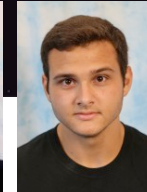


Design and Fabrication of Robot Hands for Dexterous Tasks



Robotics Institute
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Scientific Impact

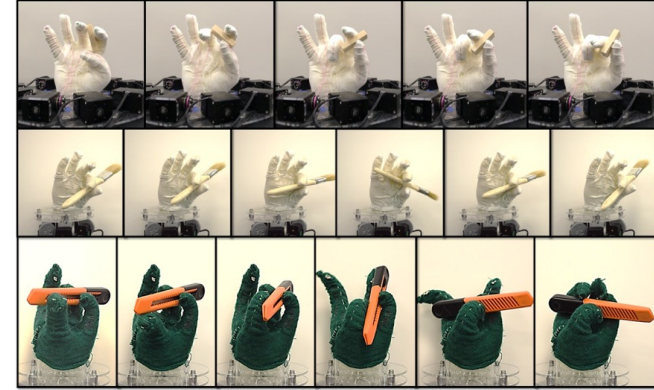
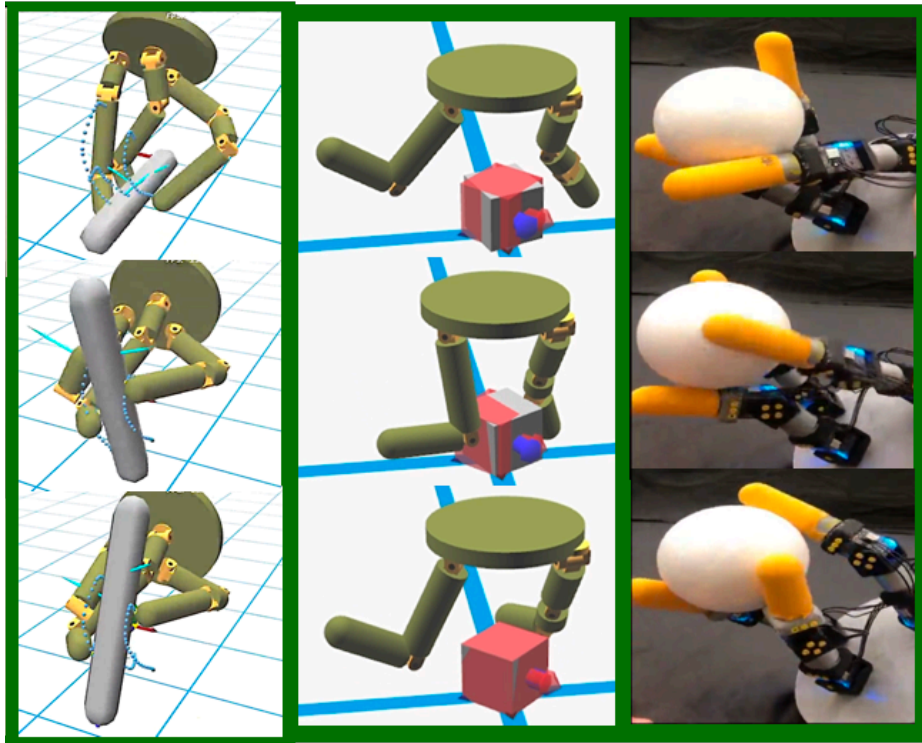
- Effective strategies for robot hand design

Challenge

- Design robot hands for dexterous manipulation

Solution

- Optimize for custom task set.
- Optimize mechanism, control, materials, joint limits, actuation, etc...
- Fully soft hands with whole-hand dexterity.



Broader Impact

- Improved understanding of human manipulation
- Applications for prosthetics
- Applications in agriculture