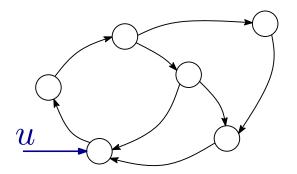
# Design of in-line controllers for continuously operating networks with structural uncertainty

Donatello Materassi

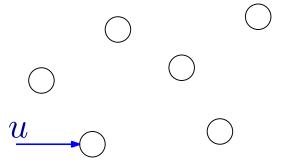
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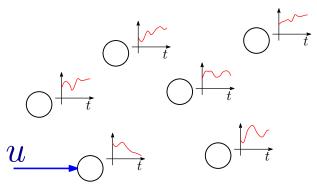
## The underlying network model is running



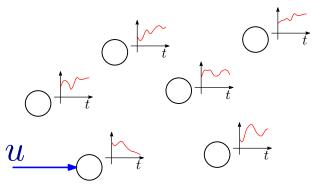
#### The structure is not known



#### Only non-invasive observations are available



## Design a control *u* meeting the specifications



Deep Brain Stimulation for Parkinson's disease



#### Automatic administration of anesthesia



