

Managing volatility of renewable energy sources in the future power grid

 Solar and wind energy are intermittent and uncontrollable, making balancing supply and demand challenging.

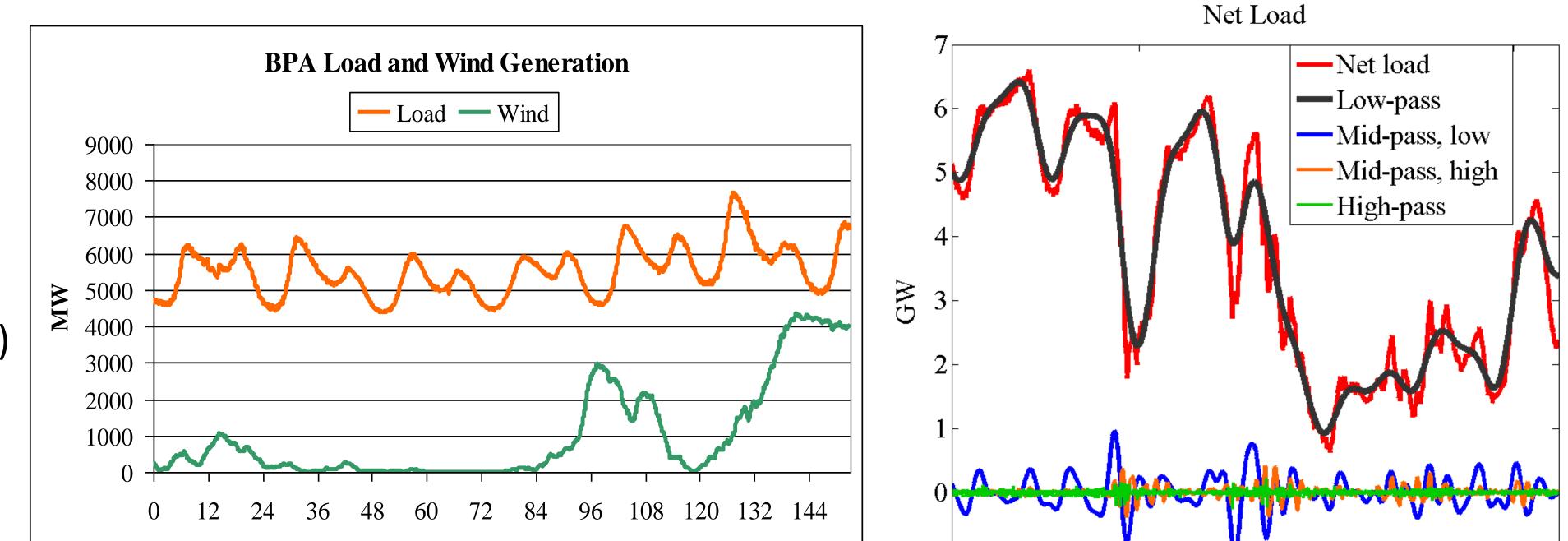
• Batteries can help, but they are expensive.

 Power demand of most loads is flexible and can be manipulated to provide "virtual energy storage" (VES).

Goal: Coordinate actions of many loads to provide robust and reliable VES

Concerns: • Computational complexity

- Decentralized decision-making (communication, privacy)
- Consumers' quality of service (QoS)
- Robustness to uncertainty (weather, human behavior, etc.)
- **Key Innovations:** Randomization to break the complexity barrier Global information from local measurements for coordination



Spectral decomposition for resource allocation

Time (hours)

100 150 Time (hours)

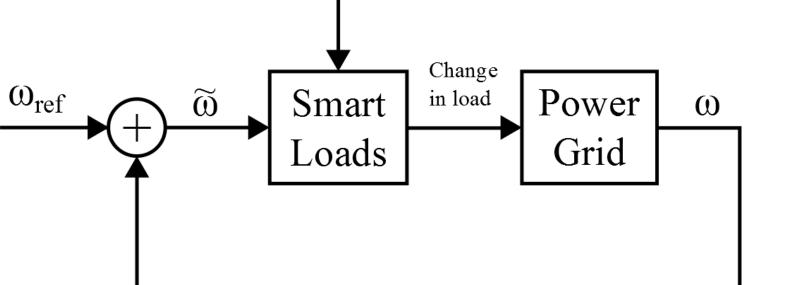
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Distributed coordination using local measurements (aggregators and commercial HVAC)	Distributed coordination using randomization (on/off loads)
dea: Restrict loads' control actions to specific frequency bands.Provides strict bounds on QoS.	 2 possible control commands for every load: on or off For 1 million loads: 2^{10^6} possible control commands AT EVERY INSTANT!
 Collectively, loads can negate fluctuations in net load. Load type can account for a different frequency ration of the repeating of t	Probabilities enforce QoS constraints $p^{\oplus}(k) :=$ Probability of switching from off to on $p^{\oplus}(k) :=$ Probability of switching from on to off

 $\mathbf{U} = \mathbf{U} =$

load-to-load communication?

Solution: Local feedback + predictions from BA.



Use local frequency measurements to scale disturbance prediction:

 $r_i[k] = \min\left\{ \max\left\{ \left| \frac{\hat{d}[k]^{(BA)}}{\hat{\vartheta}_i[k_-]} \right|, \underline{r} \right\}, \bar{r} \right\}$

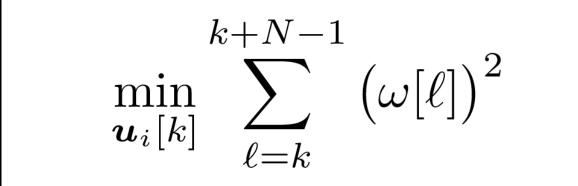
Allows loads to coordinate without communication!

 $\hat{\boldsymbol{d}}_{i}[k] \triangleq \rho_{i}[k] \hat{\boldsymbol{d}}^{(BA)}[k]$

 $\rho_i[k] = r_i[k]\rho_i[k-1]$

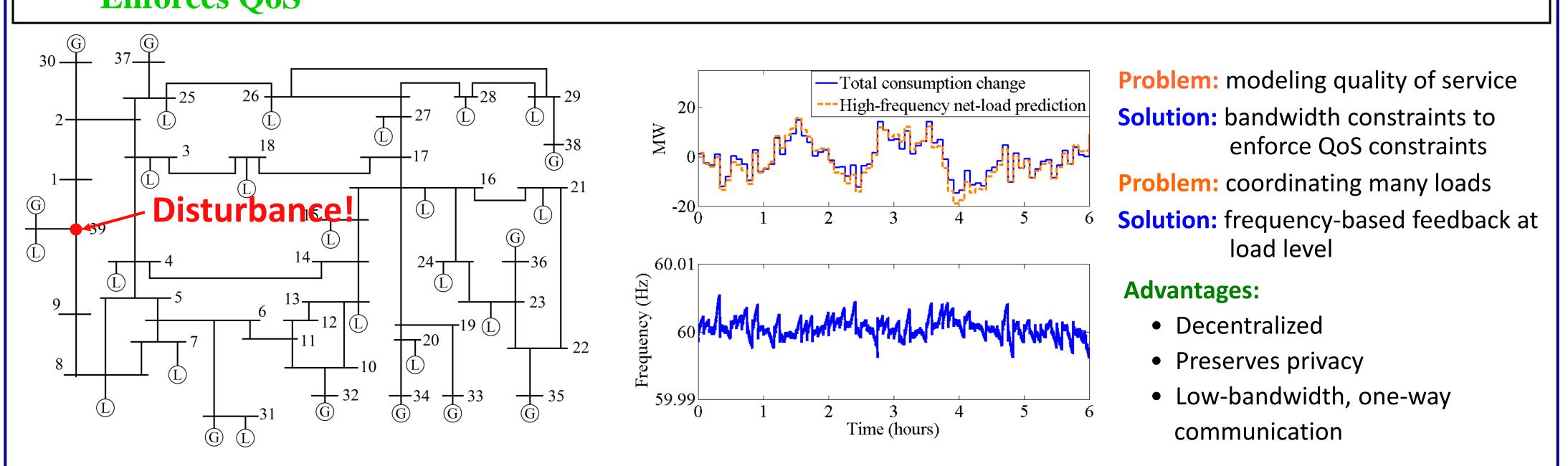
 $\hat{\vartheta}[k_{-}] = \frac{\tilde{\omega}[k]}{\tilde{\omega}[k]} - \hat{d}[k]$

BalDuR-DMPC



Subject to: $\omega[\ell] = g\left(u_i[\ell|k] + \hat{d}_i[\ell|k]\right)$ $u_i[\ell|k] \in \mathcal{U}_i$ $\left| \text{DFT}(\boldsymbol{u}_{i}[k]) \right| \leq \alpha_{i}[m], \quad 0 \leq m \leq 2N-1$



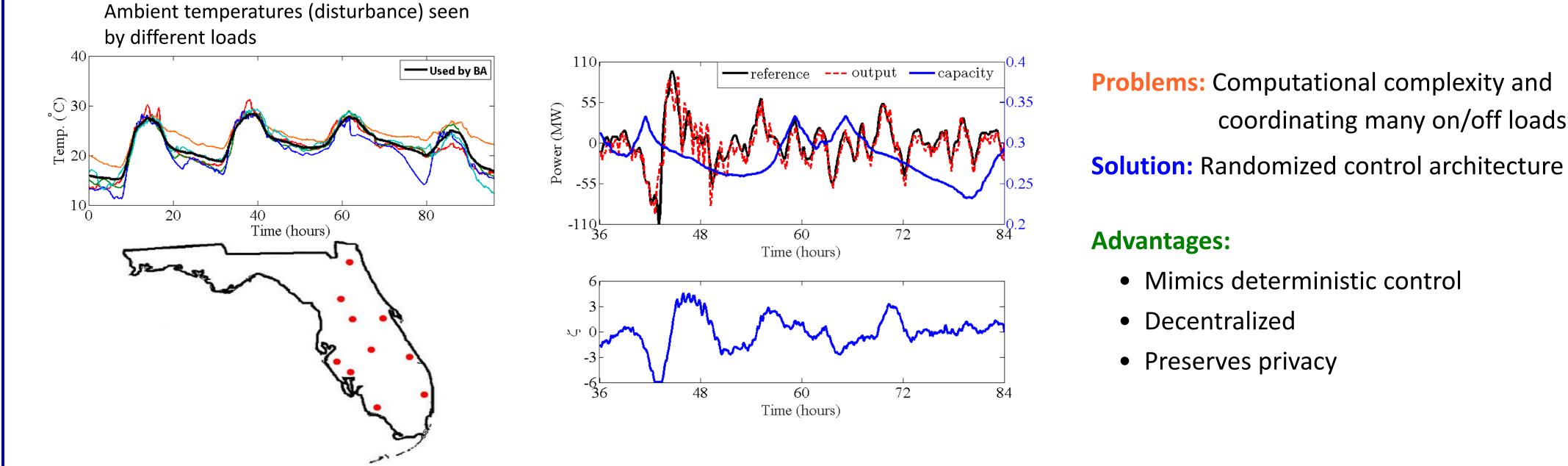


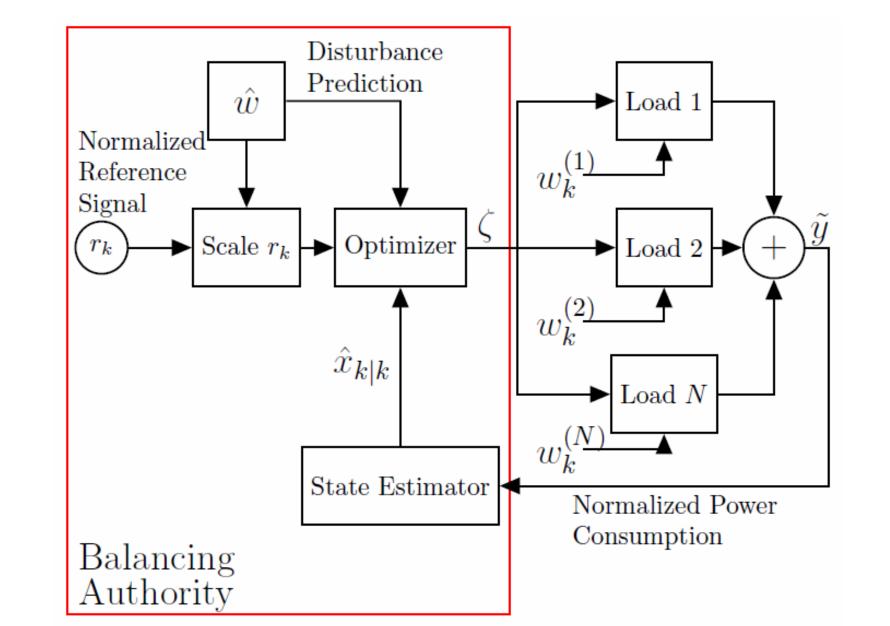
Define randomized local control law, parameterized by ζ : $R_{\zeta}(x, y^u) := R_0(x, y^u) \exp\left(\zeta \mathcal{U}(y^u) - \Lambda_{\zeta}(x)\right)$ $\mathcal{U}(y^u) = \begin{cases} 1, & y^u = \oplus \\ 0, & y^u = \Theta \end{cases}$

Linear Signal Dynamics Aggregate from power BA consumption

Design Architecture:

- Balancing authority (BA) sends signal ζ to the loads to adjust probabilities of turning on and off.
- Loads turn on and off randomly, accordingly.
- QoS constraints are maintained for each load.
- Aggregate power consumption tracks a desired reference.





coordinating many on/off loads

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