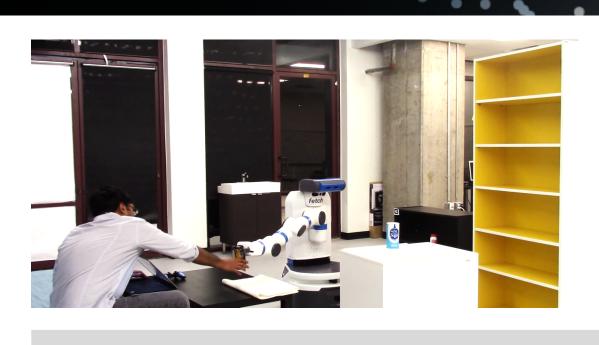
# **EAGER: Hierarchical Contrastive Explanations for Robot-Human Communication**

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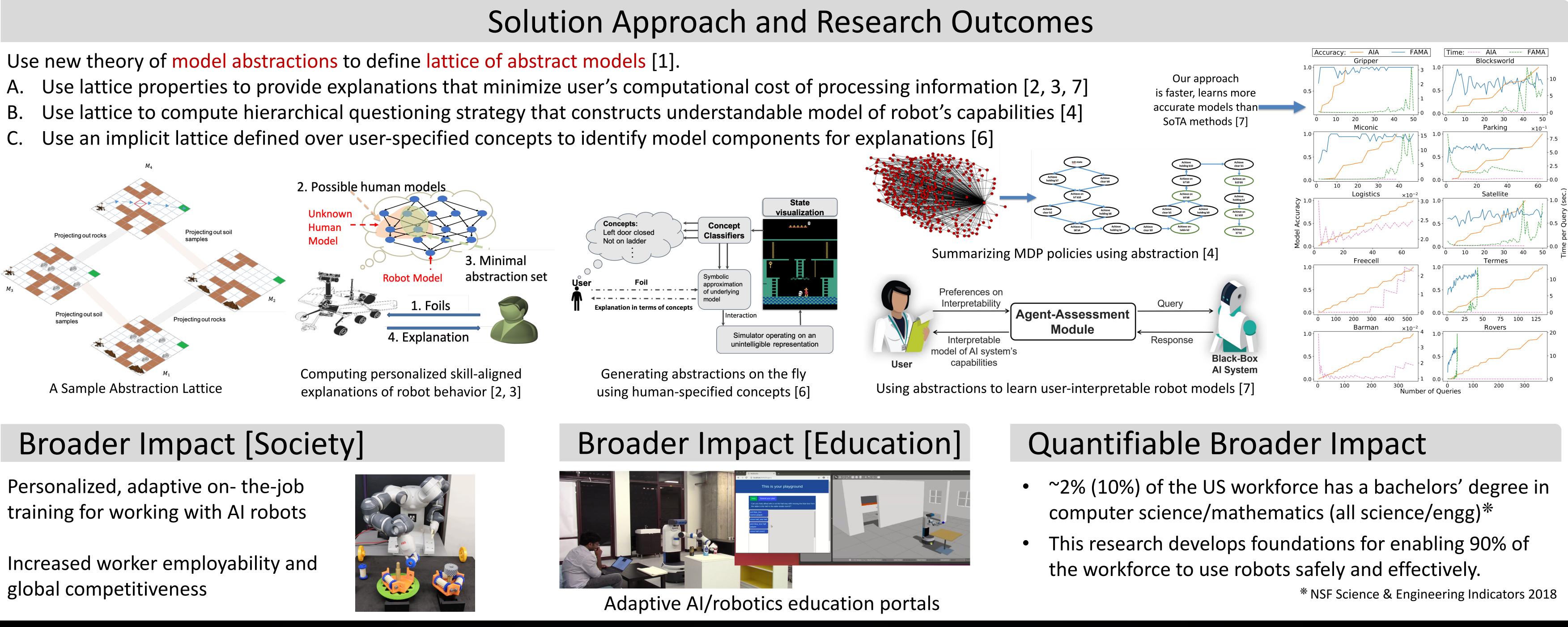


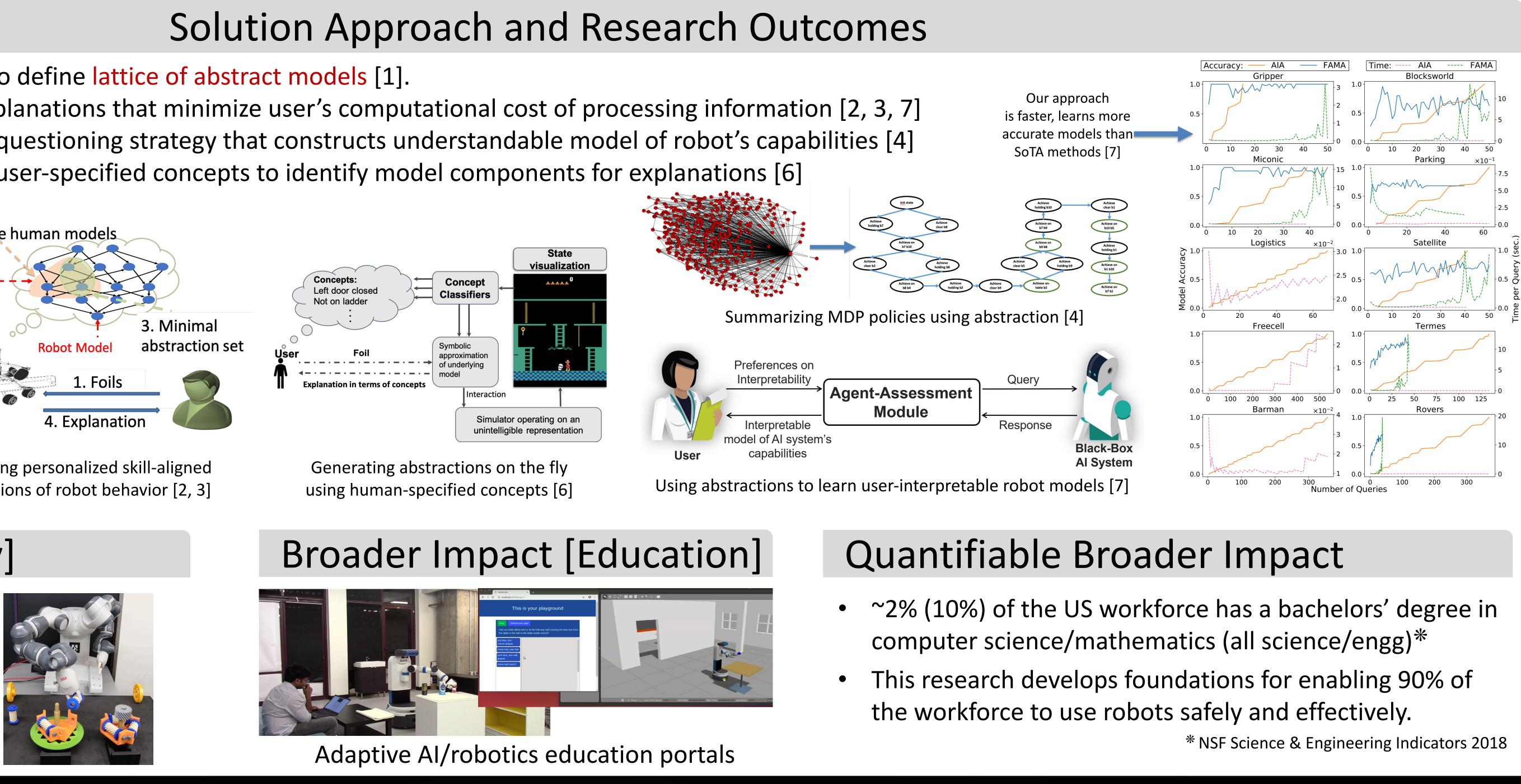
How would a non-Al/robotics expert determine what their robot can and can't do? Understand what it's doing and why? Reconfigure it for a desired objective?

## Key Challenges

- User needs to be able to ask the right questions to assess robot's capability for new tasks.
- Robot needs to be able to *explain* itself. Explanations need to minimize the computational cost of processing information.

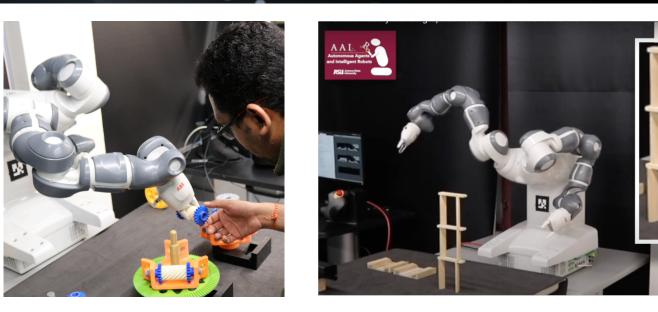
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1. Metaphysics of Planning Domain Descriptions. S Srivastava, S Russell, A Pinto. In Proc. AAAI, 2016. 2. Hierarchical Expertise Level Modeling for User-Specific Contrastive Explanations. S Sreedharan, S Srivastava, S Kambhampati. In Proc. IJCAI, 2018. 3. Why Can't You Do That HAL? Explaining Unsolvability of Planning Tasks. S Sreedharan, S Srivastava, D Smith, S Kambhampati. In Proc. IJCAI, 2019. 4. TLdR: Policy Summarization for Factored SSP Problems Using Temporal Abstractions. S Sreedharan, S Srivastava, S Kambhampati. In Proc. ICAPS, 2020. 5. Anytime Task and Motion Polices for Stochastic Environments. N Shah, K Kumar, P Kamojhalla, D K Vasudevan, S Srivastava. In Proc. ICRA 2020. 6. Bridging the Gap: Providing Post-Hoc Symbolic Explanations for Sequential Decision-Making Problems with Inscrutable Representations. S Sreedharan, U Soni, M Verma, S Srivastava, S Kambhampati. ICML HILL Workshop, 2020. 7. Asking the Right Questions: Learning Interpretable Action Models Through Query Answering. P Verma, S R Marpally, S Srivastava. In Proc. AAAI, 2021.



### Scientific Impact

Hierarchical explanations can be used to advance personalized training systems Query-based model estimation sheds new light on computing interpretable models for black-box, non-stationary cyber-physical systems and presents new algorithms for user-specific, personalized assessment of safe and assistive AI systems.

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