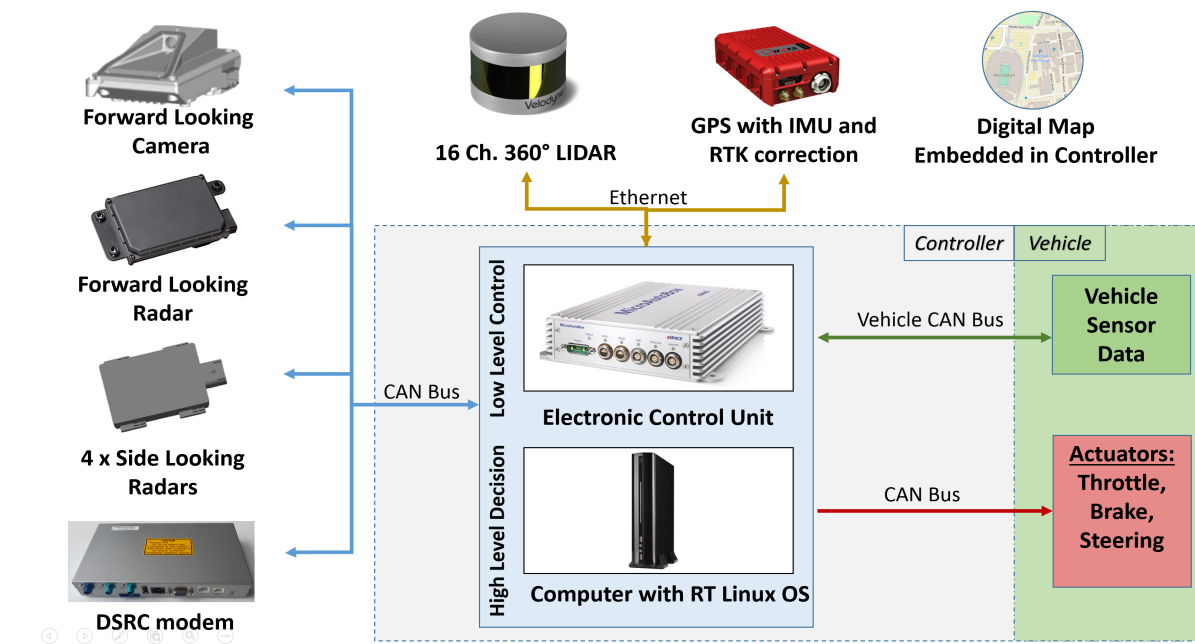




# UNIFY - Smart Shuttle

A Scalable and Replicable Architecture for Low Speed Automated Shuttles in Smart Cities  
 Pls: Prof. Levent Guvenc Prof. Bilin Aksun Guvenc Prof. Keith Redmill (The Ohio State University)



## Impact & Benefits

- The scalable and replicable nature of the Smart Shuttle approach allows results to be easily transferred and adapted to other vehicles, deployment sites and different cities.
- Full mobility solution for people who cannot easily commute to work due to the first-mile, last-mile problem.
- Expected reduction in accidents and traffic jams which will increase the safety and quality of life of those people who are affected by it.
- OSU campus proof-of-concept deployment site will be in an under-served area of campus that connects highly populated labs to the rest of the campus transportation network.



## Unified – Replicable – Scalable

- Unified architecture that can be implemented on different vehicles to make them autonomous.
- Replicable design solution that can be transferred from one vehicle to another.
- Scalable lateral and longitudinal controllers and automated driving tasks (path following, car following, collision avoidance) that can be used to control different types of autonomous vehicles.



Replicability

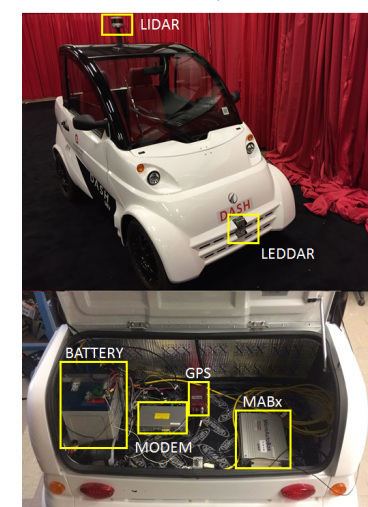
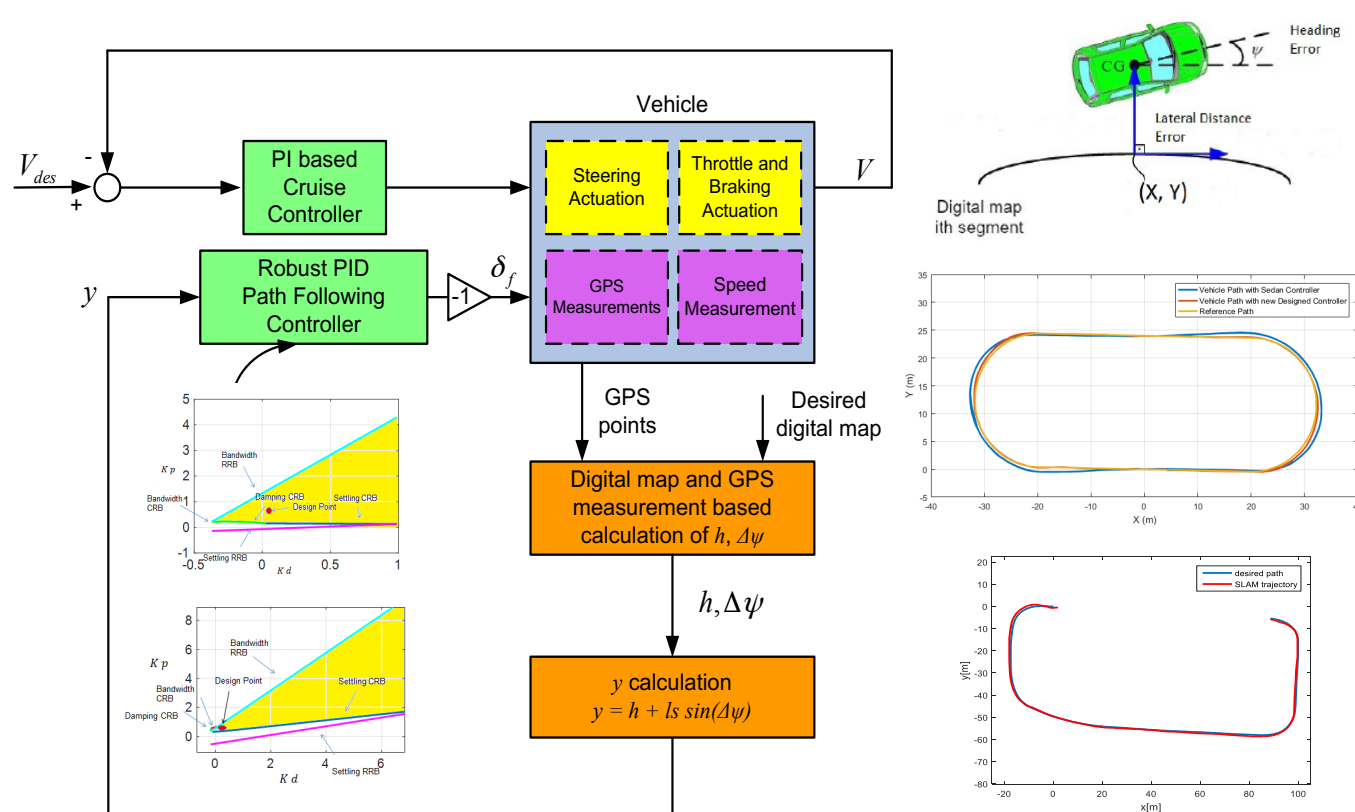


Scalability

Scalability

## Proof-of-Concept Deployment Sites

- Vehicles are first deployed in realistic CAV hardware-in-the-loop simulator (HiL).
- Smart Autonomous Shuttle (Dash) deployed successfully in private parking lot (above).
- Smart Autonomous Shuttle (Dash) will be deployed in OSU AV pilot test route (below).



Replicability



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