



# FRESCO: Fast, Resilient, and Cost-Optimal Co-Designs for Wide-Area Control of Power Systems

Aranya Chakraborty\*, Alexandra Duel-Hallen\*, Anuradha Annaswamy+, Alefiya Hussain\*\*

\*North Carolina State University, +Massachusetts Institute of Technology, and \*\*Information Sciences Institute at University of Southern California

NC STATE UNIVERSITY

Massachusetts Institute of Technology



Information Sciences Institute USC Viterbi School of Engineering

CPS PROJECT NUMBERS:-1544871, 1544751, 1544742

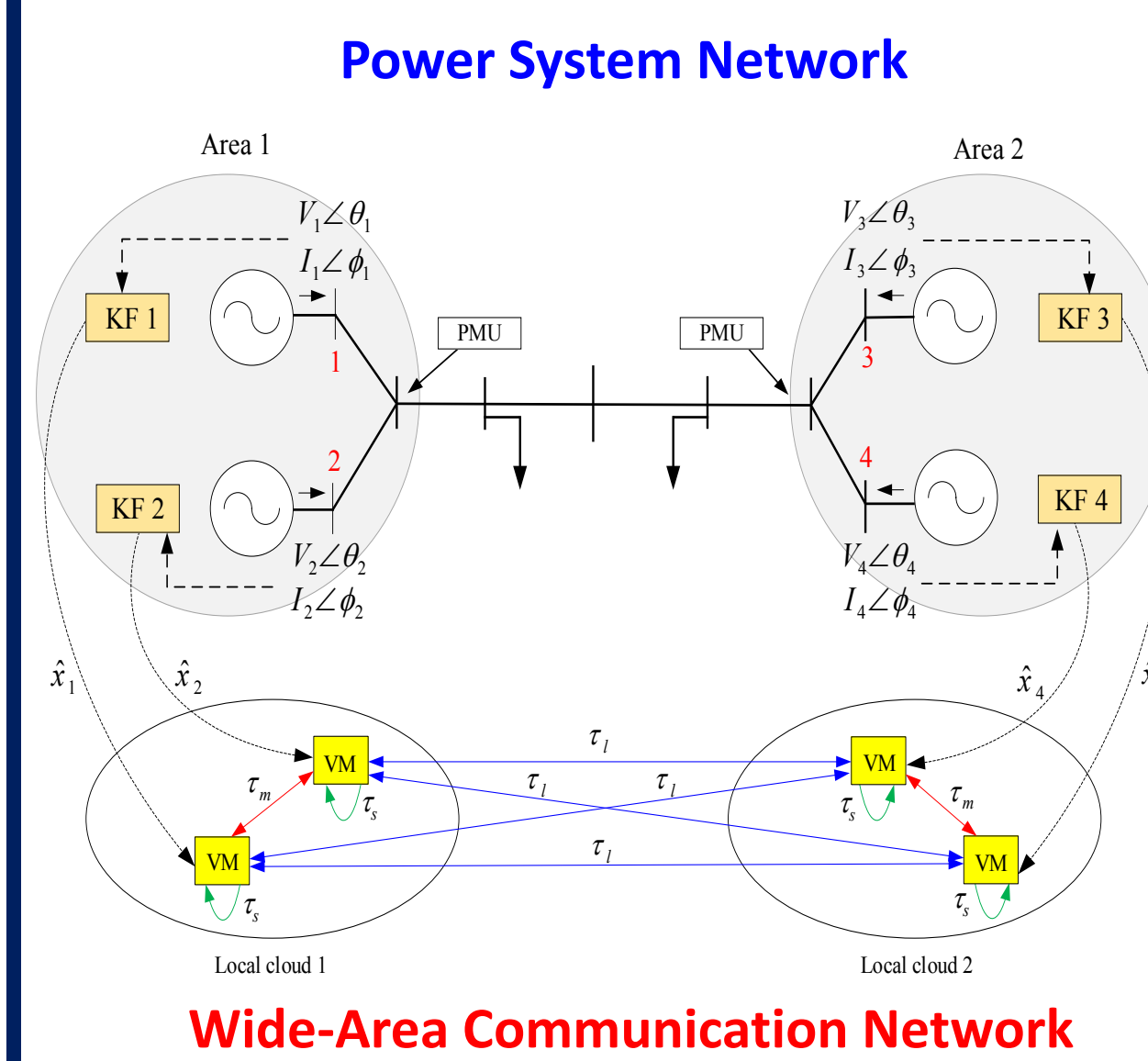
## Project Goal

To co-design communication, control, and decision-making algorithms for fast, resilient and cost-optimal wide-area control of power systems using massive volumes of Synchrophasor data

- **Inter-area oscillation damping** – output-feedback based MIMO control design for large power transmission systems to shape the closed-loop dynamic responses of power flows and frequencies using real-time Synchrophasor data
- **System-wide voltage control** – PMU-measurement based MIMO control design for coordinated setpoint control of voltages across large inter-ties using FACTS controllers (SVC, CSC, STATCOM)
- **Safe islanding** – use PMU data to continuously track *critical cutsets* of the network graph – i.e., minimum set of tie-lines lines carrying max sets of dynamic power flows

## Wide-Area Control

Coordination of multiple Phasor Measurement Units (PMUs) with multiple control actuators such as Power System Stabilizers (PSS) and FACTS devices to satisfy a global control goal in a distributed fashion over a secure communication network



### Research Challenges

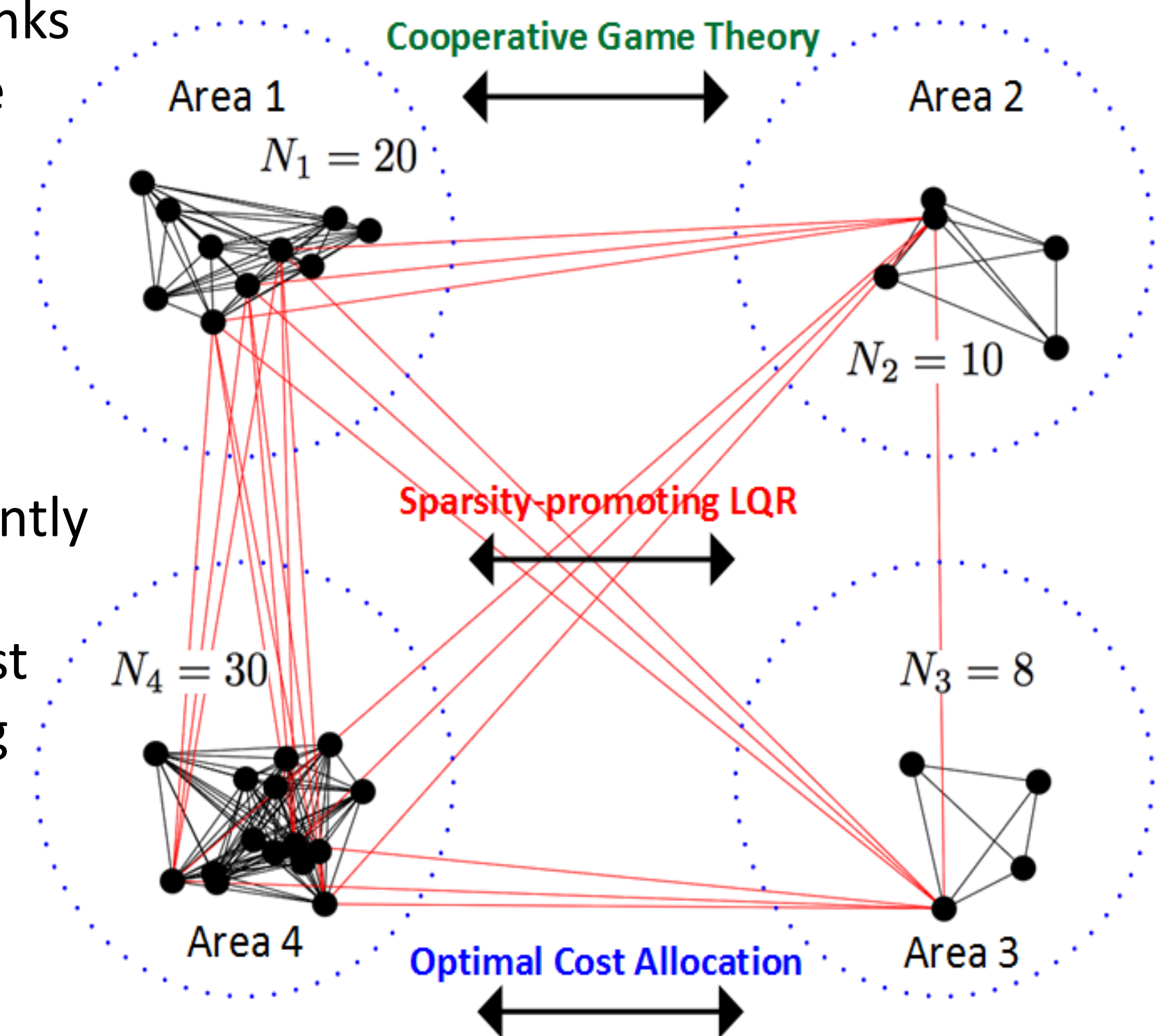
- **Time-scale for computation**  
Real-time computing  
Fast numerical algorithms
- **Communication constraints and threats**  
Multi-cast Routing  
Large inter-area delays  
Privacy of control gains  
DoS attacks
- **Control design**  
Ensure sparsity  
Accommodate delays  
Maintain privacy  
Use distributed computation  
Utilize output measurements

## Game Theory for Cost Effectiveness

The cost for *renting* bandwidth and channel links vary depending on the need for feedback. The main question is - how much is each company willing to pay off in sharing the network cost?

Our approach is to

- treat the utility companies as *players* in a cooperative network formation game to jointly minimize a global performance metric,
- determine the required communication cost and its fair allocation using Nash Bargaining Solution.
- extend the design to robust  $H_2/H_\infty$  implementation in the presence of model uncertainties

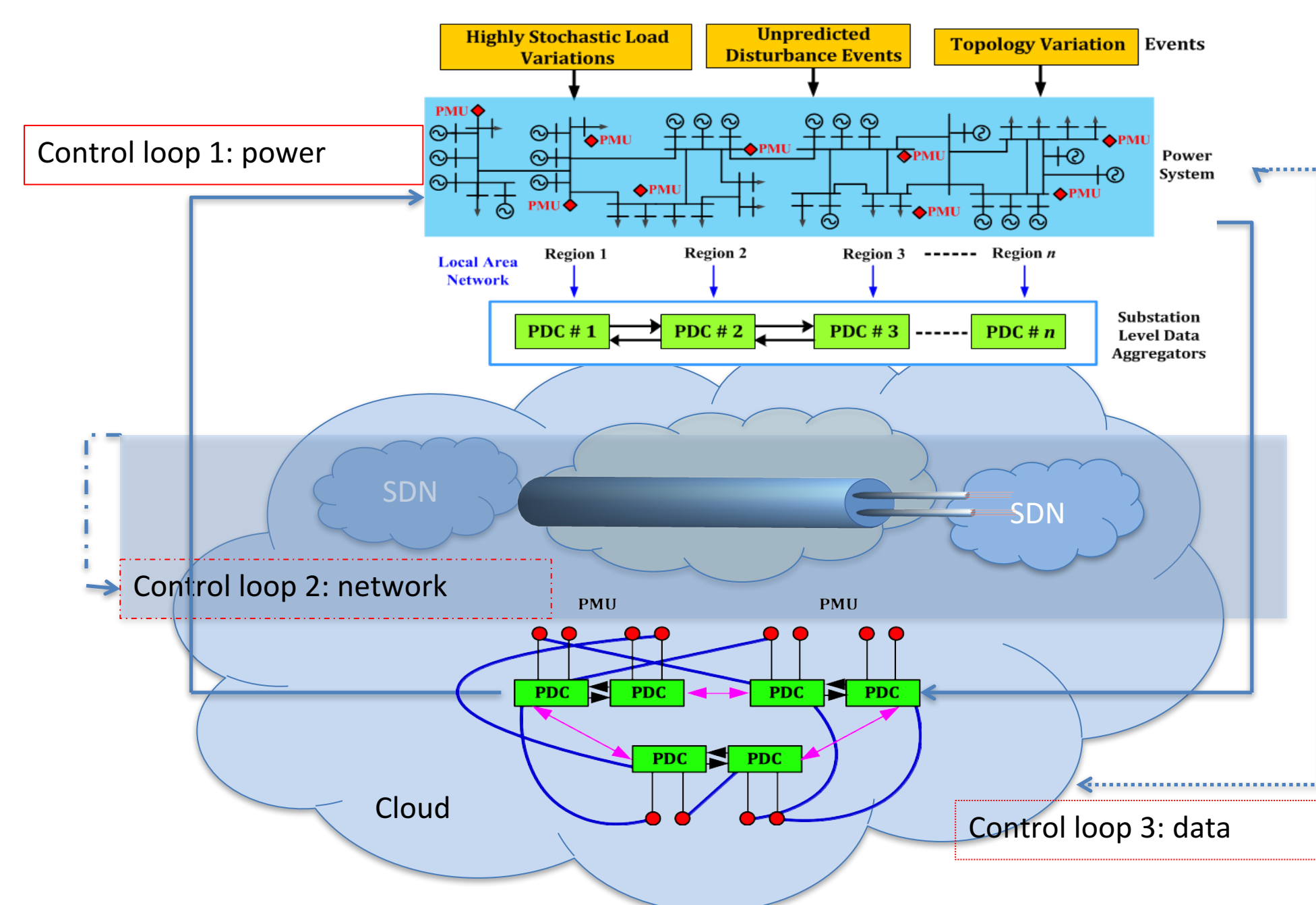


## Technical Approach

### Intellectual Merits:

1. Distributed power oscillation damping control
2. Distributed voltage control
3. Distributed middleware
5. Experimental verification using DETER security testbed

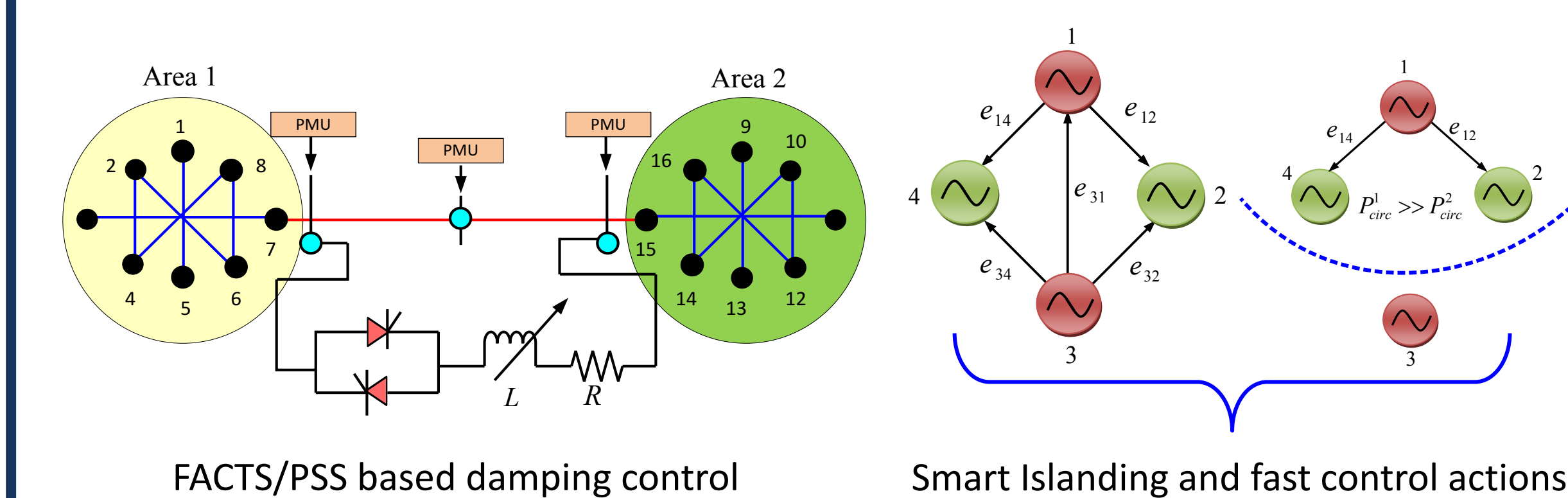
### Proposed Distributed Cyber-Physical Architecture for Wide-Area Control:



### Primary questions:

1. How to co-design distributed optimal controllers in sync with delay bounds of wide-area comm. networks
2. How to optimally allocate investment costs of communication infrastructure to different utility companies
3. How to make WAMS resilient to Denial-of-Service, data manipulation, and other forms of cyber attacks.

## New Control Algorithms



Consider the power system model with swing + excitation dynamics:

$$\begin{bmatrix} \Delta \dot{\delta} \\ M \Delta \dot{\omega} \\ \Delta \dot{E} \end{bmatrix} = \begin{bmatrix} 0 & I & 0 \\ -L(G) & -D & -P \\ K & 0 & J \end{bmatrix} \begin{bmatrix} \Delta \delta \\ \Delta \omega \\ \Delta E \end{bmatrix} + \begin{bmatrix} 0 \\ \text{col}_{i=1}^{(1)n}(\gamma_i) \\ \text{col}_{i=1}^{(1)n}(\rho_i) \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & I \\ I & 0 \end{bmatrix} \begin{bmatrix} \Delta P_m \\ \Delta E_F \end{bmatrix}$$

due to load

$$y = \text{col}_{i \in S}(\Delta V_i, \Delta \theta_i).$$

Choose  $m$  generators for implementing wide-area control via  $\Delta E_F$ . Let the measurements available for feedback for the  $j^{\text{th}}$  controller be  $y_j(t)$ . Let  $Y(t, \tau) = [y(t - \tau_j)]$  where  $\tau_j$  is signal transmission delay. Let  $\tau$  be the vector of all such delays.

Define a performance metric  $\mathcal{J}$  to quantify the closed-loop damping of the slow eigenvalues of  $A$ . Let  $\mathcal{P}$  denote the set of all possible models resulting from parameter/structural variations in the system. Design an output-feedback dynamic controller  $F(Y(t, \tau))$  that solves:

$$\min_{\mathcal{F}} \max_{\mathcal{P}} \mathcal{J}$$

### Potential approaches:

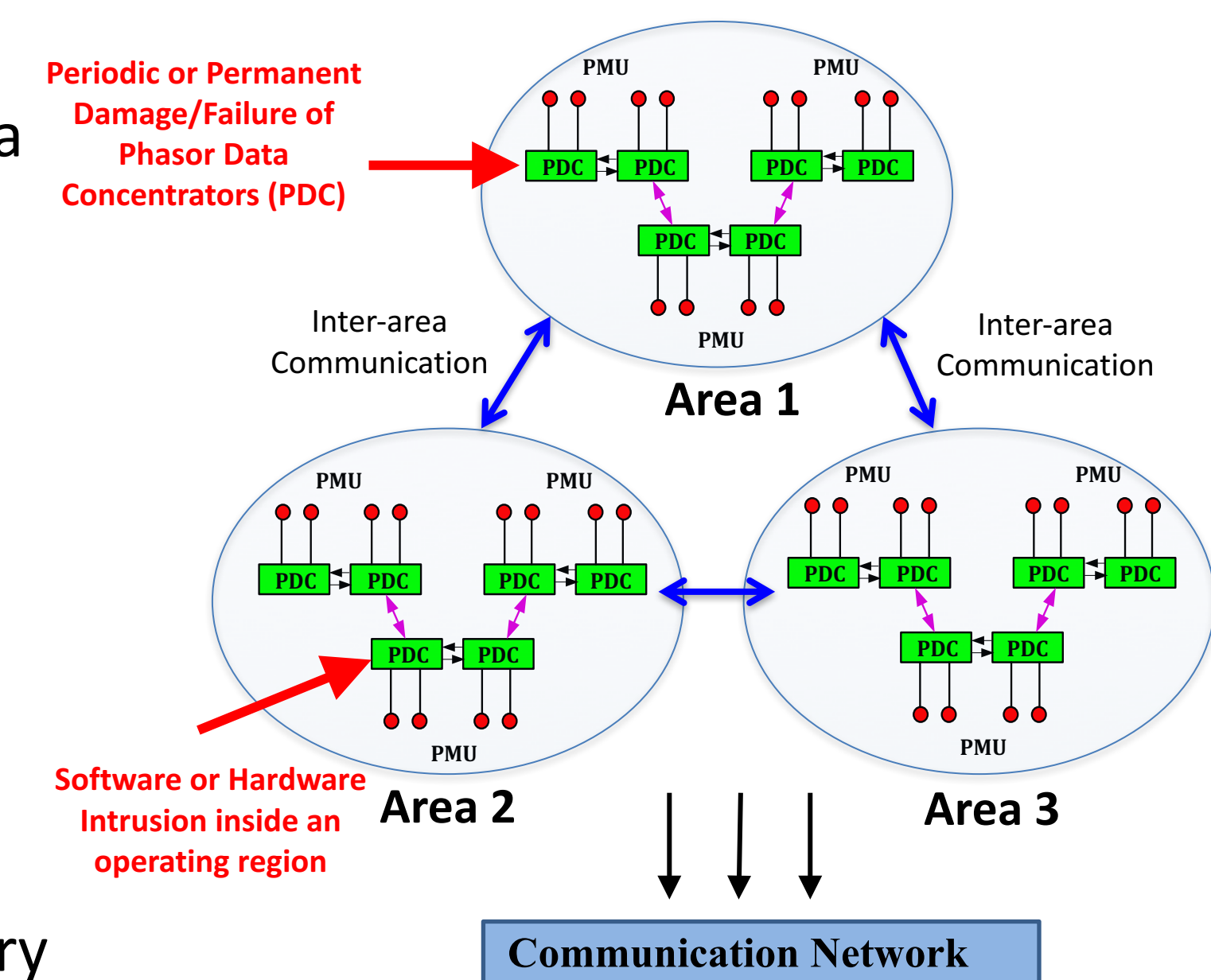
1. Delay-aware and sparsity-constrained optimal control designs
2. Distributed MPC
3. Graph-theoretic control designs for shaping eigenvalues and eigenvectors (convex optimization)

## Cyber-Security of Wide-Area Control

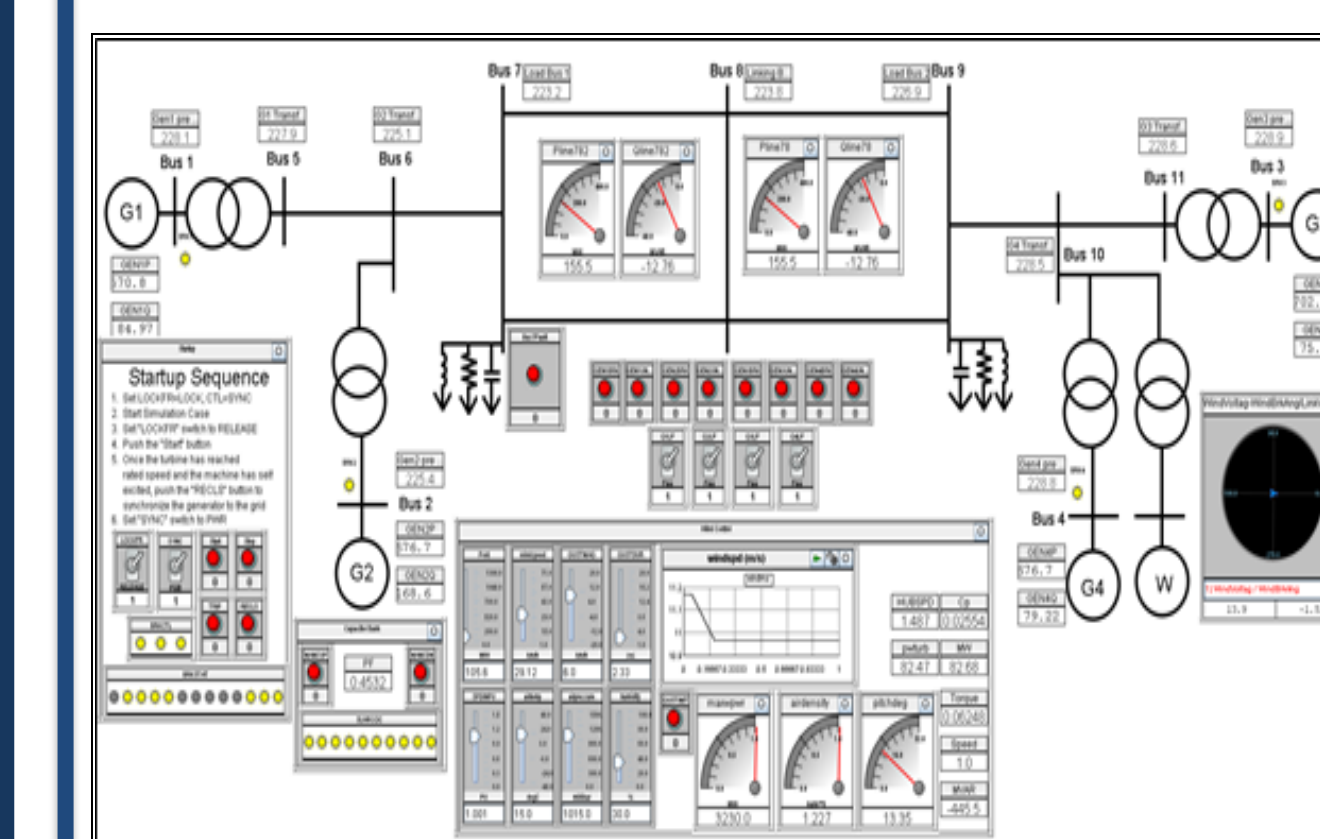
Develop security solutions that operate efficiently under different real-world constraints of wide-area communication, and that cyber-security defense design has to be done strategically with an understanding of economic constraints.

### Proposed approaches:

1. Threat Modeling
2. Enumerating the Attack Space from PMU data and Controller Signals
3. Intrusion Resilience via Response Graphs
4. Allocating Resilience Resources via Game Theory



## Experimental Testbed



- Participated in Smart America Challenge 2014 Initiative of NIST and US White House
- Federated *DETER Cyber-Security Testbed*
- Multi-vendor PMU-based hardware-in-loop simulation testbed at NCSU and DETERLab at Univ. of Southern California to showcase resiliency of distributed wide-area control

## Broader Impacts

- Undergraduate, K-12 and minority education via Science House and FREEDM ERC programs at NC State
- Women's education program at MIT and USC
- Undergraduate summer internship at Information Science Institute at USC
- Industry collaborations with power utilities and software vendors via TTP