

Formal Methods at Scale Formal + Informal

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- One niche in aerospace is formal analysis of specific models and requirements codified into industry-wide standards
 - When possible, design models to be reusable for similar applications (open source release)
- Three recent examples:
 - SAE AS 6802: Time-Triggered Ethernet
 - Formalization of fault-tolerance properties of a safety-critical data network
 - (SC 228) RTCA DO-365: Minimum Operational Performance Standards [MOPS] for Detect and Avoid (DAA) Systems
 - Formalization of well-clear requirements and DAA alerting logic
 - (SC 186) RTCA DO-260C (draft): MOPS for ADS-B
 - Formalization of requirements and reference implementation of Compact Position Reporting algorithm

Time-Triggered Ethernet



- Fault-tolerant data network for safety-critical applications
- Formal modeling and analysis using SAL and PVS during development of AS 6802 standard (by SRI, TTTech, & Honeywell)
- Analysis using PVS helped identify and fix a design defect. The fix was incorporated into the published standard:
 - B. Dutertre, A. Easwaran, B. Hall, and W. Steiner, <u>Model-Based</u> <u>Analysis of Timed-Triggered Ethernet</u>, presented at the 31st Digital Avionics Systems Conference (DASC), October 2012.

Detect and Avoid Alerting Logic For Unmanned Systems (DAIDALUS)



- Reference implementation of NASA's **detect and avoid** concept for the integration of **Unmanned Aircraft Systems** into civil airspace (RTCA DO 365).
- Formally verified core algorithms that:
 - Determine the current pairwise well-clear status (Detection Logic).
 - Compute maneuver guidance to maintain or regain well-clear status (Maneuver Guidance Logic).
 - Determine alert type (Alerting Logic).
- DAIDALUS core algorithms have been implemented as an Application Programming Interface (API) library in Java and C++ (≈ 44k lines of code).
- DAIDALUS API provides a highly configurable interface:
 - Aircraft performance limits (acceleration, turn rate, etc.)
 - Wind information (simple wind-field model)
 - Alerting and guidance thresholds
- Code is released under NASA Open Source Agreement: http://github.com/nasa/wellclear



Compact Position Reporting – ADS-B Positioning







CPR divides the globe into "zones," and transmits only the target's position within the zone. The receiver has to determine the correct zone for proper decoding.

- CPR is used to save message space in ADS-B position messages
- Formal analysis led to tightening of decoding requirements, and simplified calculations.
- Spurred development of a PRECiSA, a tool for formal analysis of floating point (IEEE-754 spec) programs
- Formally verified implementations in floating point (double) and fixed point (single).
- Changes from formal analysis and verified implementation to be in revision C of DO-260 (ABS-B MOPS)

https://shemesh.larc.nasa.gov/fm/CPR/ https://shemesh.larc.nasa.gov/fm/PRECiSA/



Visualization of loose requirement for decoding. Target is within stated distance threshold, but decodes incorrectly

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On (formal) models ...

- "Essentially, all models are wrong, but some are useful"
 - George Box





Formal or Informal models?



Benefits

- Explore system behavior earlier in lifecycle
- Ability to verify properties that cannot be effectively demonstrated by test
 - Airborne separation
 - Robust partitioning for Integrated Modular Avionics
 - No memory leaks, buffer overflows, etc.

Risks

- Invalid assumptions
- Unstated assumptions
- Tendency to conflate model with reality
- Maintaining consistency between multiple models (with different underlying abstractions)
- Incompatibility between models
 - Especially design models vs. failure models

. . .

Representative Avionics Incidents



- Ariane 501 4 June 1996; Software defect in initialization routine for the inertial reference unit resulted in shutdown of both IRU and subsequent loss of rocket 37 seconds into launch
- B777 Malaysia Airlines Flight 124 1 August 2005; Latent software defect in ADIRU startup routine forgot prior failure of an accelerometer; second failed accelerometer resulted in incorrect data output from ADIRU to other critical systems (ADIRU was supposed to fail silent in this case).
- F-22 International Date Line February 2007; multiple softwarerelated systems failures when crossing the 180th meridian; failures resulted in simultaneous loss of navigation and communication; clear weather allowed squadron to follow tankers back to Hawaii.

Common to these incidents is presence of a software defect coupled with error propagation affecting critical functions unrelated to the software failure..







First Picture of a Byzantine Fault?

Honeywell

At 12:12 GMT 13 May 2008, a NASA Space Shuttle was loading hypergolic fuel for mission STS-124 when a 3-1 split of its four control computers occurred. Three seconds later, the split became 2-1-1. During troubleshooting, the remaining two computers disagreed (1-1-1-1 split). *Complete system disagreement.* But, none of the computers or their intercommunications were faulty! The *single fault** was in a box (MDM FA2) that sends messages to the 4 computers via a multi-drop data bus that is similar to the MIL STD 1553 data bus. This fault was a simple crack (fissure) through a diode in the data link interface.



* the Byzantine Assassin

From https://c3.nasa.gov/dashlink/static/media/other/ObservedFailures4.html

Questions?





Downloaded from http://xkcd.com/246/

Backup Slides



An assumption will remain valid only until you come to depend on it^{*}.





* http://www.ece.mtu.edu/faculty/rmkieckh/Kieckhafer-top-ten.htm (version 11.1; law 4.2)

On Standards





Downloaded from https://xkcd.com/927/



Design Verification vs. Certification

Design Verification

- Focus on functional correctness, desired properties, and performance
- Emphasis on average case behavior (e.g., for performance)
- Intended interactions between components & environment
 - Presumption that the only interaction is through defined interfaces

Certification

- Focus on non-functional requirements – Safety, Security, etc.
- Emphasis on worst-case behavior
- Preclude adverse interaction between components & environment
 - In addition to failure propagation through defined interfaces, must also consider "out-of-band" failure modes

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Assumed importance order

- Assumed/known fault hypothesis violated

exhaustion of resources (known fault hypothesis)

- Single point of failure

- unknown fault hypothesis
- forgotten failure mode
- underestimated probability of occurrence
- Fault propagation = domino effect (fault containment)

Real occurrence frequency order

- Chain or domino effect (missing fault containment)

- E.g. TTP membership; shown to be a fault propagation path [Ademaj, Sivencrona]
- Single point of failure (unknown fault hypothesis)
 - E.g. quad-redundant control system (termination of bus)[2003]
- Exhaustion of resources (known fault hypothesis)