

What's the Problem?

Participatory Sensing is a promising domain; e.g. Smartphone-mounted bomb detection sensors distributed to crowds can passively provide wide coverage

Anyone can Join \Rightarrow Vulnerable to **disinformation**

- Adversary can inject imitant forgeries (Sybils) into network
- Sybil clusters can easily overpower local decisions and give adversary unlimited leverage from afar.

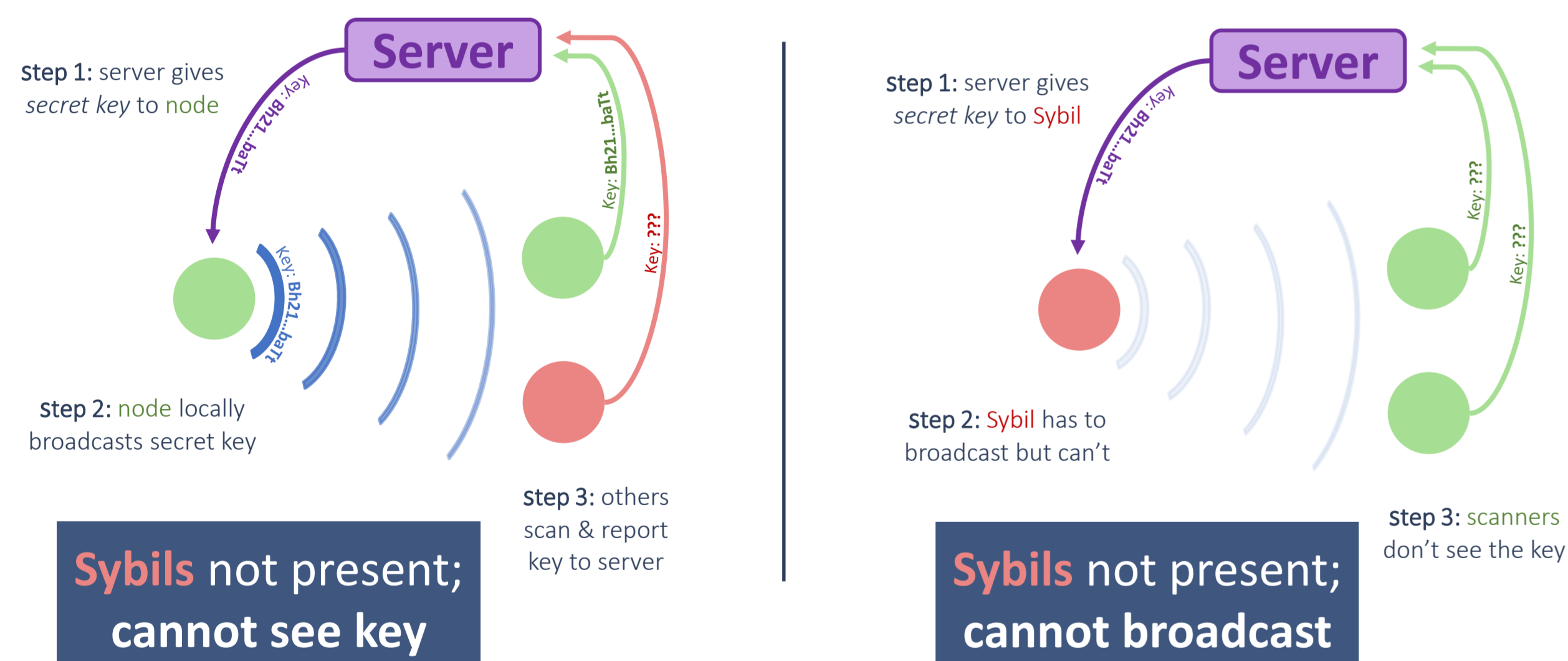


A **bomb**, **honest nodes**, and **Sybils** are shown. The Sybil cluster can claim to see **no bomb** and overpower local honest data, which would be deemed a false positive.

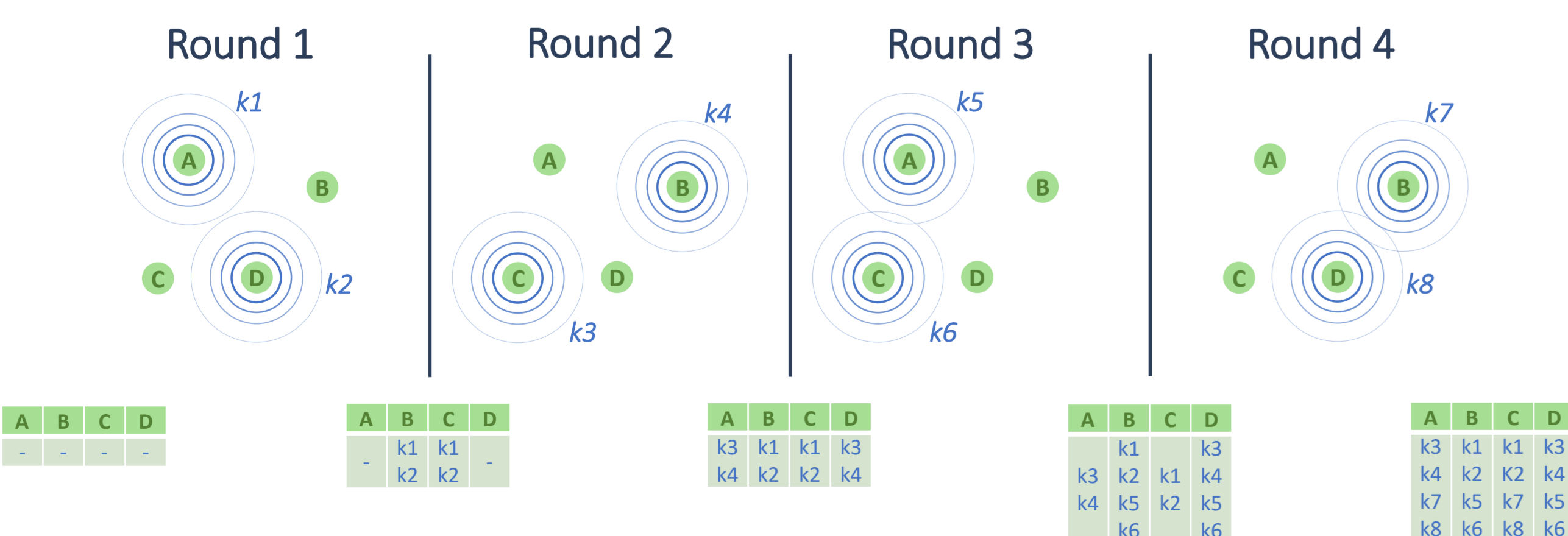
Sybils must be detected and ignored.

Key Idea

- Force nodes to communicate locally: Sybils will be helpless!



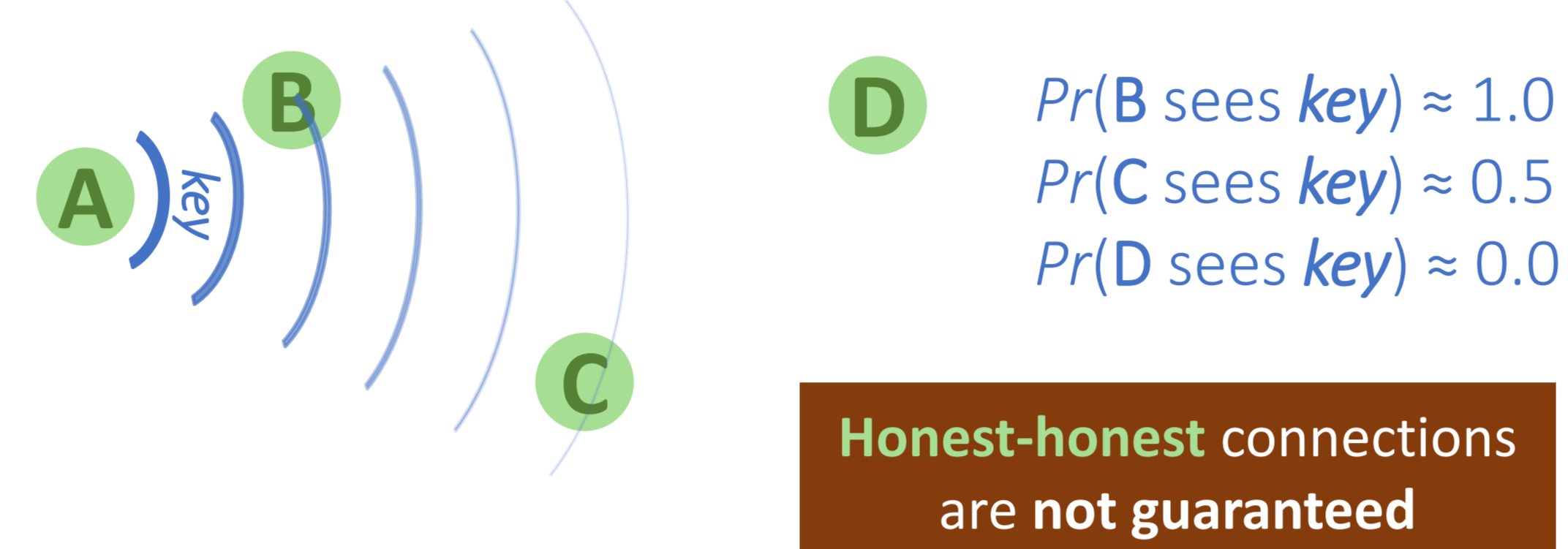
- *No nodes are trusted*, so all nodes forced to communicate with each other in both directions; **all directed pairs formed**. Done in **logarithmic time** in discretized rounds.



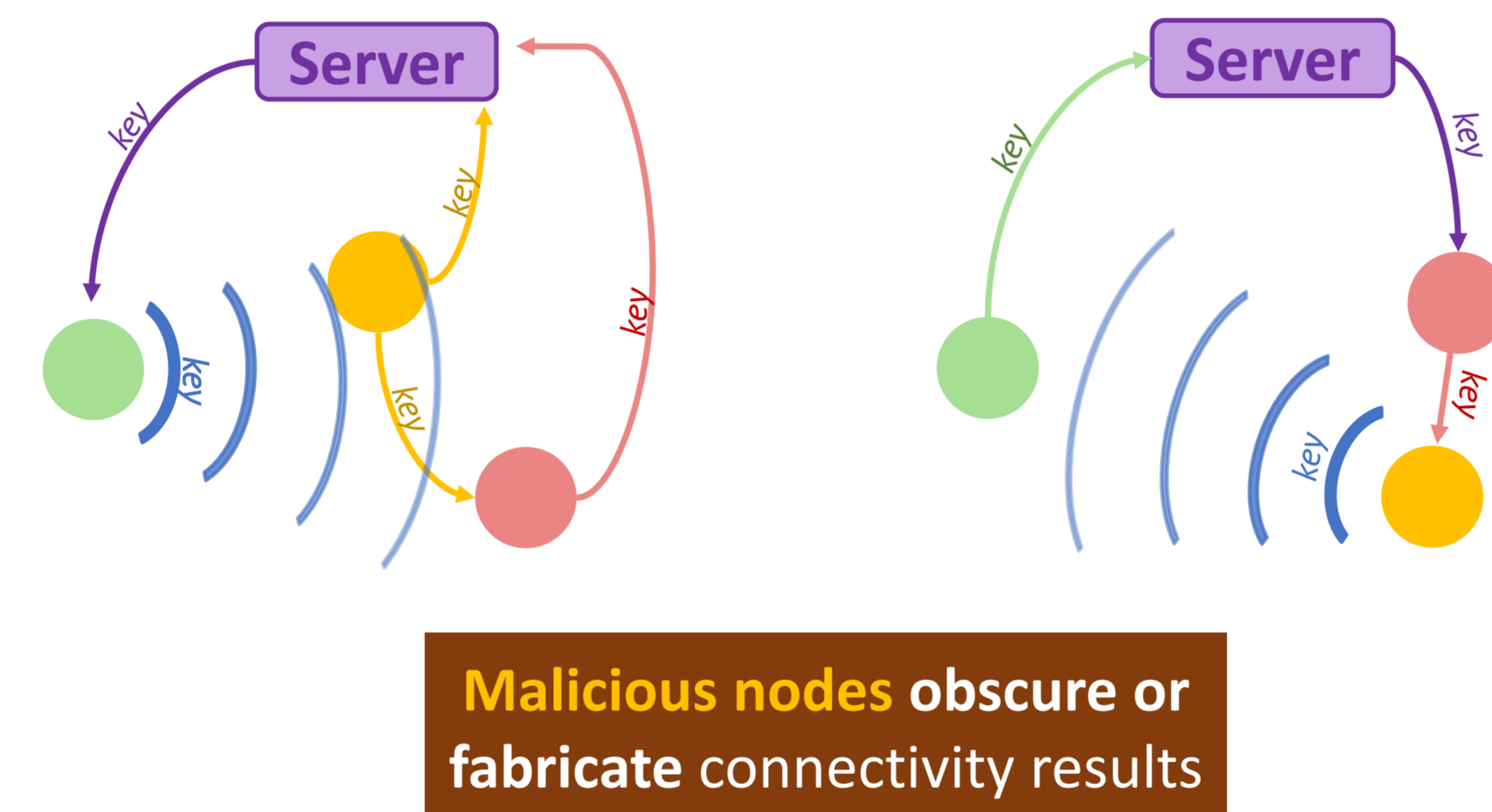
All directed pairs (and possibly more) made in $2\lceil \log_2(N) \rceil$ rounds

Challenges

- 1) Connectivity is **uncertain**, and a function of distance

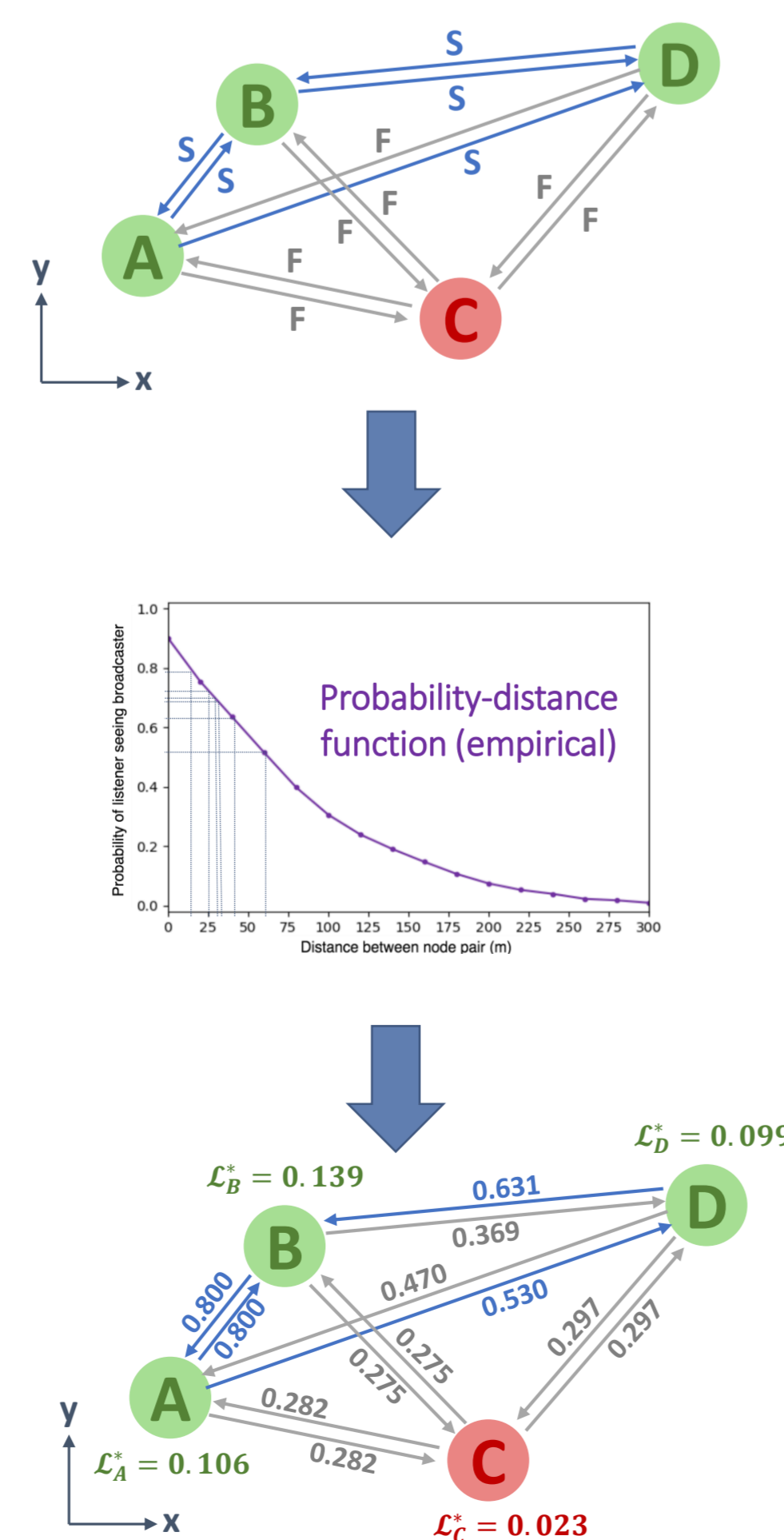


- 2) Adversary may have **malicious nodes** (physical agents on-site) who may collude and pass keys they hear to **Sybils** [left]
- 3) **Malicious nodes** may also **broadcast on behalf of Sybils** [right]



Probabilistic Proximity Graphs

- After the local communication algorithm, all connections—both successful and failed—are encoded as directed edges with initial weights $w \in \{S, F\}$ (source = listener)
- Weights are then transformed to probabilities with $w \in (0,1)$, based on pairwise distances and a **probability-distance function**



- For every node i , all incoming edge likelihoods are multiplied to yield **total likelihood value \mathcal{L}_i^*** for observed combination of edge outcomes
- **Sybils**, even with malicious node support, obtain **low \mathcal{L}_i^*** values and can be detected
- However, **scale is relative** and depends on node quantities and positions

\therefore Find distribution of \mathcal{L}_i values and test the extremeness of \mathcal{L}_i^*

Obtaining \mathcal{L}_i Distribution

- For every edge e with $P(e = S) = p_e$, define the random variable:

$$X_e = \begin{cases} \log(p_e) & w.p. p_e \\ \log(1 - p_e) & w.p. 1 - p_e \end{cases}$$

- Can examine **all combinations of $X_{e \in in(i)}$ values** to find \mathcal{L}_i directly for node i with incoming edges $in(i)$, but this is **exponential**

- We use **linear time Lyapunov's CLT** to get:

$$\sum X_e \sim \mathcal{N}$$

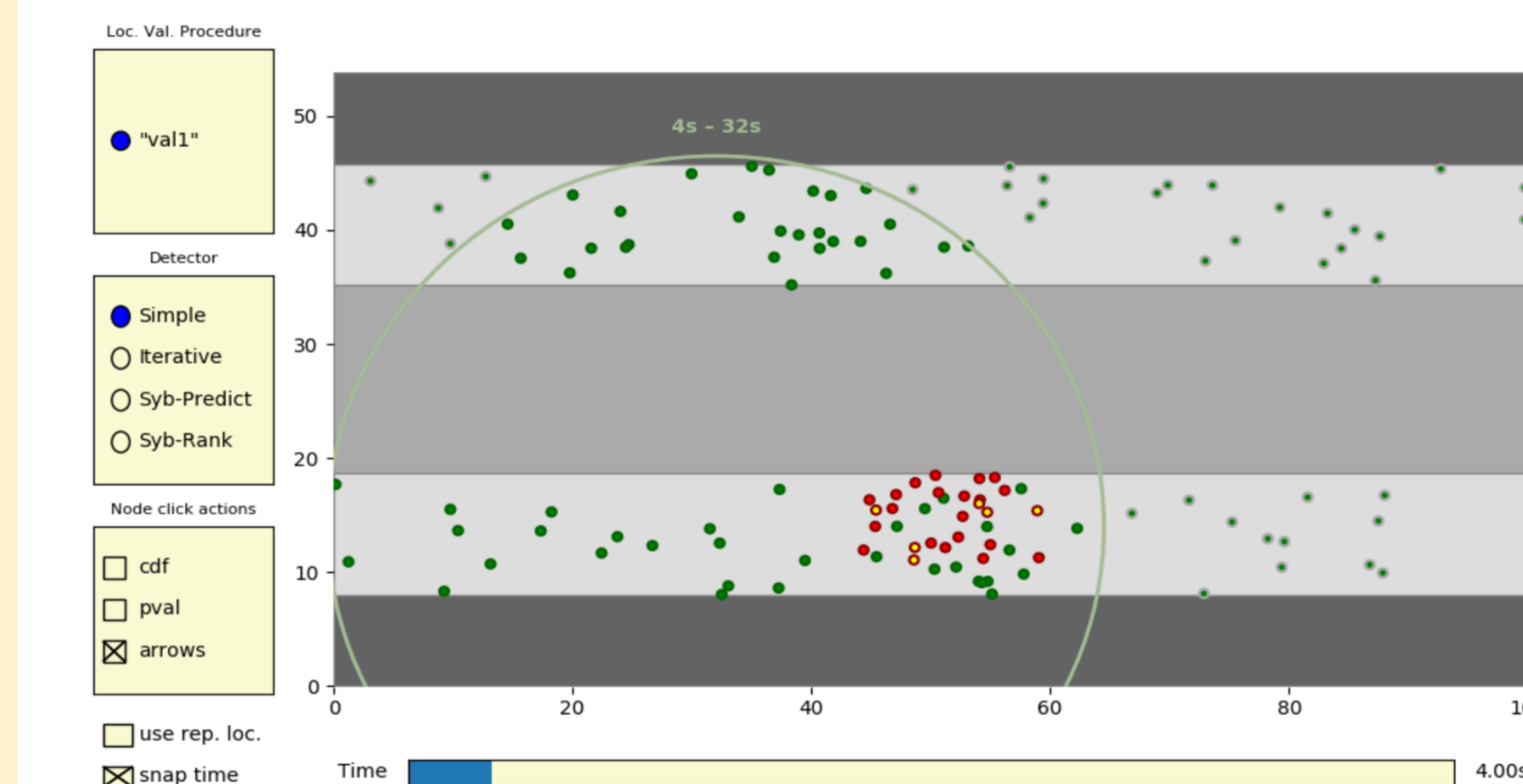
Detecting Sybils

- Choose threshold τ (default $\tau \approx 10^{-6}$)
- Nodes with $P(\mathcal{L}_i < \mathcal{L}_i^*) < \tau$ are **candidates**
- Now, repeat:
 - 1) **worst candidate** is a **Sybil**
 - 2) discard it with its **outgoing edges**
 - 3) recalculate τ for remaining nodes until no **candidates** left
- This approach iteratively crumbles Sybil clusters one **Sybil** at a time

Simulation Analysis

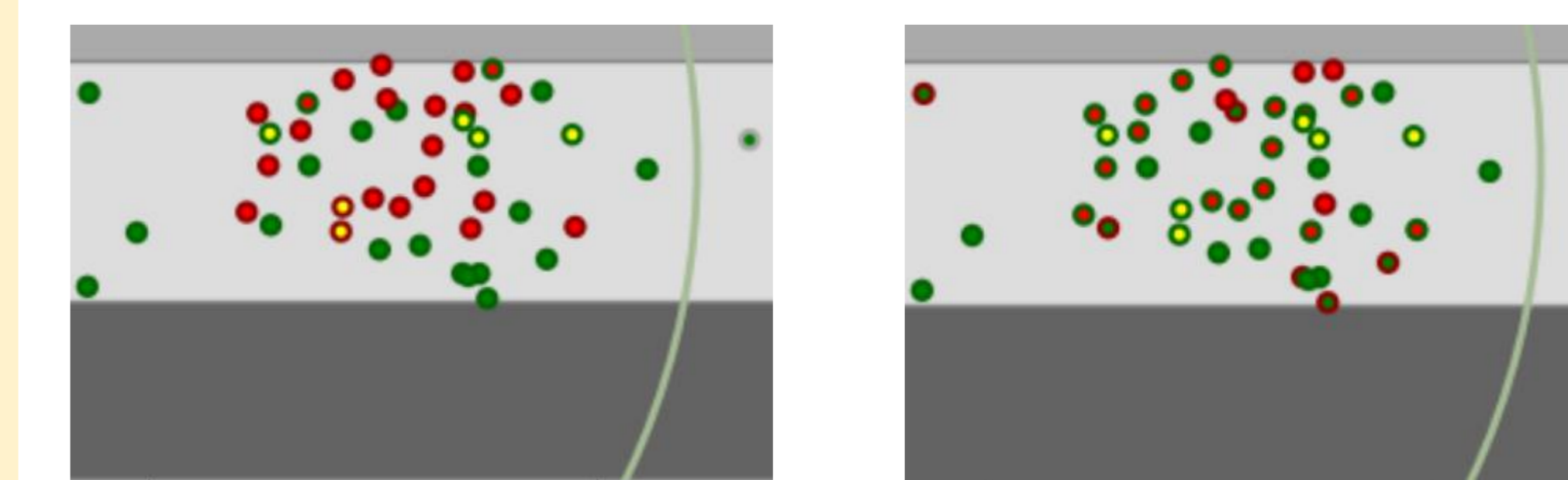
Simulator

- Generates life-scale distribution of nodes
- Simulates connectivity algorithm and successes/failures based on pairwise distance
- Creates Sybil and malicious nodes (physical adversarial agents) and employs evasive tactics
- Runs primary detection algorithm along with Graph-Based methods for comparison



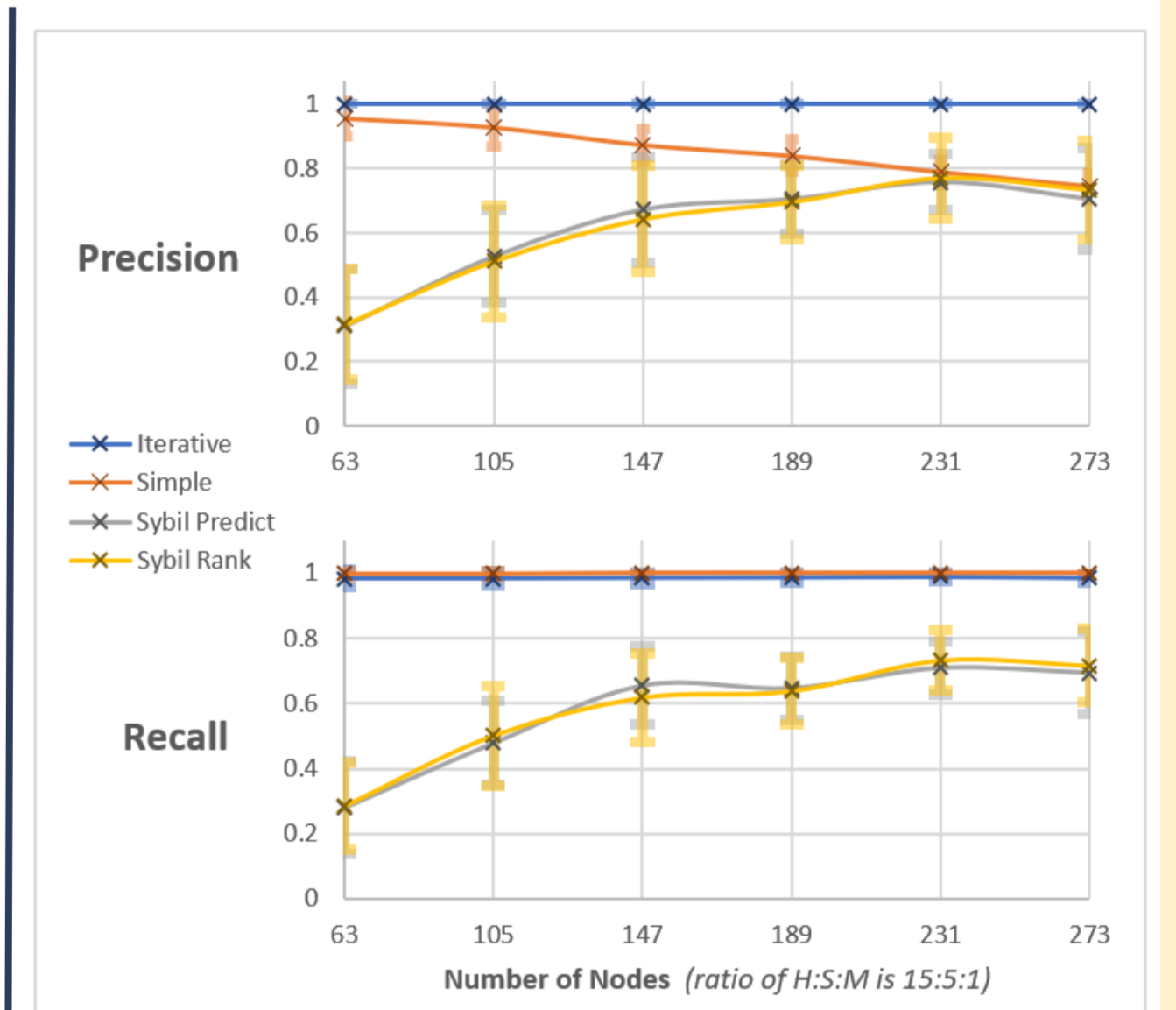
Simulation scenario: **100 honest nodes**, **20 Sybil nodes**, and **6 Malicious nodes** (fill) on Market Street in SF. Large circle defines participants. Selected detection algorithm ("Simple") predicts **real** and **Sybil** nodes (rim).

Malicious nodes use evasive tactics (challenges 2 & 3) to integrate Sybils into the proximity graph. This may have **devastating effects** on traditional Graph-Based Detection algorithms, while **our approach remains robust**.



Sybil-Rank Detector. Performance is worse compared to our approach: **2 false negatives** compared to 0.

Sybil-Predict Detector. Catastrophic output on the same input, highlighting the fragility of Graph-Based Sybil Detection methods.



Results. Detection performance across 4 detection algorithms, with **Iterative** (our approach) clearly dominating in both precision and recall.

Here the adversary uses evasive strategies to intermix **Sybils** with **honest nodes** in the proximity graph.

The most important aspect is the difference in **variance** (shown as error bars), indicating that the Graph-Based Detection algorithms occasionally have **catastrophic failures**, as shown in the example on the left.

The robustness of our approach comes from the smoothness of the likelihood when used as a test statistic.