

Integrated Safety Incident Forecasting and Analysis

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Project: Objective: Develop Principled Algorithmic Decision Procedures for Emergency Response

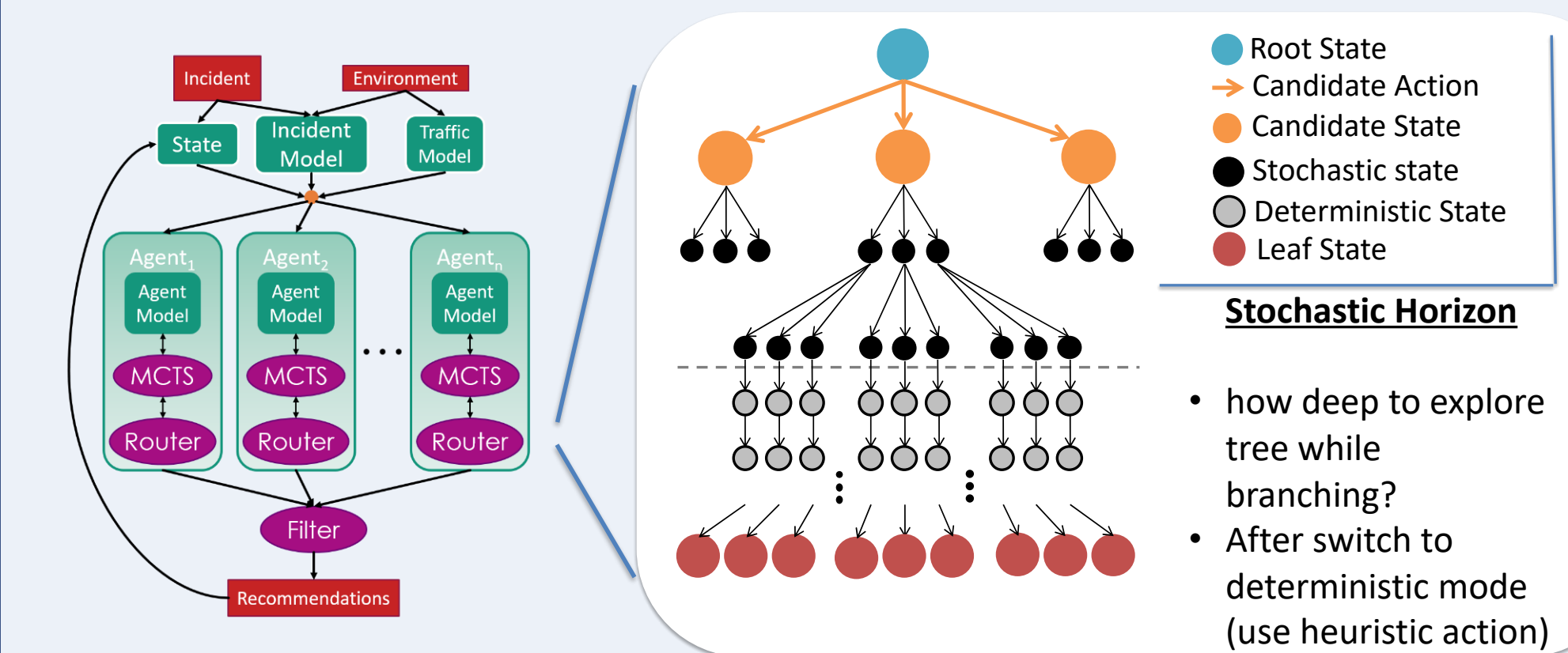
- There are limited emergency responder resources.
- How to assign resources to incidents while reducing average response time
- Decision must be made quickly.



- The planning process should occur before incidents. It is difficult to justify sending anyone but the closest responder at the time of an incident's occurrence.
- Optimizing over responder distribution and response as a multi-objective optimization problem is typically computationally infeasible.
- Example: let the number of responders $r=20$, and the number of possible depot locations be $d=30$. Possible actions for dispatching is the number of responders $\rightarrow 20$
- Possible actions for rebalancing is $P(d, r) = 30!/10! = 7.31 \times 10^{25}$.

Our Approach: Partially Decentralized Decision Process

- We focus on three problems (a) designing an accurate incident prediction model; (b) design approach for rebalancing the responders pre-incident and (c) designing an emergency response system that is equipped to deal with scenarios that require decentralized planning with very limited communication.



Reward function: The primary metric to consider is the response time for each incident
Secondly, the movement of responders needs to be controlled

$$r_s^d = \begin{cases} r_{s-1} - \alpha^{t_s}(t_s^d), & \text{if responding to an incident} \\ r_{s-1} - \alpha^{t_s} \psi \frac{\sum_{i \in \mathcal{A}} (d_i^d)}{|\mathcal{A}|}, & \text{if balancing at } s \end{cases}$$

Online Incident Prediction

- Features:** Weather, time, previous incidents, neighboring incidents
- Needs to react to dynamic incident occurrence
- Streaming survival analysis:**

$$L = \prod_i h(\log(t_i) - \bar{\beta}W)$$

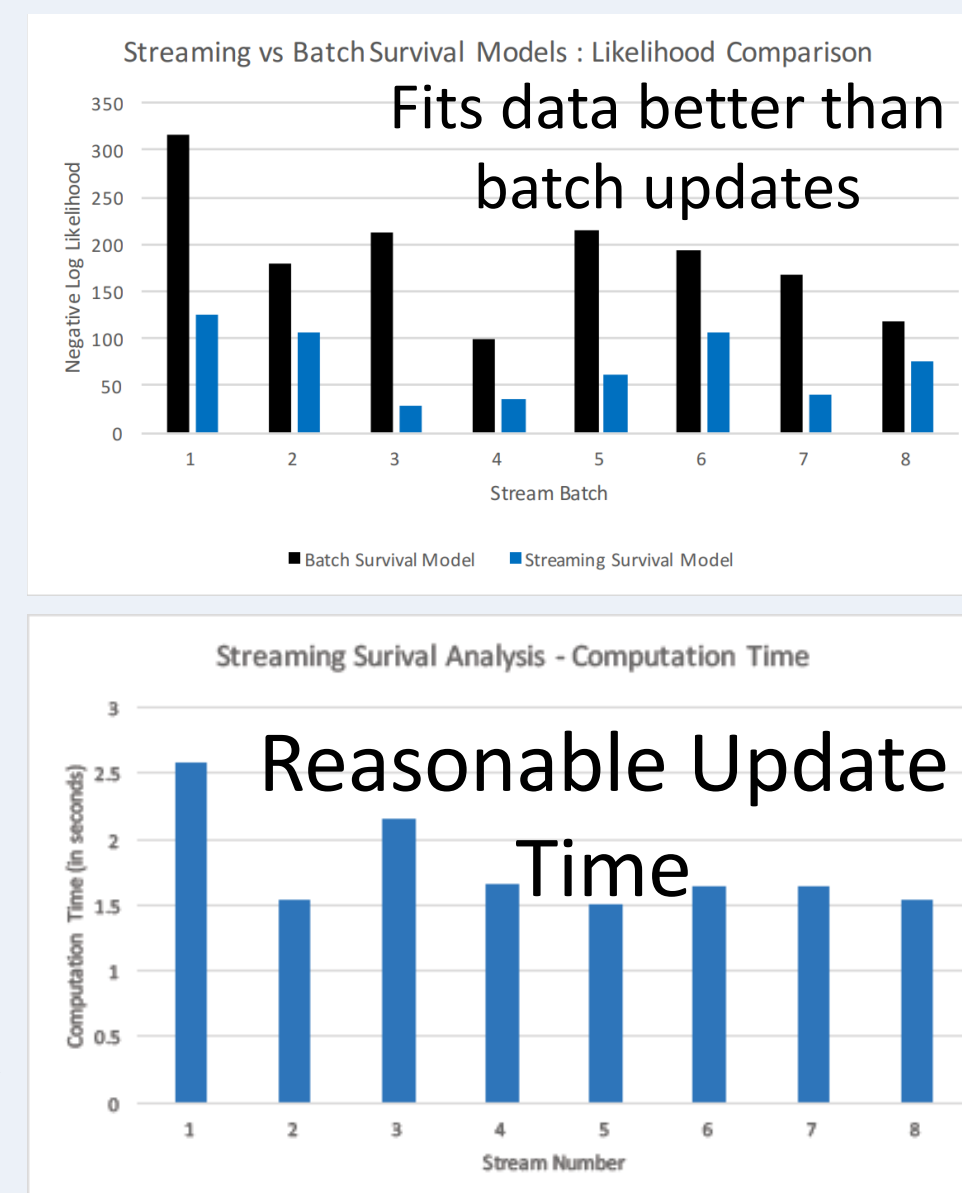
Probabilistic Model for Incident Prediction

$$\beta^{p+1} = \beta^p + \alpha \nabla L(\beta^p, D')$$

Online Update of Coefficients

$$\frac{\partial L}{\partial \beta_j} = \sum_{i=1}^k -w_{ij} + w_{ij} \{e^{(\log \tau_i - \beta^* w_i)}\}$$

Gradient Calculation



Preemptive Rate Based Rebalancing

- We use a multi-class queue model to enable the responders to anticipate the action of other responders.
- Multiple cells serviced by each depot and vice versa
- Must split request rate for cells between depots
- Since depots closer to a cell are more likely to service it, rates are split such that they are inversely proportional to the distance

$$\sum_{d \in D} v_g^d = v_g$$

$$\text{dist}(d_1, g) v_g^{d_1} = \text{dist}(d_2, g) v_g^{d_2} \quad \forall d, d_2 \in D$$

$$\pi = \sum_{d \in D} \sum_{g \in G} \text{responseTime}(c, v_g^d, \mu) + \text{travelTime}(d, g)$$

Where c is number of responders at depot, v is split incident rate, and μ is the service rate. $\text{ResponseTime}(c, v_g^d, \mu)$ is $M/M/c$ queue response time, $\text{travelTime}(d, g)$ is the time to travel from depot d to the grid in question g

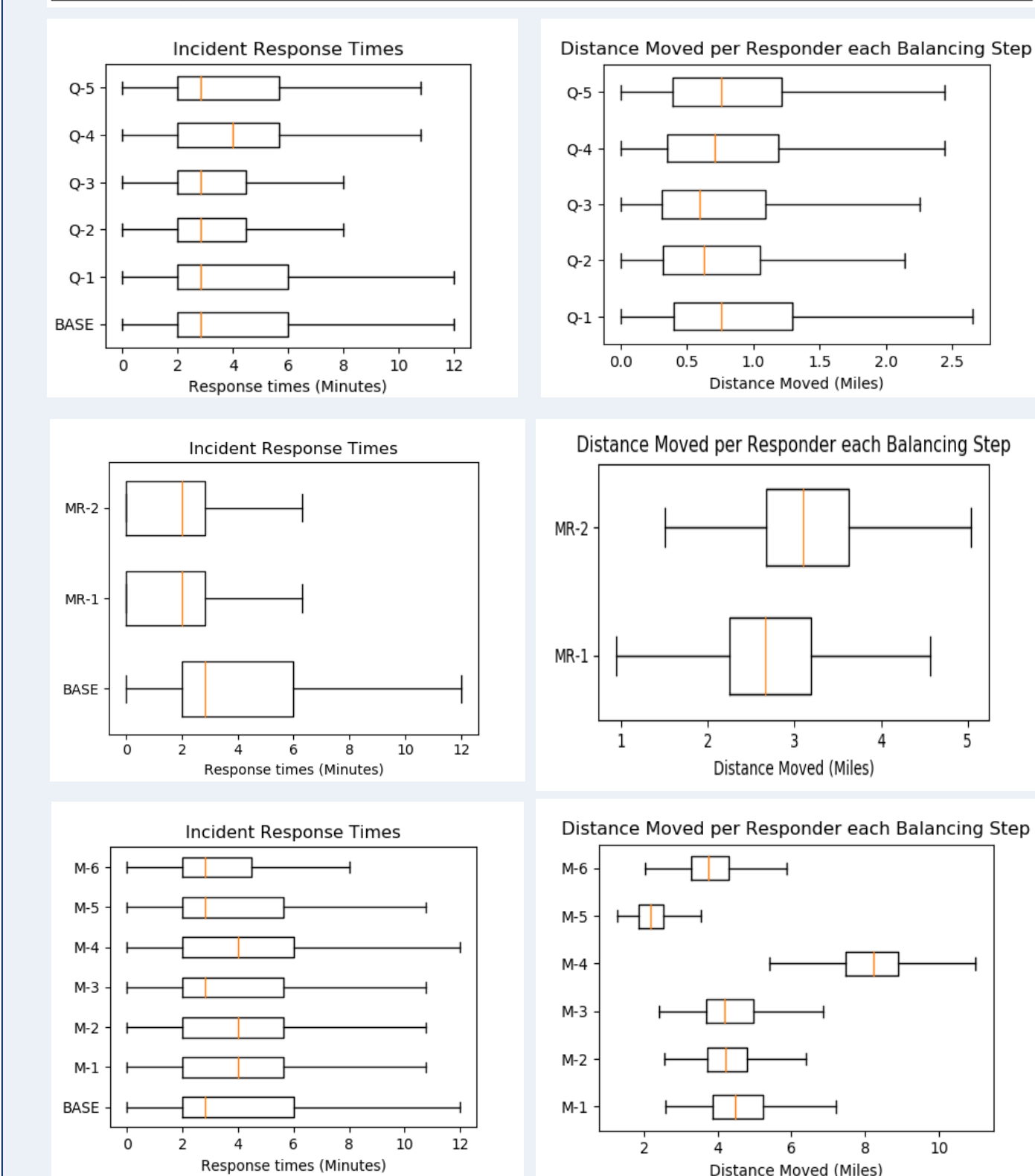
- To score a particular assignment of responders to depots, all response times (computed from multi class queue formulation) are summed using the split rates.
- To determine the best placement, an iterative greedy search is used to select the best depots one at a time using the above score

Integrated Dashboard



Results

Identifier	Description	Hyper-Parameter Choices
BASE	Greedy Baseline Without Rebalancing	N/A
Q-1	Queue Based Rebalancing Policy with RoI of 1	RoI = 1
Q-2	Queue Based Rebalancing Policy with RoI of 2	RoI = 2
Q-3	Queue Based Rebalancing Policy with RoI of 3	RoI = 3
Q-4	Queue Based Rebalancing Policy with RoI of 4	RoI = 4
Q-5	Queue Based Rebalancing Policy with RoI of 5	RoI = 5
MR-1	MMCTS - using an oracle for future incidents and a Static Agent Policy	Same as MMCTS Baseline M-1
MR-2	MMCTS - using an oracle for future incidents and a Queue Rebalancing Policy	Same as MMCTS Baseline M-1
M-1	MMCTS - Baseline The foundation for the parameter search. Each parameter varies independently while other parameters retain these values. (All M-* experiments use generated incident chains and a Static Agent Policy)	MCTS Iteration Limit = 250 Lookahead Horizon = 120 min Reward Distance Weight $\psi = 10$ Reward Discount Factor = 0.99995 Rebalance Period = 60 min
M-2	MMCTS - Iteration Limit of 100	MCTS Iteration Limit = 100*
M-3	MMCTS - Iteration Limit of 500	MCTS Iteration Limit = 500*
M-4	MMCTS - Reward Distance Weight ψ of 0	Reward Distance Weight $\psi = 0^*$
M-5	MMCTS - Reward Distance Weight ψ of 100	Reward Distance Weight $\psi = 100^*$
M-6	MMCTS - Rebalance Period of 30 minutes; Lookahead Horizon of 30 minutes	Lookahead Horizon = 30 min* Rebalance Period = 30min*



MMCTS performs better than greedy baseline with most parameters
Oracle solutions show the potential upside. It requires an even better incident forecasting model.

- Data: Nashville, TN incident data
- Training for predictive model: 1-1-2018 to 1-1-2019
- Testing: 1-1-2019 to 2-1-2019
- Utilized Regions of Interest (RoI) for queue model: Only depots within a cell's RoI are considered when splitting its rate
- Encourages even responder distribution
- Reduces computation time
- Explored several parameters for MMCTS, particularly the distance reward weight and iteration limit for MCTS
- Compared to the incumbent policy of greedy dispatch without rebalancing as a baseline
- An Oracle refers to an incident predictor with perfect knowledge about future incidents (best case scenario for MCTS)

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<https://github.com/scope-lab-vu/DataDrivenEMSDispatch>