Interactive Human-Drone Partnerships in Emergency Response Scenarios

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Challenge:

To deploy sUAS as true partners with humans in emergency response missions -- serving as autonomous, self-coordinating, trusted members of a mission team.

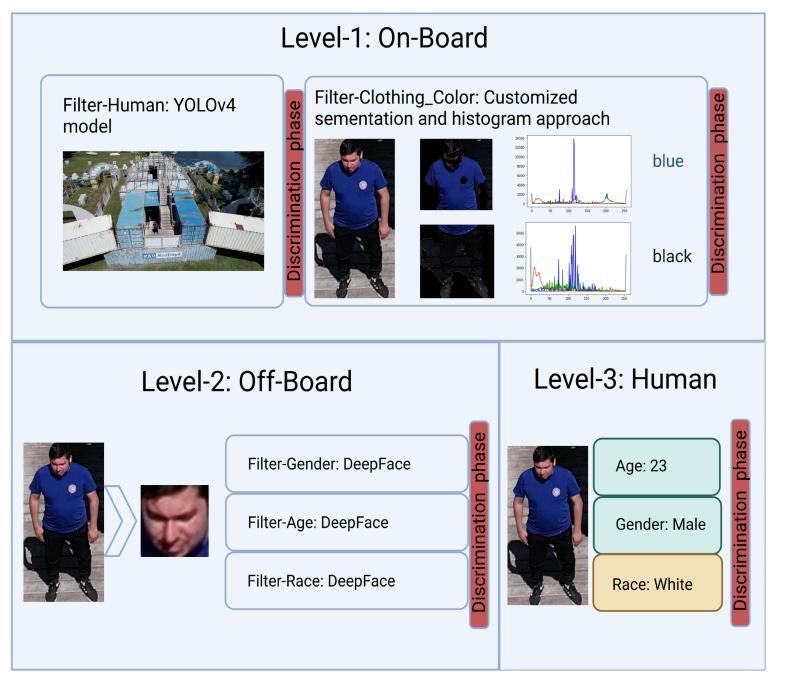


Solution:

Dynamically configurable sUAS by emergency responders for diverse missions.



- Human-machine partnerships through autonomous and collaborative sUAS.
- Interoperability across flight controllers & sUAS
- Air-tunnel leasing for multi sUAS missions.
- Hierarchical Computer Vision model distributed across edge devices and ground-based Microservices.
- CV-driven sUAS maneuvers to improve perspective.

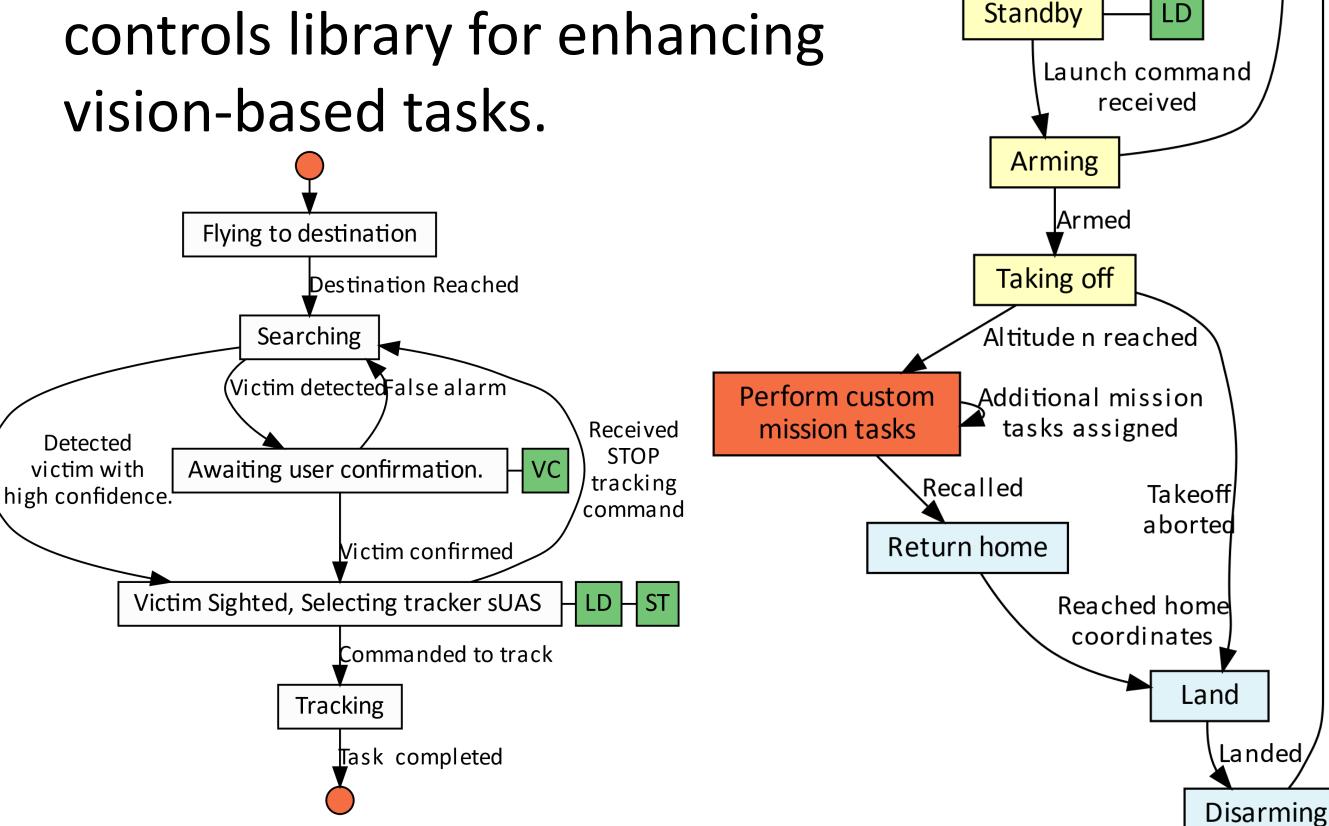






Scientific Impact:

- Novel aerial dataset of occluded people to support training new Computer Vision models.
- Vision-based maneuver controls library for enhancing



Each sUAS receives a specification, self-configures prior to launch, to enact and coordinate missions.

Broader Impacts:

- Developing next-gen intelligent sUAS for use by emergency responders to save lives.
- Public events hosted with South Bend and Michigan City Fire departments.
- Research opportunities provided for over 20 undergraduate and 8 graduate students -- including underrepresented minorities.
- STEM outreach to local primarily minority-serving elementary schools.



Mission configuration

OnGroundAndInactive

checks

failed

Disarmed

Landed

checks

jnitiated

Preflight checks

passed

Preflight Checks

Configuration







