NRI: FND: Knowledge-based Robot Sequential Decision Making under Uncertainty #1925044, 9/1/2019, PI: Shiqi Zhang, SUNY Binghamton

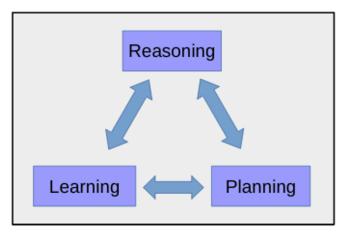


Challenge

 Robot decision-making is challenging: imperfect perception, incomplete domain knowledge, non-deterministic action outcomes, and limited interaction experience...

Solution

 A robot sequential decision-making framework that simultaneously supports learning to perceive the environment, reasoning about declarative contextual knowledge, and planning to actively collect information for task completion



Robot sequential decision-making

Scientific Impact

 Bring in computational methods of different modalities toward a generally applicable, robot decisionmaking framework that can significantly promote the development of intelligent agents

Broader Impact

- Example application domains include robotics, finance, urban planning, healthcare, games, transportation, e-commerce...
- K-16 education, University Undergraduate Research programs, etc

Learning, Commonsense Reasoning, and Probabilistic Planning (LCORPP), A Robot Sequential Decision-Making Framework



