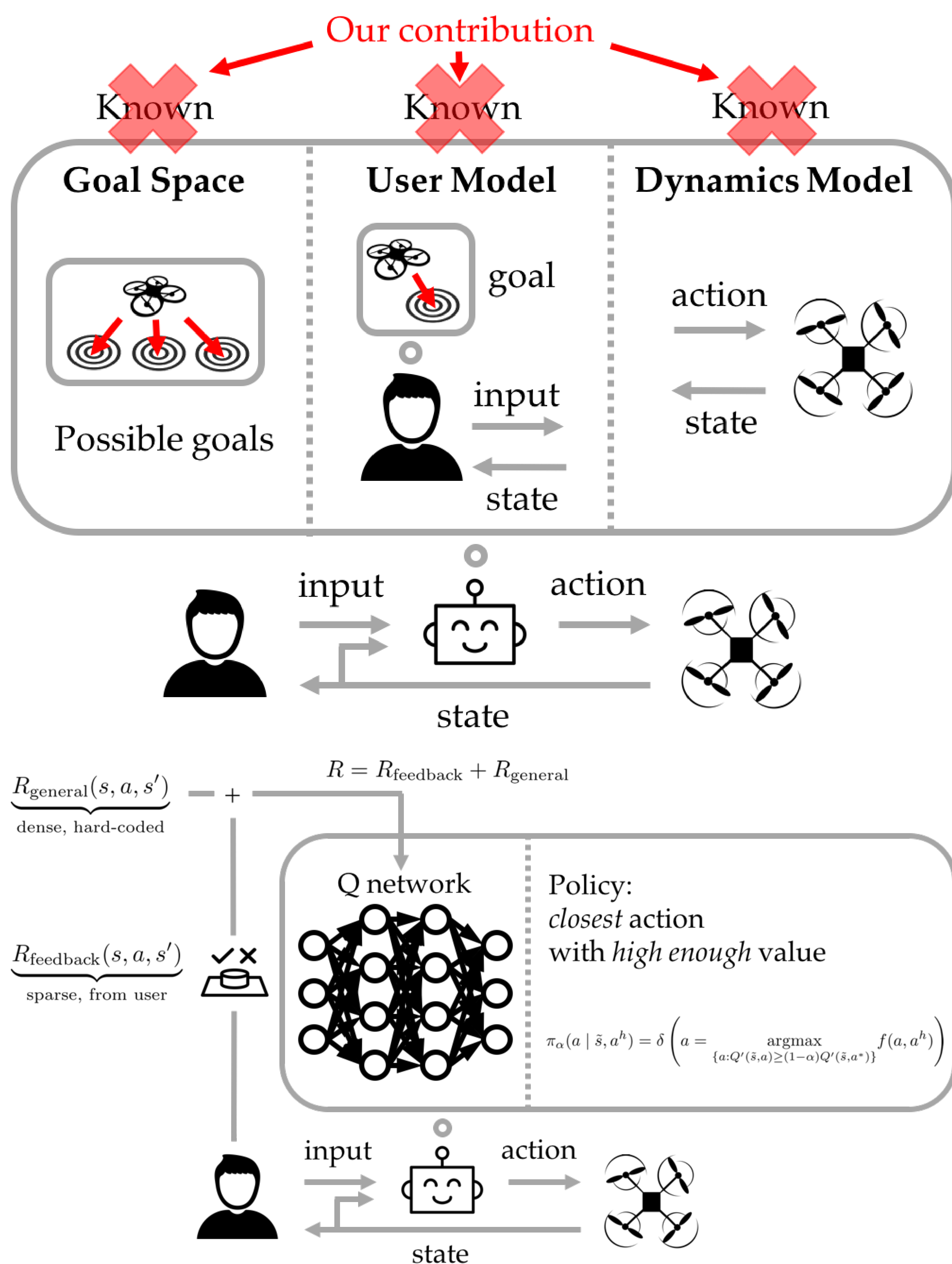


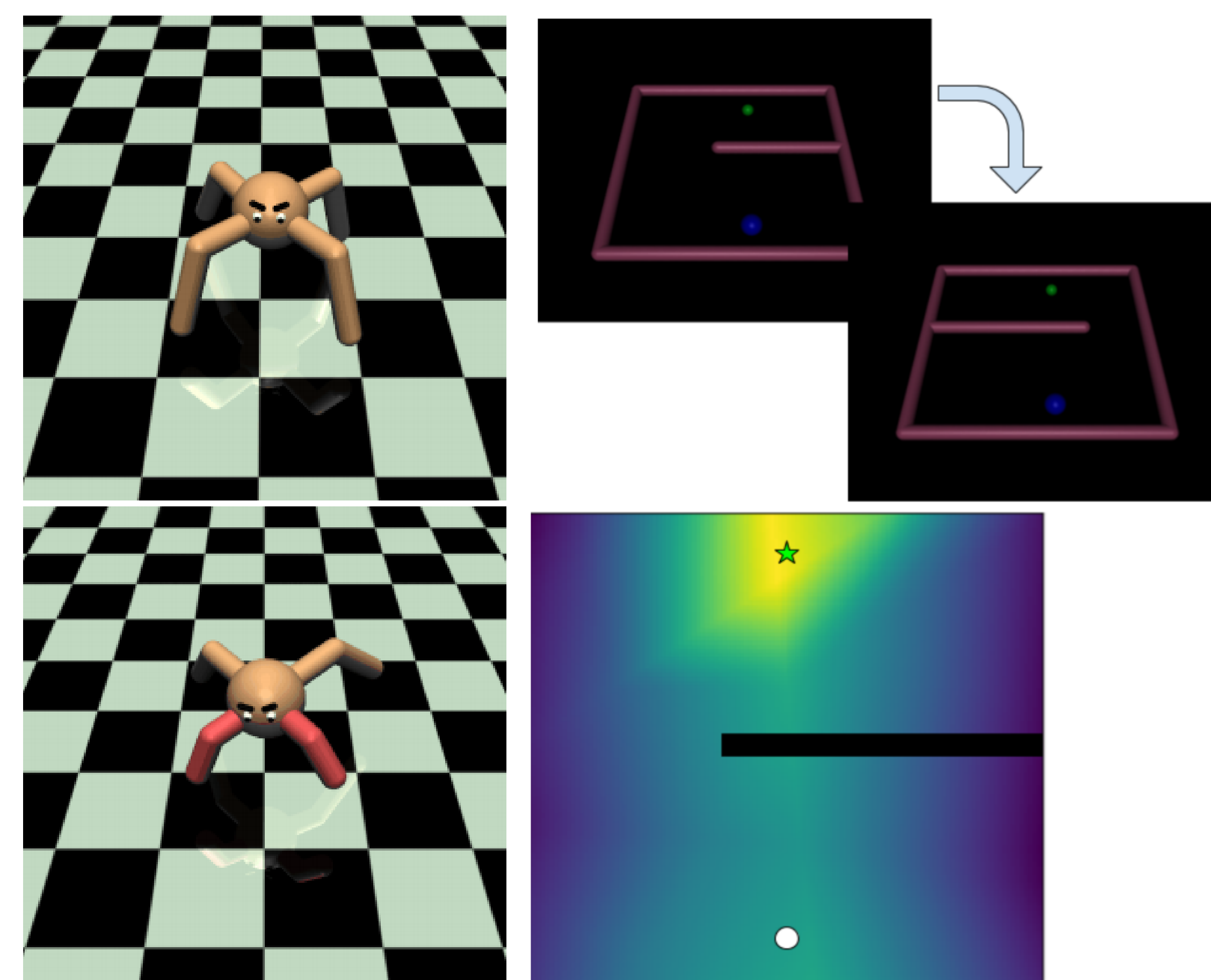
# Learning Deep Sensorimotor Policies for Shared Autonomy

Sergey Levine, UC Berkeley

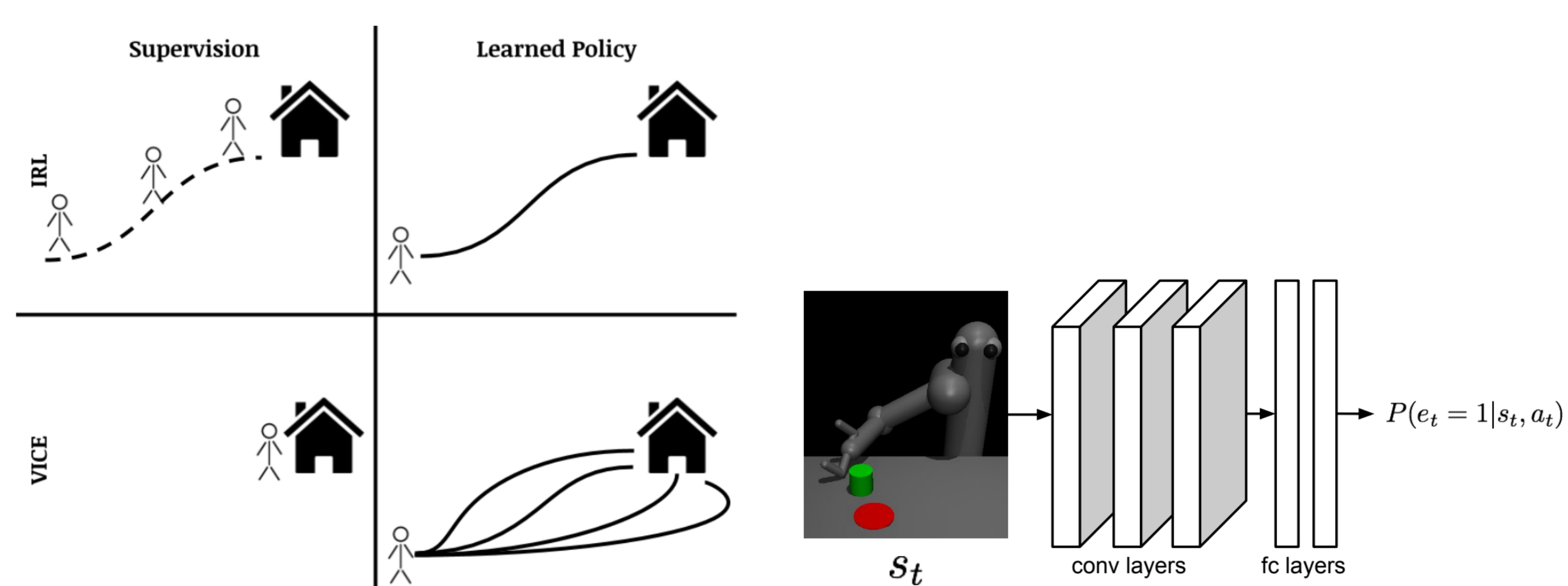
## Augmenting Human Control with Deep Q-Learning



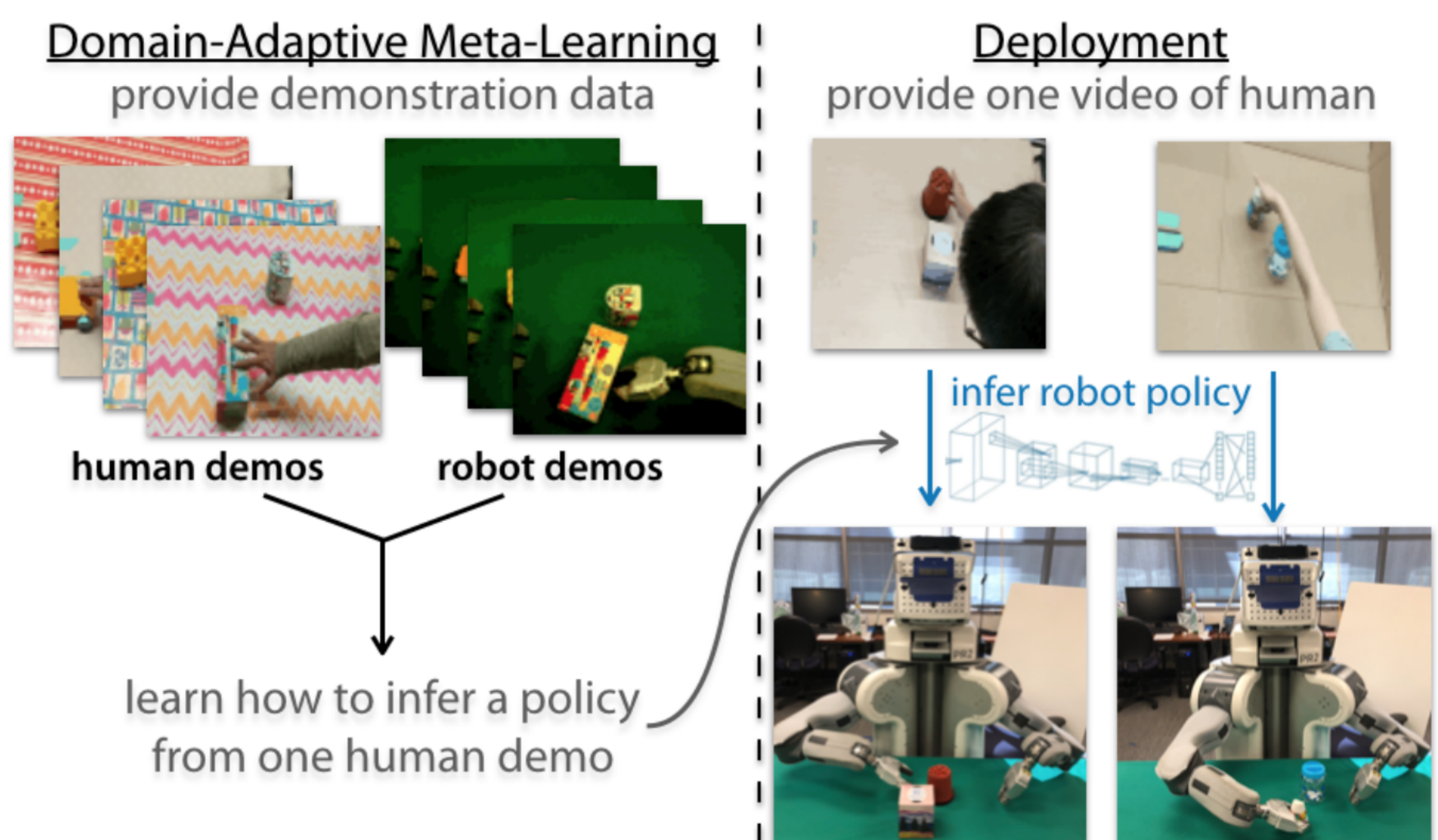
## Robust Inverse Reinforcement Learning



## Event-Based Task Specification and Control



## Learning to Learn for Imitating Humans



## Inferring Beliefs about Dynamics from Behavior

