

# Models and System-Level Coordination Algorithms for Power-in-the-Loop Autonomous Mobility-on-Demand Systems

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## Introduction: Autonomous Mobility-on-Demand (AMoD)

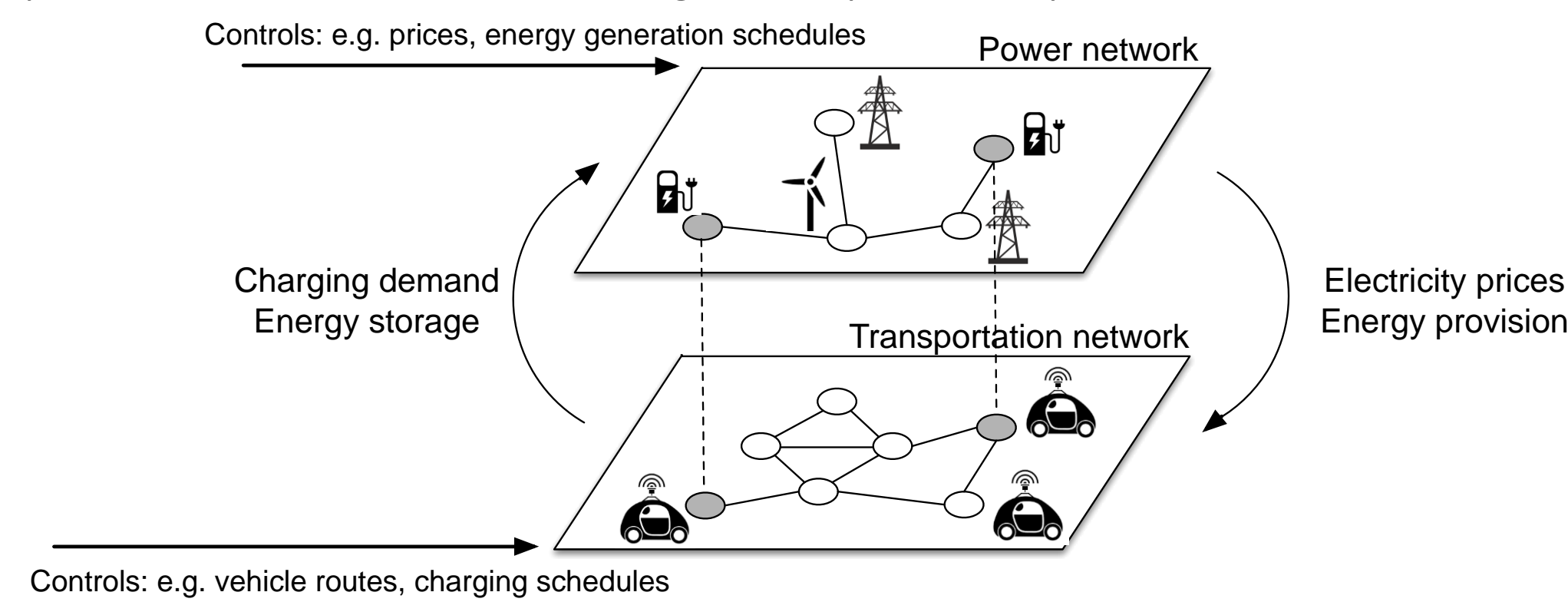
**Electric AMoD:** mode of transportation wherein **self-driving, electric vehicles** transport passengers on demand in a given environment



Autonomous Mobility-on-Demand (AMoD)

## Couplings between AMoD and the Power Network

**Key observation:** AMoD will give rise to complex couplings between the power and transportation networks over a wide range of temporal and spatial scales

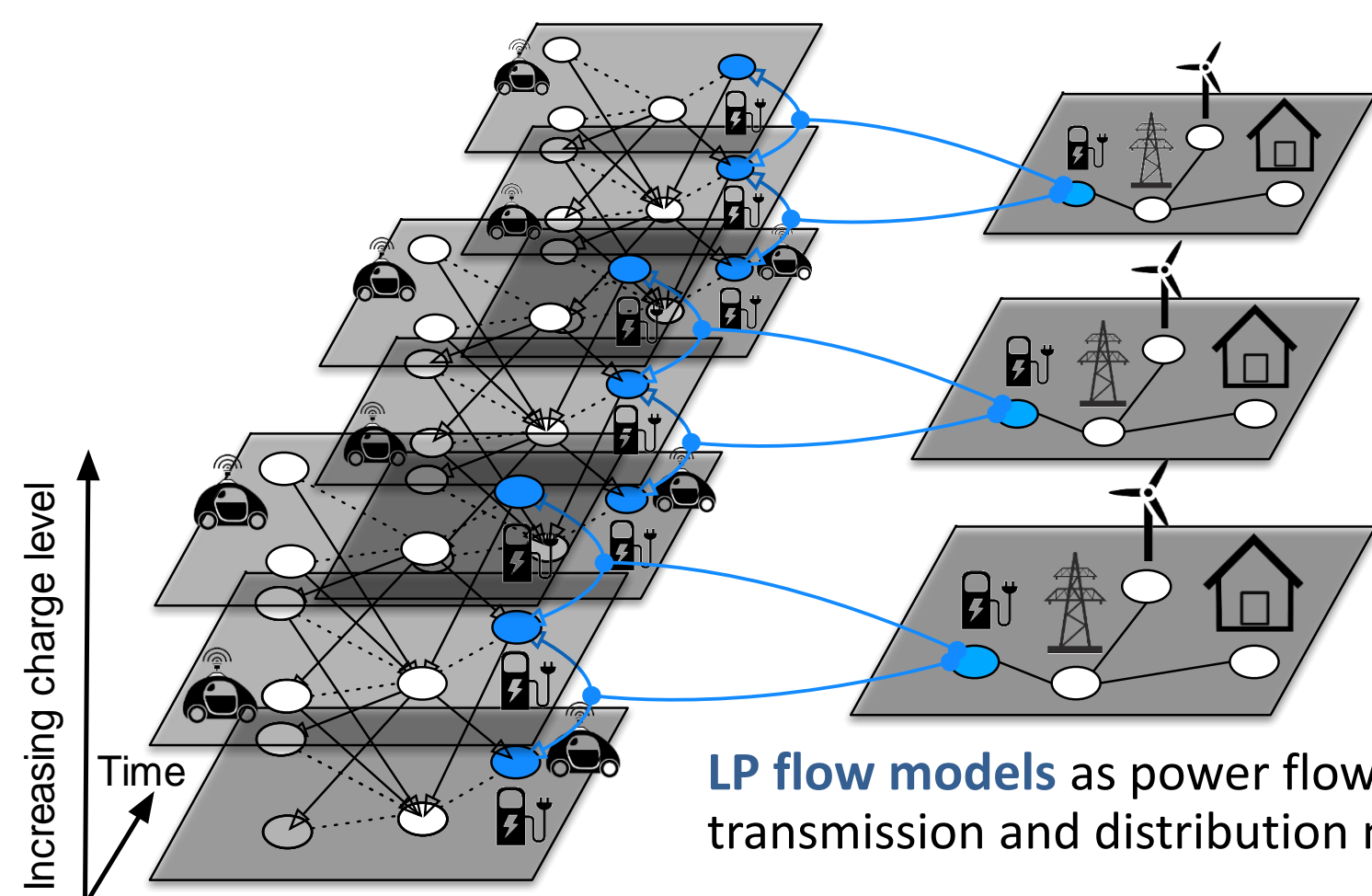


## Technical Approach: Multi-commodity Network Flows

**Road network:** directed graph  $G(V, E)$

**Congestion model:** capacity constraint on each edge

Augmented **network flow model:** time and state of charge



**LP flow models** as power flow surrogates for transmission and distribution networks

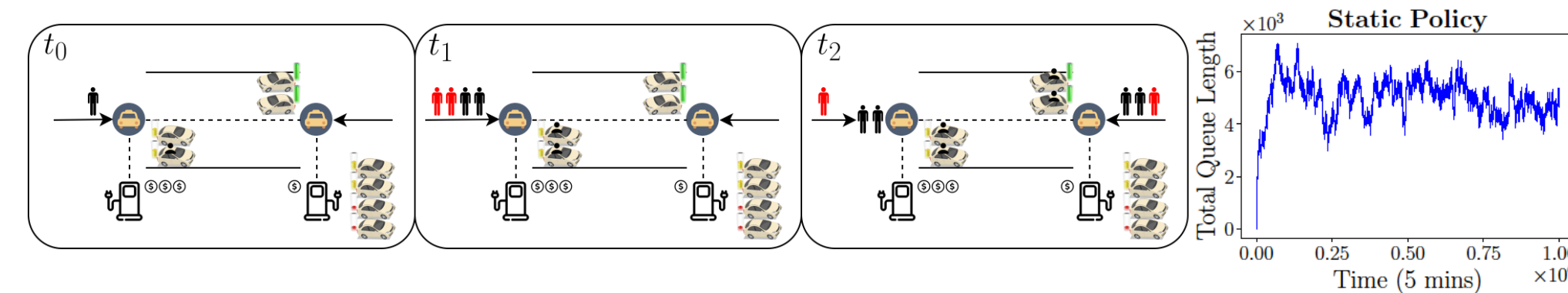
Interaction between AMoD and power network can be optimized as a **linear program**

## Summary of Recent Objectives and Results

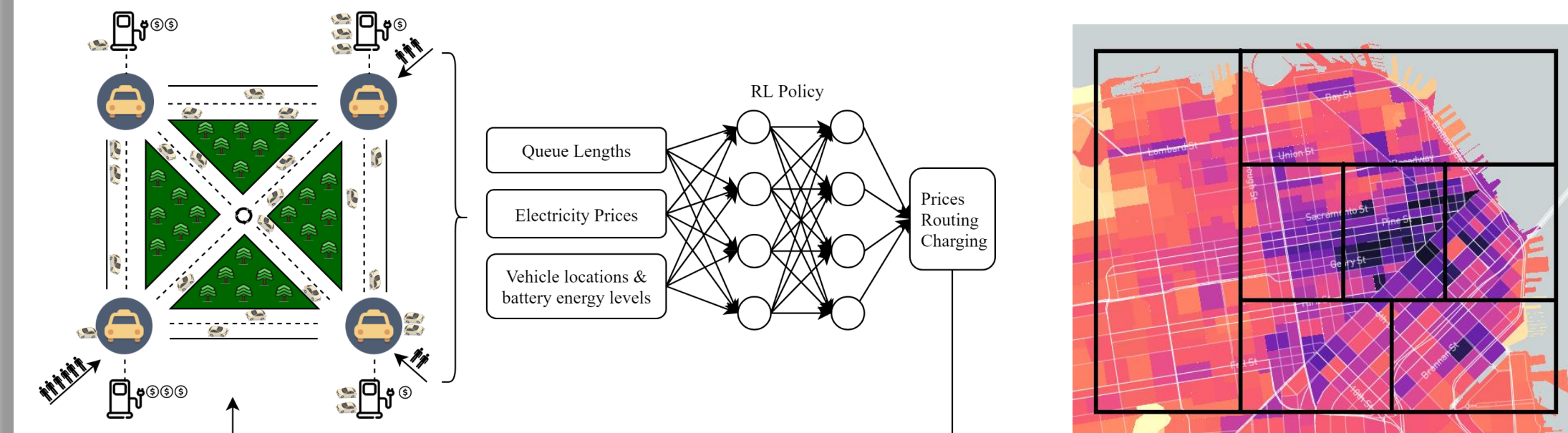
- Offline analysis:** optimizing P-AMoD and 3-phase power distribution networks in Orange County; joint optimization of electric AMoD and station siting in San Francisco
- Online control:** deep RL model for real-time control in Bay Area and Manhattan
- Competition:** study monopoly vs duopoly equilibria of electric AMoD systems

## Results: Real-time Control

- Develop joint pricing, vehicle routing, and vehicle charging policy
- Optimal static policy guarantees stability of the queues, however, is oblivious to the stochastic events occurring in the dynamic environment

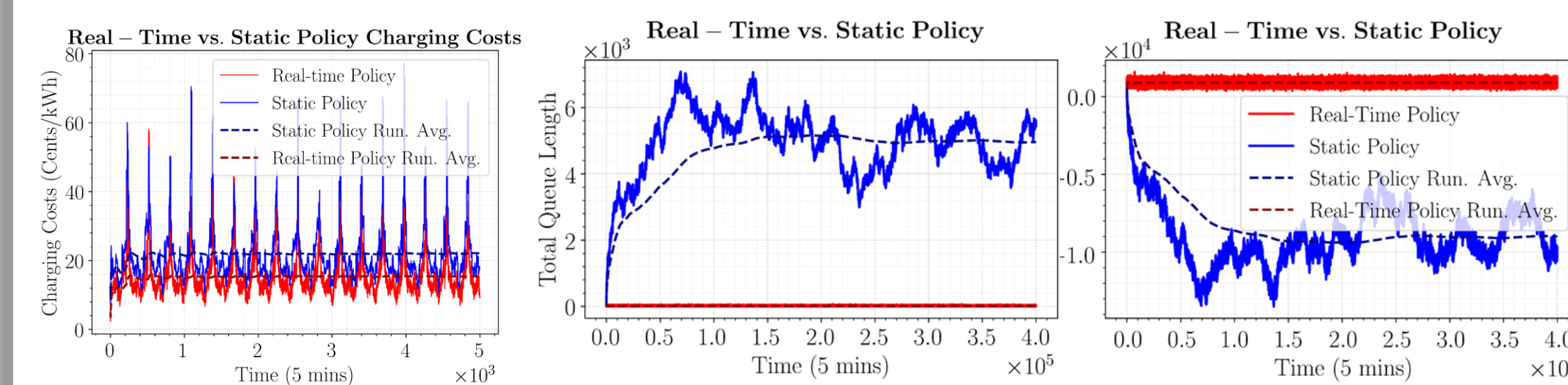


- A real-time control policy can perform better in the stochastic environment
- Due to the curse of dimensionality, intractable to solve for the optimal policy
- Utilize deep reinforcement learning to establish a near-optimal policy



## Case Study in Bay Area

- Using real network and demand data, develop and implement RL policy
- 400x shorter queues, 25% less charging costs, increased profits



## Improvements with Multi-agent RL

- Reinforcement Learning network has good performance, but it's increasingly difficult to train when applied to larger maps, as both the state and action spaces are of dimension  $O(n^2)$
- Multi-Agent RL exploits the locality of the process, accelerates training by significantly reducing the number of parameters required

## Case Study in Manhattan Area

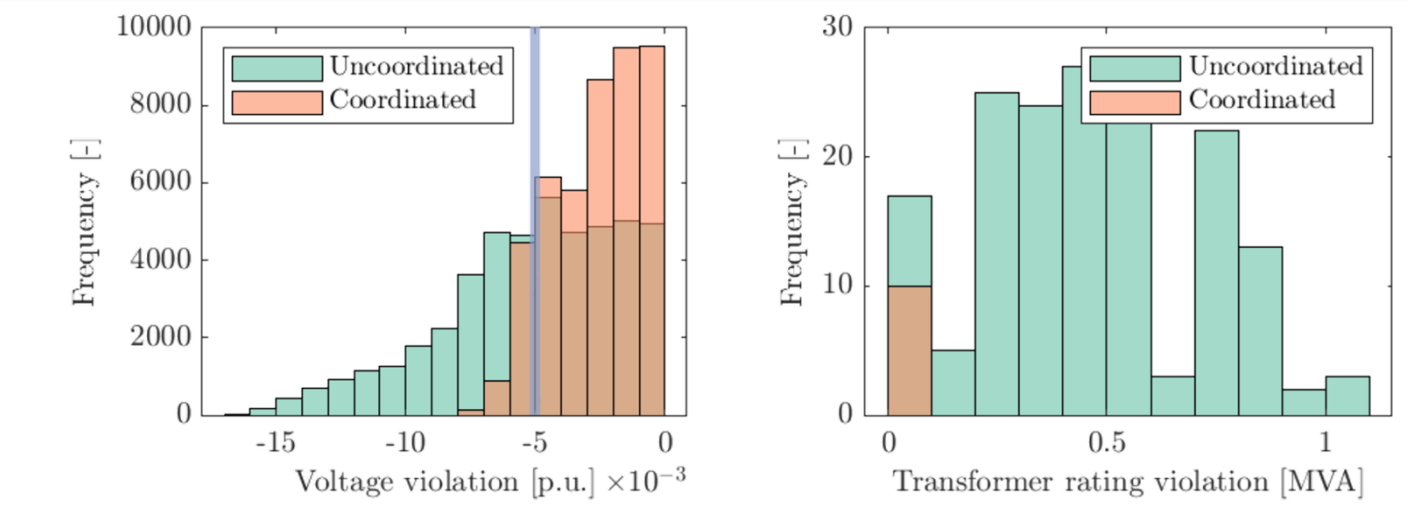
- Using real network and demand data, develop multi-agent RL policy
- 80% increase in profits

[1] B. Turan, R. Pedarsani, and M. Alizadeh, "Dynamic pricing and fleet management for electric autonomous mobility on demand systems," *Transportation Research Part C: Emerging Technologies*, vol. 121, p. 102829, 2020.

[2] A. Wang, B. Turan, and M. Alizadeh, "Multi-agent Reinforcement Learning for Dynamic Pricing and Fleet Management in autonomous mobility-on-demand systems," *International Telemetering Conference*, 2022.

## Results: Power-in-the-loop AMoD (P-AMoD) in Orange County, CA

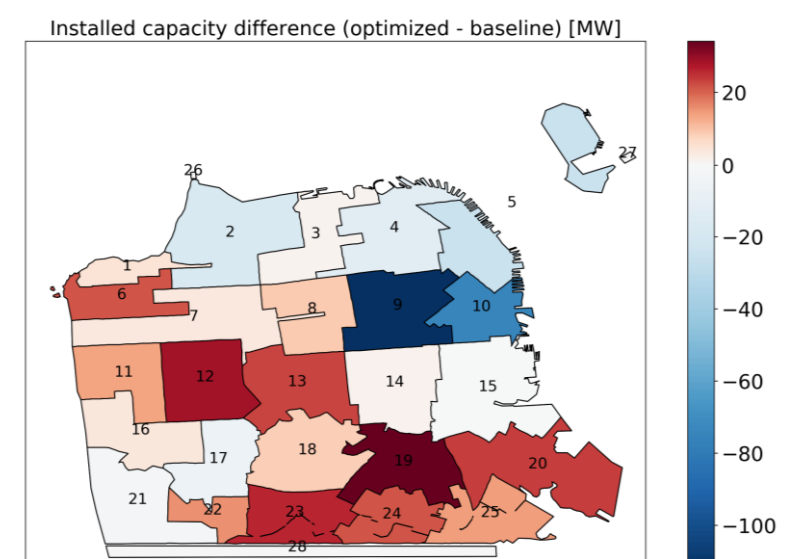
- Uncoordinated electric AMoD causes substation overloads (7.98MVAh) and voltage violations (24.04 p.u.-h) across 14 PDNs over an 8-hr commute cycle
- Coordination reduces substation overloads by 99.71% and voltage violations by 50.28%, while operating costs increase by only 3.13% (3300 USD)



[3] A. Estandia, M. Schiffer, F. Rossi, J. Luke, E. C. Kara, R. Rajagopal, and M. Pavone, "On the Interaction between Autonomous Mobility on Demand Systems and Power Distribution Networks – An Optimal Power Flow Approach," *IEEE Transactions on Control of Network Systems*, 2021.

## Results: Electric AMoD Systems with Charging Station Siting

- Planning and operations optimized jointly: station siting, heterogeneous fleet sizing, charging, routing, and rebalancing solved using LP network flow model
- Case Study in San Francisco, CA: joint siting of stations reduces vehicle deadhead travel, peak charging demand, and total fleet costs by 10% compared to scaled-up present-day siting baseline
- Stations are more spatially distributed than present-day siting
- Low-cost, efficient EVs are more cost-effective despite short range

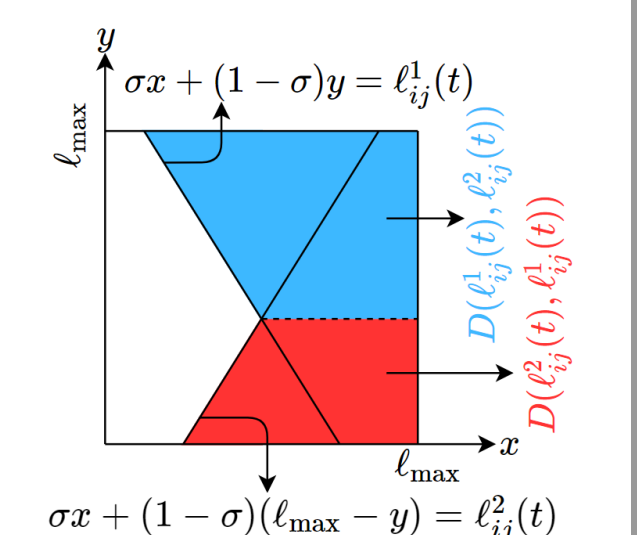


- Mid-power charging (20-30kW) is sufficient; reduction in installed  $\geq 50$ kW DC fast charging capacity

[4] J. Luke, M. Salazar, R. Rajagopal, and M. Pavone, "Joint optimization of autonomous electric vehicle fleet operations and charging station siting," *2021 IEEE International Intelligent Transportation Systems Conference (ITSC)*, pp. 3340–3344, 2021.

## Results: Competition in Electric AMoD Systems

- Study competition in electric AMoD systems by comparing the monopoly and the duopoly in equilibrium
- Identical competitors can only be in a symmetric equilibrium
- Closed-form bounds quantify the impacts of the competition on the ride prices, the profits of the firms, the aggregate demand served and the consumer surplus
- Higher correlation between customers' preferences strengthens the competition and boosts the impacts of competition



	Empirical		Theoretic LB		Theoretic UB	
Correlation Coefficient $\sigma$	0.6	0.8	0.6	0.8	0.6	0.8
Price Ratio	0.80	0.42	0.11	0.67	0.29	0
Demand Ratio	1.44	1.73	2.04	1.25	1.11	1
Profits Ratio	0.57	0.32	0	0.39	0.19	0
Consumer Surplus Ratio	2.00	2.95	4.18	1.46	1.22	1

[5] B. Turan and M. Alizadeh, "Competition in electric autonomous mobility on demand systems," *IEEE Transactions on Control of Network Systems*, vol. 9, no. 1, pp. 295–307, 2022.

## Conclusions

**Electric AMoD systems can act as mobile storage units in the power network**

- Cooperation results in near elimination of substation overloads and halving of voltage violations with a modest cost increase (Orange County, CA case study)
- Reinforcement learning model controls pricing and fleet operations in a stochastic real-time environment with reduced queues and charging costs
- Joint optimization** of E-AMoD systems with charging station siting reduces total costs, vehicle deadhead, peak charging, and fast charging capacity (San Francisco, CA case study)



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