

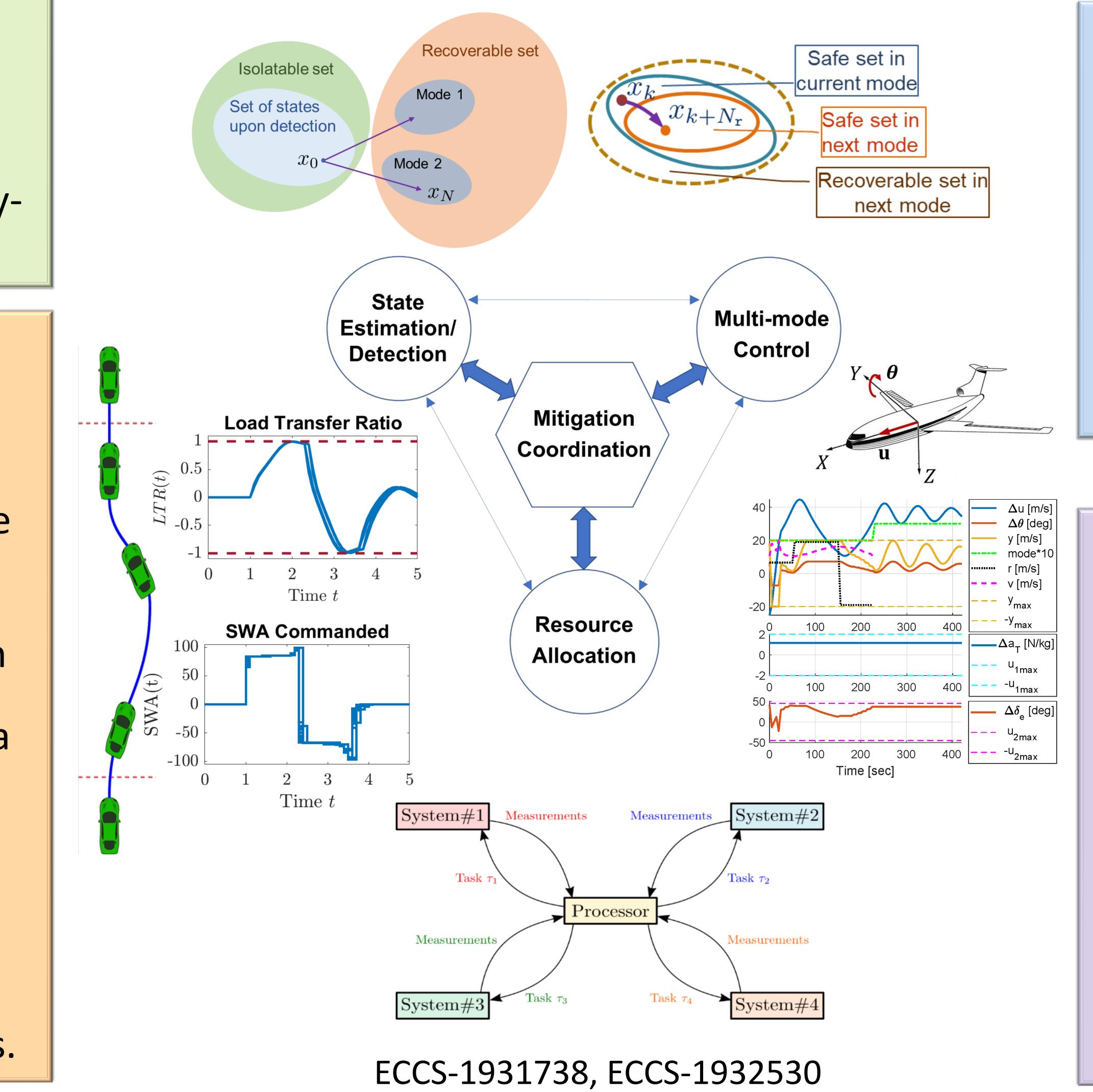
CPS: Medium: Collaborative Research: Multi-Objective Mitigation Strategies for Viability and Performance of Cyber-Physical Systems Bruno Sinopoli (WUSTL), Sanjoy Baruah (WUSTL), Ilya Kolmanovsky (U. Michigan)

Challenge:

Run-time mitigation when complex CPSs operating in uncertain environments confront unanticipated viabilitycompromising situations.

Solution:

- Set-theoretic and stochastic failure detection, isolation and reconfiguration multi-mode control strategies that integrate command governors and enforce safety constraints.
- Computing resource allocation strategies for optimizationbased controllers executing in a shared processor.
- Robust to Early Termination algorithms for optimizationbased control.
- Computationally efficient viability maximizing Model Predictive Control formulations.



Scientific Impact: Strategies for continuing operation in the face of a variety of contingencies. Addressing emergent problems arising from interactions of resource-allocation and optimization-based control strategies.

routing.

Broader Impact:

Outcomes support automotive and aerospace industries in developing safer advanced and autonomous vehicles.

Traffic control solutions to facilitate emergency vehicle

Students and postdocs develop cross-disciplinary expertise.