

NRI: INT: Collaborative Research: Buoyancy-assisted Collaborative Robots That are Cheap, Safe, and Never Fall Down.

Investigators: Dennis Hong @ UCLA | Joseph Lim @ USC | Sehoon Ha @ GaTech
NSF Award #: 2024940 | 2024949 | 2024768 Start Date: Oct 1, 2020

Challenge

Develop novel robots that are safely deployable to human daily environments.

Solution

Introduce a fundamentally new family of legged robots, namely buoyancy assisted robots (BARs).

empower BARs with reliable locomotion and collaboration skills using deep reinforcement learning.



Buoyancy-assistive Robots (BARs):
BALLU (top) and BLAIR (bottom)

Scientific Impact

Design of new cheap and safe robots.
Control of low-fidelity, high-sensitive system.

Broader Impact

Human indoor interactions w/
cameras/microphones/projectors.
Disaster zone / outdoor monitoring with
thousands of robots.
Low-cost and safe platform for STEM
education.