

## **NRI: INT: MiaPURE** (Modular, Interactive and Adaptive Personalized Unique Rolling Experience)

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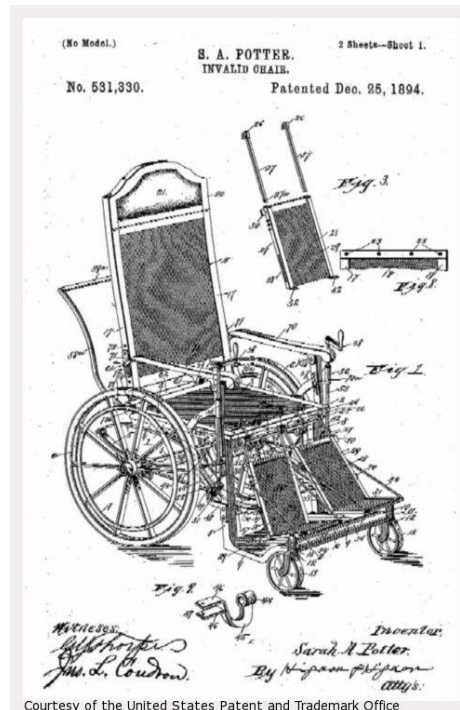
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# Transforming wheeled mobility

## Challenge

- Wheelchair design has changed little in 150 years
- Manual wheelchairs
  - 70% upper extremity injuries
  - Propulsion needs both hands
  - Limited terrain & tight spaces
  - Easy to tip/fall
- Powered wheelchairs
  - Heavy, large, costly
  - Limited tight spaces
  - Need modified vehicle



# INT: MiaPURE (Modular, Interactive and Adaptive Personalized Unique Rolling Experience)



## Solution

- PURE (Personalized Unique Rolling Experience)

- Self-balancing ballbot
- Hands-free motion
- Lean-to-steer ability
- Omni-directional motion
- Compact design

- Modular

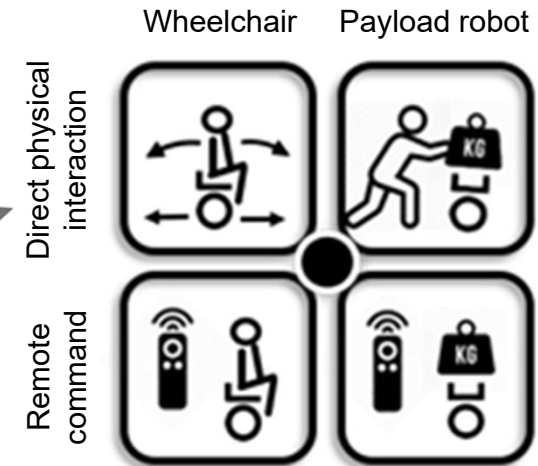
- Common ballbot drivetrain
- Open-source drivetrain platform
- Wheelchair - Payload robot

- Interactive

- Intuitive user interface
- Direct physical interaction
- Remote command

- Adaptive

- Multiple users – loads
- Multiple terrains
- Driving assistance



## Scientific Impact

- Common omnidirectional ballbot platform
  - Compact, agile, safe
  - Open-source
  - Multiple human-robot interfaces

User-Centered Design (continual focus & UX groups)  
manual wheelchair users, able-bodied allies

**AIM 1:** Explore intuitive human-robot user interfaces.

**AIM 2:** Address low-level control of ballbots under direct physical interaction or remote command.

**AIM 3:** Establish higher-level control to improve user driving experience.



Self balancing w/ 50 lb load

## Broader Impacts

- Transformational user-centered co-robot
  - Organic hands-free rolling mobility
- University courses, high school summer camps
  - Design thinking focused on design for disability
- New Human Performance Maker Lab
  - US Paralympic Training Center in UIUC/DRES

