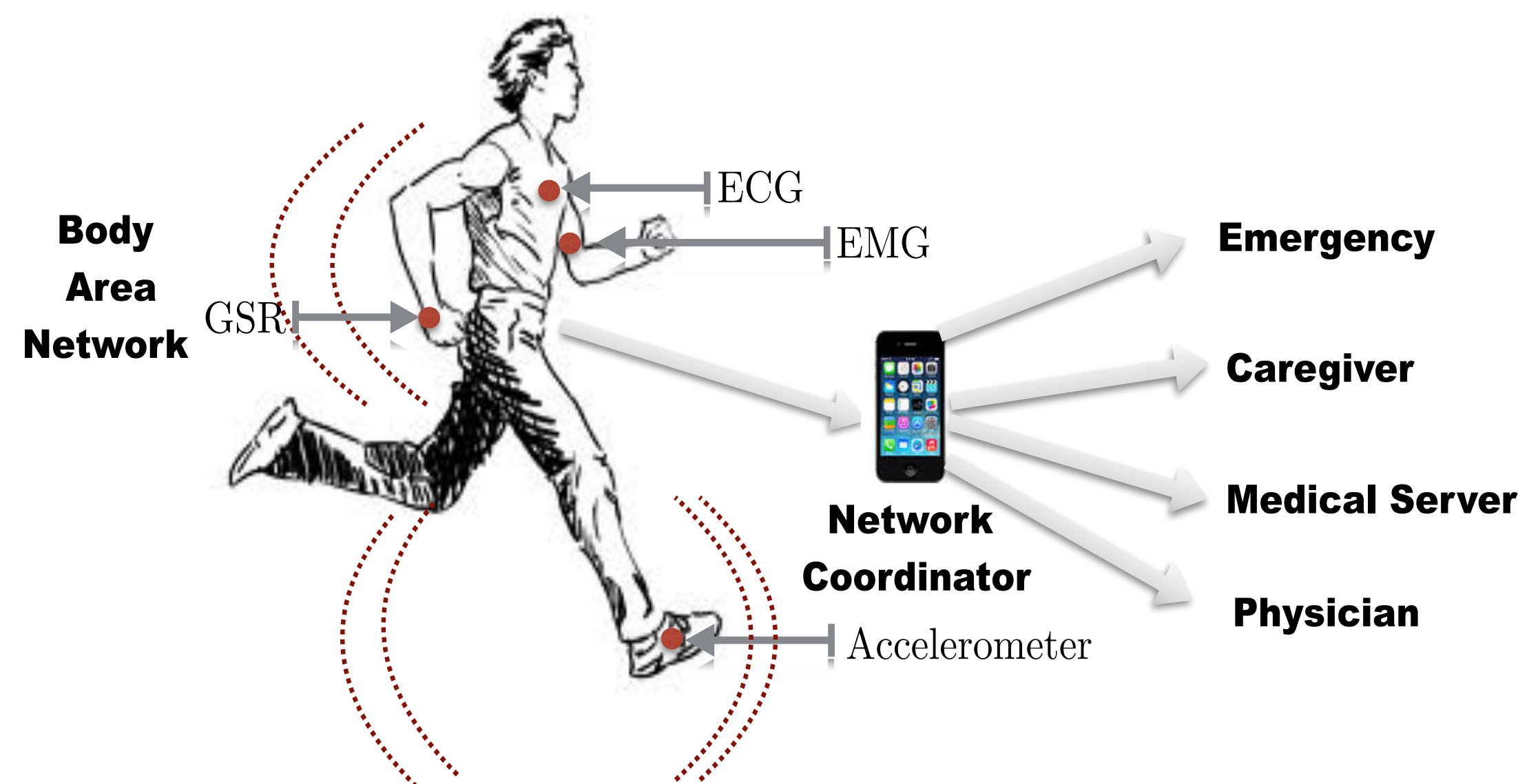


Network Optimization in Cyber-Physical Human Sensing Systems

Marcos M. Vasconcelos, Mukul Gagrani, Ashutosh Nayyar and Urbashi Mitra

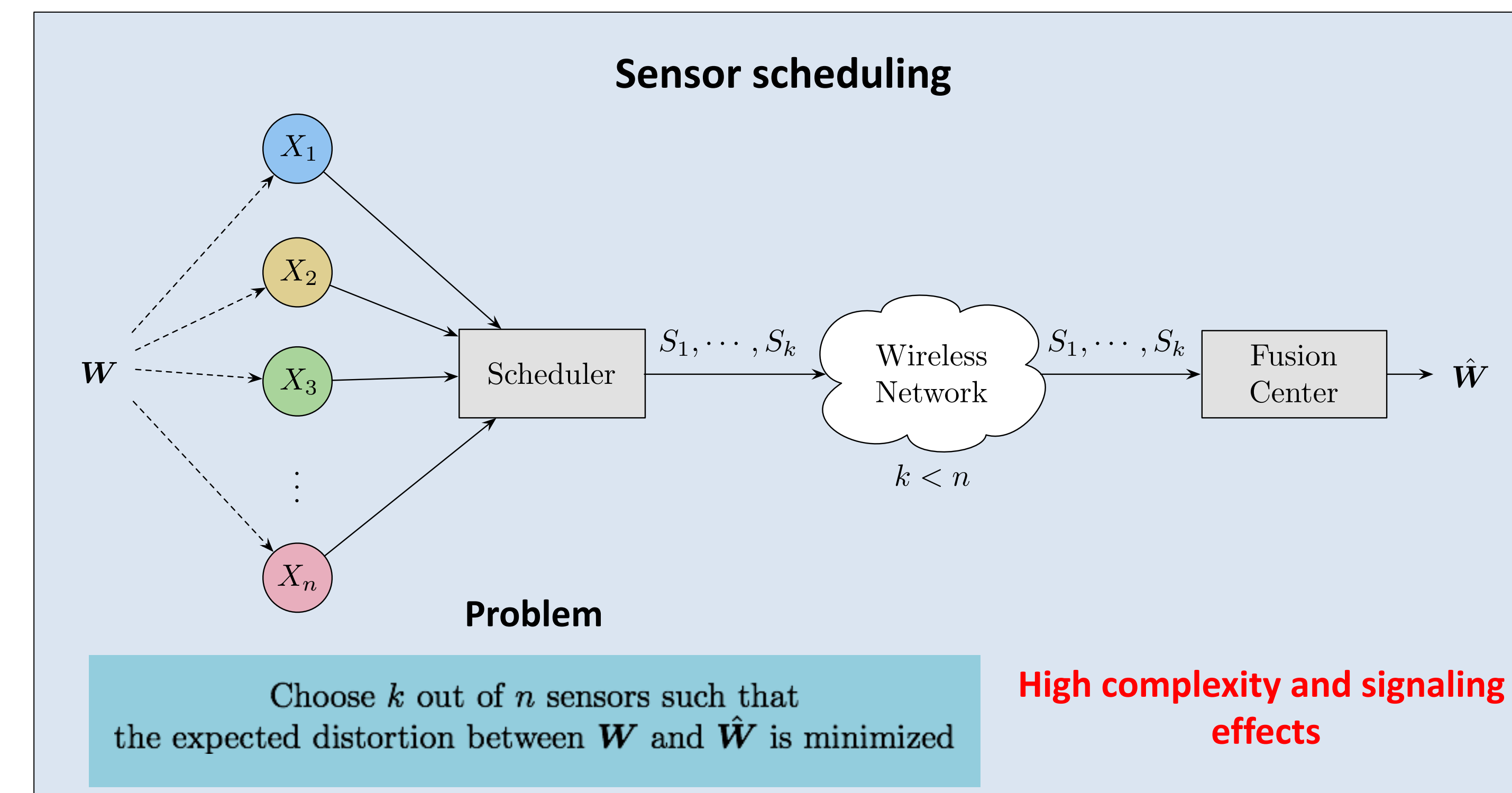


Cyber-Physical System
coupling **bio-sensors** on people and **wireless networks**

Goals
Real-time monitoring health and behavior
Feedback via adaptive and personalized interventions

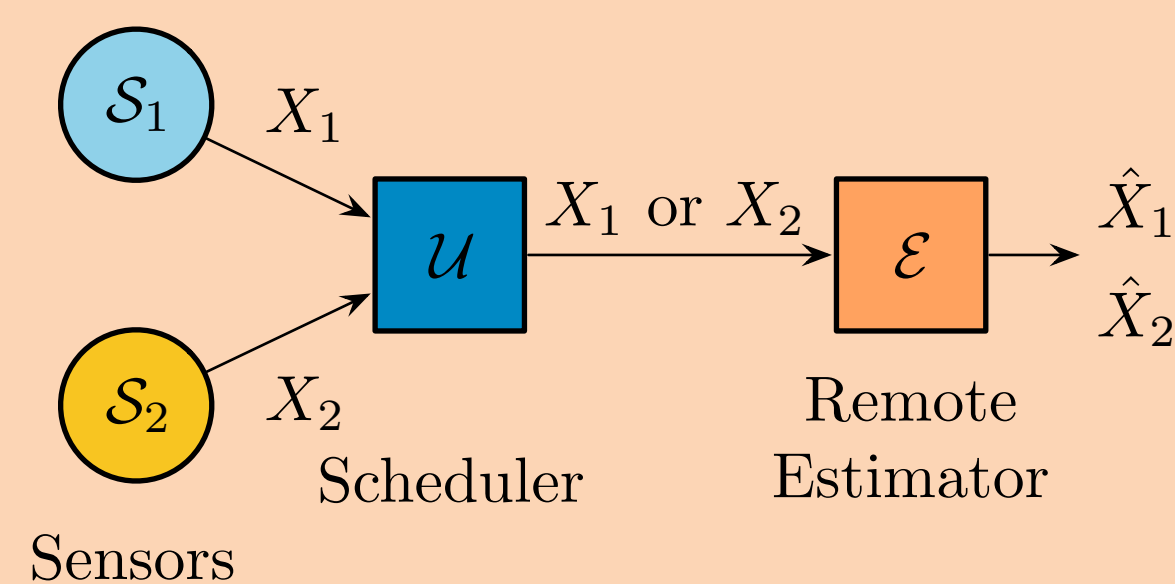
Design challenges
Sensors & data **heterogeneity**
Sensors & coordinator **energy constraints**
Sensing & communication are **state dependent**

Networked decision systems
New decision-making problems involving
the joint design of **sensing, communication and control**



Observation-driven scheduling for networked estimation

Observation-driven scheduling: One-shot Problem



$$X_1, X_2 \sim \mathcal{N}(\mathbf{0}, \Sigma)$$

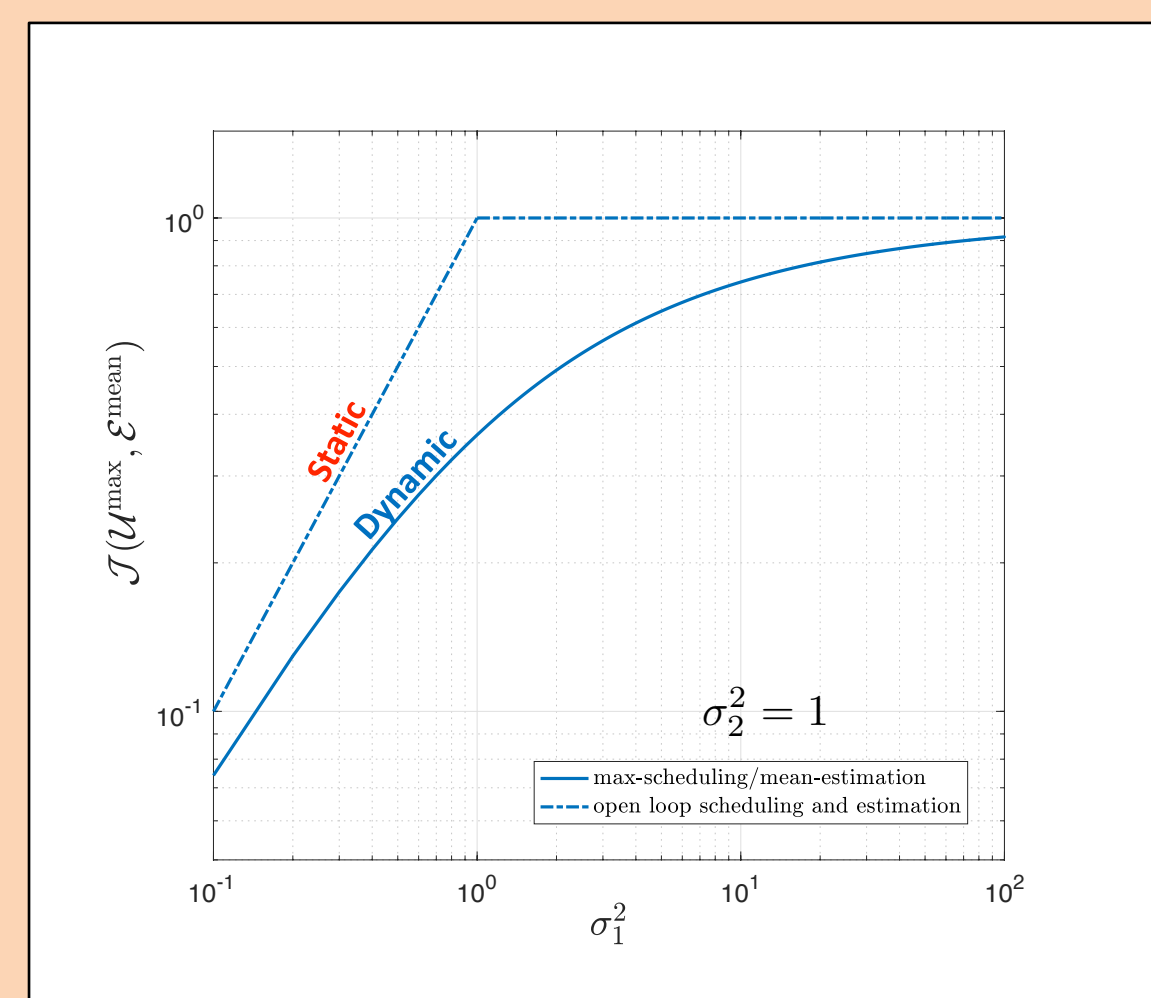
$$\mathcal{J}(\mathcal{U}, \mathcal{E}) = \mathbf{E}[(X_1 - \hat{X}_1)^2 + (X_2 - \hat{X}_2)^2]$$

Main result^[1]

Person-by-person optimality of max-scheduling and simple estimation strategies for independent and symmetrically correlated Gaussian observations

Send the measurement with largest magnitude

Estimate for the unobserved sensor: Conditional mean given the observed sensor value



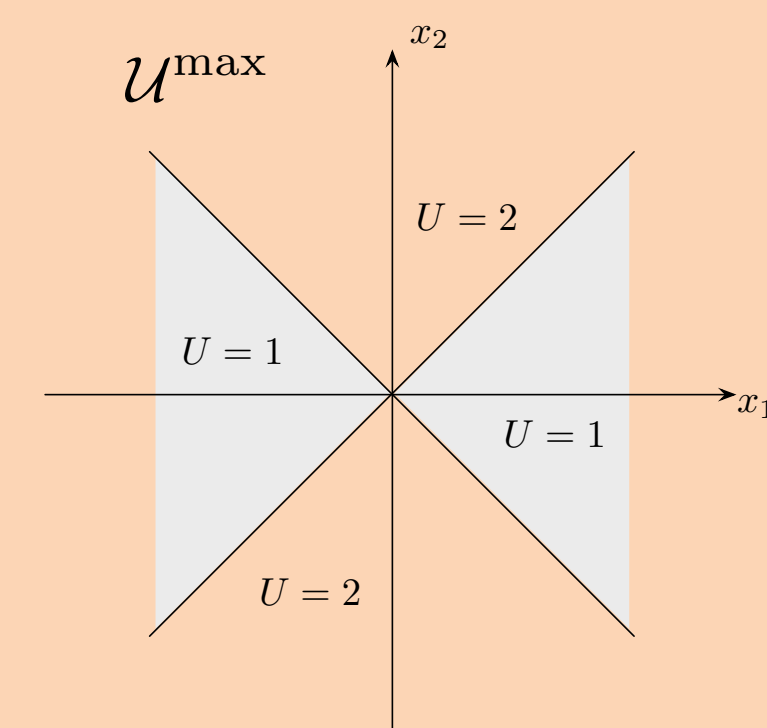
Performance comparison in the independent Gaussian case

$$\bar{\mathcal{J}}(\sigma_1^2, \sigma_2^2) = \min\{\sigma_1^2, \sigma_2^2\}$$

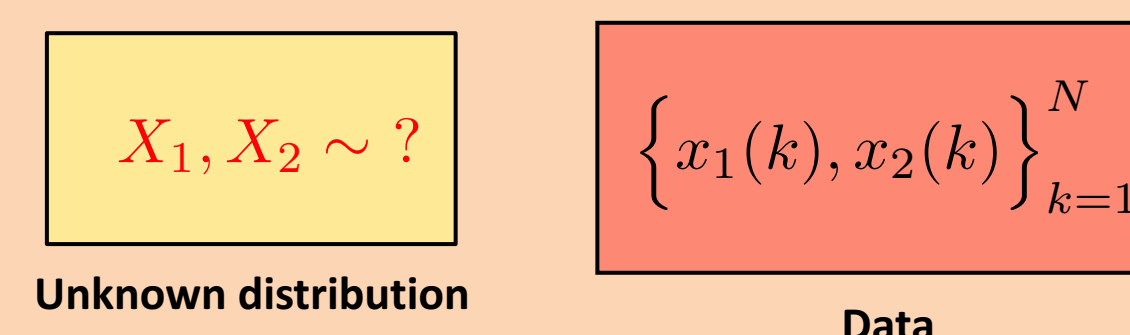
"Open-loop" sensor scheduling

$$\mathcal{J}(\mathcal{U}^{\max}, \mathcal{E}^{\text{mean}}) = \mathbf{E}[\min\{X_1^2, X_2^2\}]$$

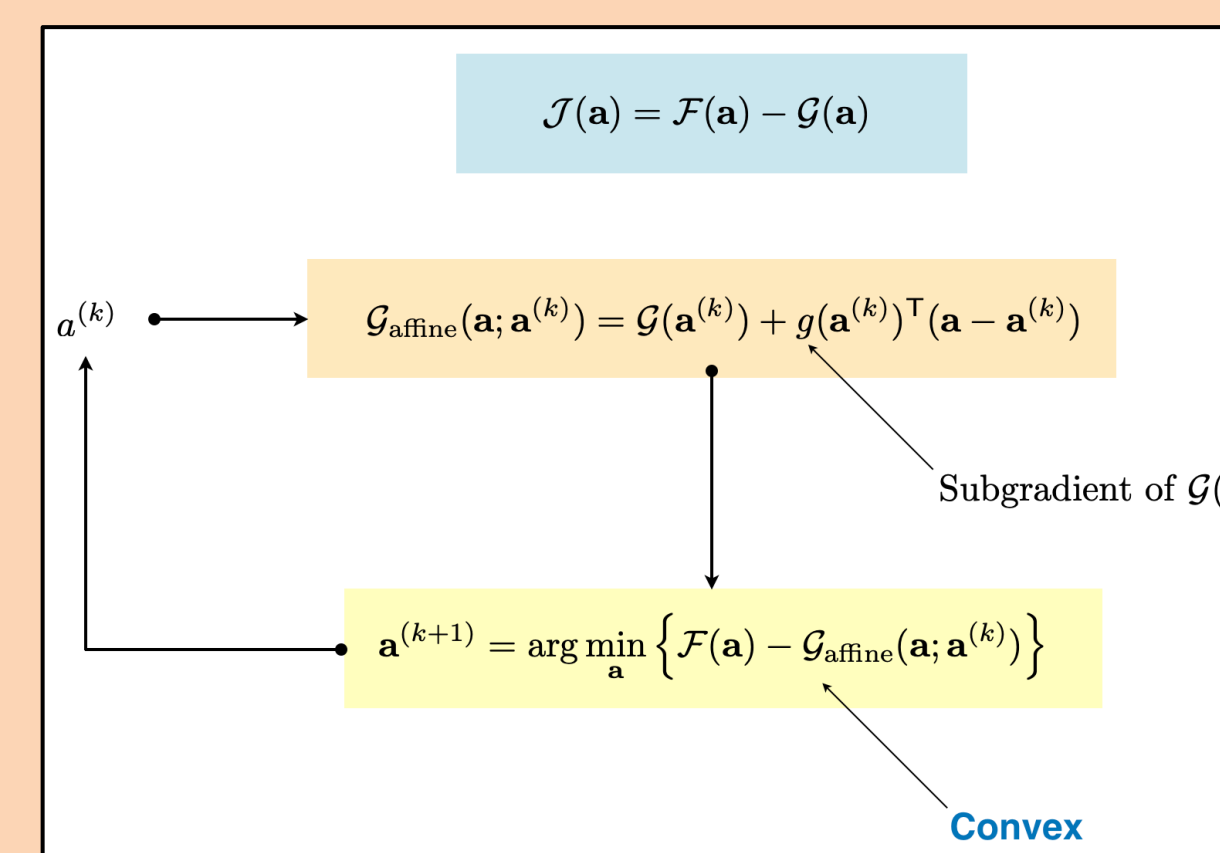
Observation-driven scheduling



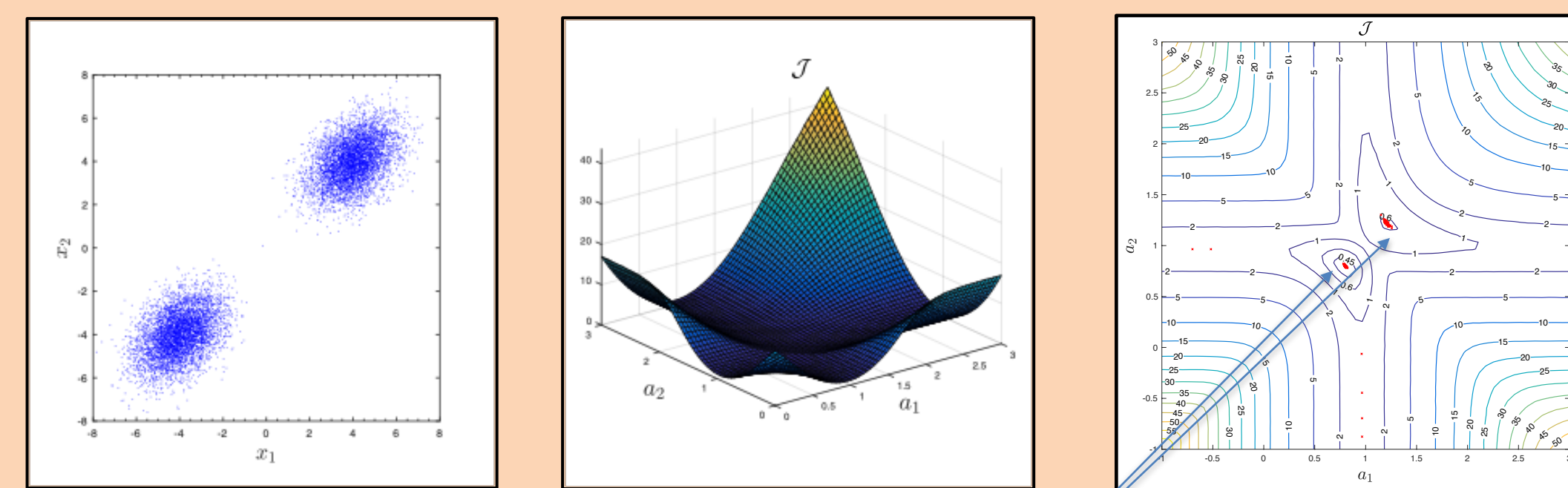
Model-free observation-driven scheduling



$$\mathcal{J}(\mathbf{a}) = \frac{1}{N} \sum_{k=1}^N \min\{(x_1(k) - a_1 x_2(k))^2, (x_2(k) - a_2 x_1(k))^2\}$$



Approximate Convex-Concave Procedure



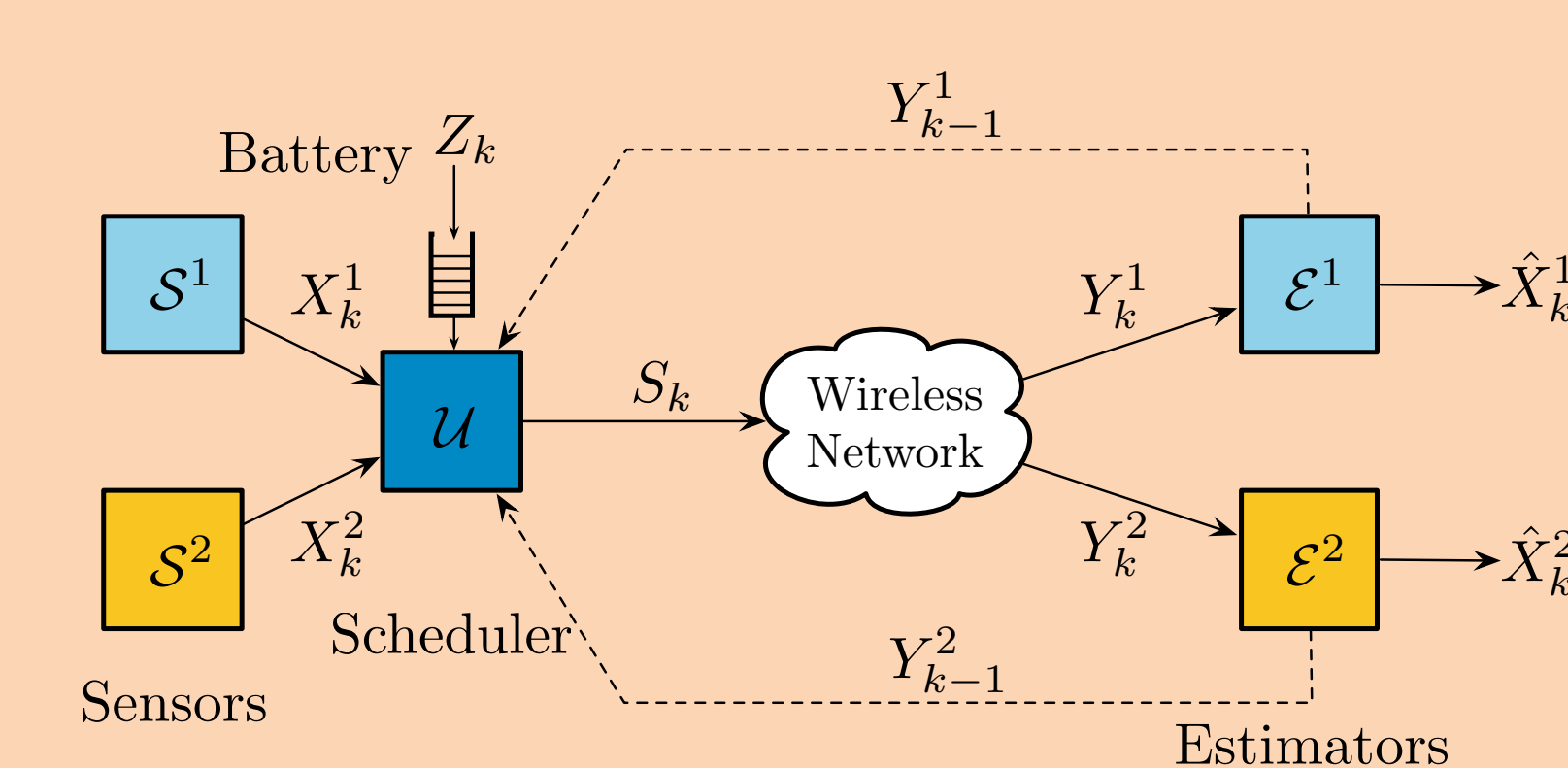
Data: Gaussian Mixture

Exact cost function

Experimental results

≈ 85% are within 50% of the optimal cost

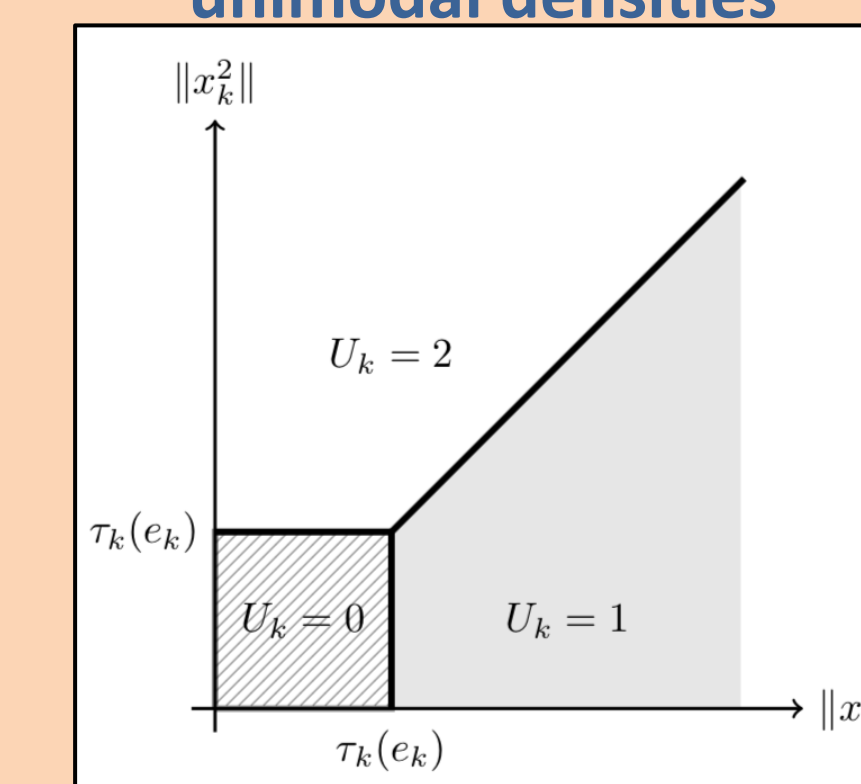
Scheduling with Energy Harvesting: Sequential Problem



$$\{X_k^1, X_k^2\}_{k=1}^N \text{ i.i.d.} \quad E_{k+1} = \min\{E_k - 1(U_k \neq 0) + Z_k, B\}$$

Main result^[2]

Global optimality of max-scheduling with simple estimation strategies for independent observations with symmetric and unimodal densities



[1] Vasconcelos & Mitra "Observation-driven scheduling for remote estimation of two Gaussian RVs" IEEE Trans. on Control of Network Systems (under review) 2018

[2] Vasconcelos, Gagrani, Nayyar & Mitra "An optimal sensor scheduling for networked estimation with energy harvesting" IEEE Trans. on Control of Network Systems, under review, 2019