CAREER: Physical Principles and Applications of Plant-Inspired Tip Growth for Robotics

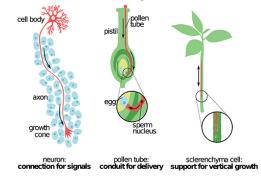


3) New Understanding and Applications:

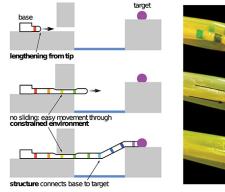
Elliot W. Hawkes (University of California at Santa Barbara)

Concept

Can we leverage the concept of tip growth, found across diverse organisms in nature?



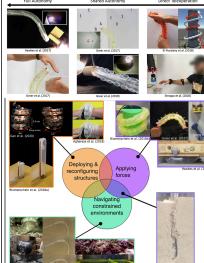
The research objective of this project is to use analytical modeling and hypothesisdriven experimentation to elucidate the physical principles governing the behavior of tip-growing "vine" robots.



material energes and evorts

Scientific Impact

1) Design, Modeling, Control: Organizing Current Knowledge



<u>Soort at D2200</u> Steet at (2027) Long at J2039 Refer to a Construction of Exercise at Construction of Exercise at Construction of Exercise at Construction of Exercise at Construction of Exercise and Coad, Margaret M. and Haggerty, David A. and Okamura, Allison M. and Hawkes, Elliot W. (2020). Design, Modeling, Control, and Application of Everting Vine Robots. Frontiers in Robotics and A. 7.

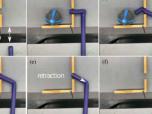
Broader Impact

Developing Remote Soft

Robotics Course

We have created fully remote courses with six lab modules for instructing soft robotics at the undergraduate and graduate levels. We have shared the content with an initial group of colleagues for feedback.

2) New Methods for Steering and Retraction





Haggerty, David Arthur and Naclerio, Nicholas and Hawkes, Elliot Wright. (2021). Hybrid vine robot with internal Steering-Reeling Mechanism enhances system-level capabilities. *IEEE* Robotics and Automation Letters.

Medical Applications

We are developing the understanding and expertise to move easily through the body. The first application area is emergency intubation.



Extreme subterranean mobility

We are developing the understanding and expertise to move below ground. Applications include search and rescue in mudslides as well as deployment of sensors



(55) Article No. eabe2922.

Outreach

Naclerio, Nicholas D. and Karsai, Andras and Murray-Cooper, Mason and Ozkan-Aydin, Yasemin and Aydin, Enes and Goldman, Daniel I. and Hawkes, Elliot W.. (2021). Controlling

subterranean forces enables a fast, steerable, burrowing soft robot. Science Robotics. 6

We created a science outreach <u>video</u> in collaboration with the YouTube Science Channel Veritasium, and has been viewed more than 20 million times!



2022 NRI & FRR Principal Investigators' Meeting April 19-21, 2022

Award ID#: 1944816

