

UNIFYING CONTROL AND VERIFICATION OF CYBER-PHYSICAL SYSTEMS

(UnCoVerCPS)

Name Surname, Affiliation

MAIN OBJECTIVES

- Novel on-the-fly control and verification concepts.
- Ground-breaking methods for unifying control and verification to quickly react to changing environments.
- Seamless integration of modelling and conformance testing.
- Prototypical realisations of the novel methods in automated vehicles and human-robot collaborative manufacturing.
- Analysis of the benefits of formal methods on wind turbines and smart grids case studies.
- A new development process that reduces development time and costs for critical cyber-physical systems to strengthen European companies which design or produce cyber-physical systems.

DEMONSTRATORS



Automated Vehicles



Wind Turbines

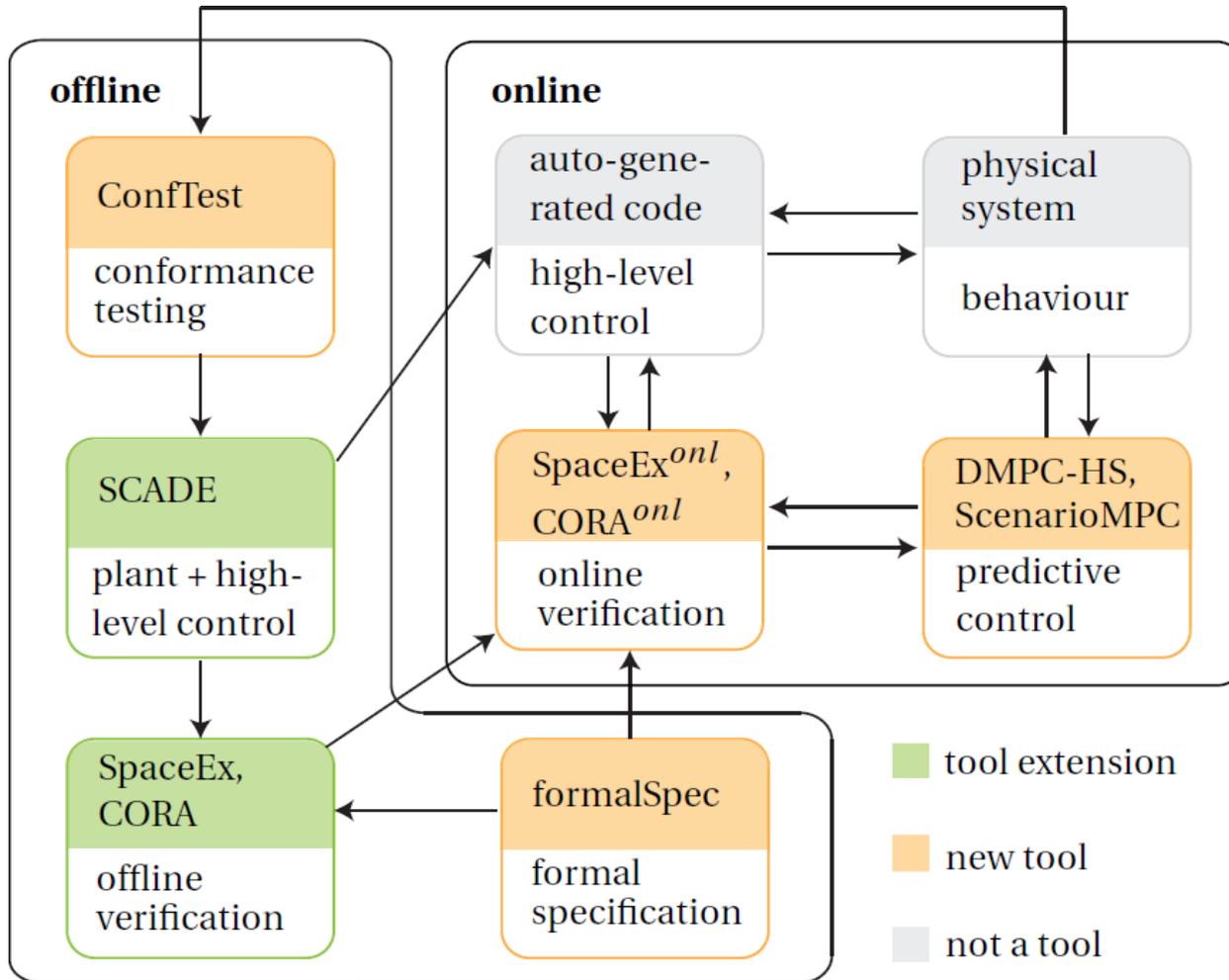


Human-Robot Collaboration



Smart Grids

TOOL CHAIN



A unique tool chain to integrate:

- modelling,
- control design,
- formal verification,
- automatic code generation.

CONSORTIUM



Technische Universität München (TUM) – Coordinator
Germany



BOSCH

Robert Bosch GmbH (Bosch)
Germany



Université Joseph Fourier Grenoble 1 (UJF)
France



Esterel Technologies (ET)
France

**UNIKASSEL
VERSITÄT**

Universität Kassel (UKS)
Germany



Deutsches Zentrum für Luft- und Raumfahrt (DLR)
Germany



Politecnico di Milano (PoliMi)
Italy



Tecnalia (Tec)
Spain



GE Global Research Europe (GE)
Germany



R.U.Robots Limited (RUR)
United Kingdom