

Secure and Plug-n-Play Energy Cyber-Physical Systems

submitted to
2013 National Workshop on Energy Cyber-Physical Systems

Z. Qu and M. A. Simaan

Keywords: Power Systems, smart grid, cooperative control, plug-n-play, modular design, secure CPS, game theory

October 31, 2013

Profs. Zhihua Qu and Marwan A. Simaan are with Department of Electrical Engineering and Computer Science, University of Central Florida (UCF), 4000 University Blvd., Orlando, FL 32816, USA. Emails: qu@ucf.edu & simaan@ucf.edu

This work is supported in part by US National Science Foundation (under grants ECCS-1308928, CCF-0956501 and CMMI-0825502), by US Department of Energy's award DE-EE0006340 (under the Grid Engineering for Accelerated Renewable Energy Deployment program), by US Department of Energy's Solar Energy Grid Integration Systems program, by US Department of Transportation (through the Electric Vehicle Transportation Center, a tier-1 University Transportation Center), and by L-3 Communications.

Abstract

In this position paper, cooperative control of distributed renewable generation is outlined, and three fundamental research topics are presented for robust, intelligent and efficient operations of power systems. The first topic deals with modular design and plug-n-play operation of heterogeneous systems in such networked settings as distributed energy resources (DERs) and electric distribution networks. The second topic addresses secure cyber-physical systems by analyzing the topological and design requirements under which networked operation of cooperative systems becomes robust under attacks. And the third subject deals with game theoretical analysis and design of energy cyber-physical systems.

1 Cooperative Control of Distributed Power Generation

Figure 1 shows a modern grid in which several DERs competitively and collaboratively provide power to both local loads in the microgrids and the main grid. It is well recognized [3] that these distributed energy sources are intermittent, that their presence will shift the operation of power system from the current mode of regulated utilities to a competitive generation provision, and that a high penetration level of DERs demands new regimes of communication, control, optimization, and security. Based on the dynamic energy control protocols (DECPs) [2], innovative algorithms of cooperative control, robustification, and dynamic game can be implemented to enable robust, intelligent and efficient operations for power systems with distributed and intermittent power generation sources.

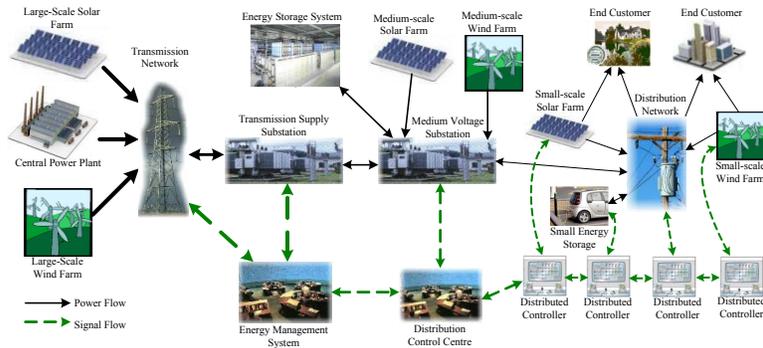


Fig. 1: A modern power grid of high DG penetration

Cooperative control is to make individual but networked dynamical systems achieve the same behavior (i.e., consensus) in the presence of intermittent information exchanges and/or topological connectivity changes [8]. Cooperative control problems arise naturally from energy cyber-physical systems. For instance, the voltage control problem is to ensure that the per-unit values of voltages at all the nodes in a microgrid be 1 or very close to 1. For DERs to supply active power to the loads in a microgrid, the load sharing policy intuitively imposes the so-called fair utilization ratio:

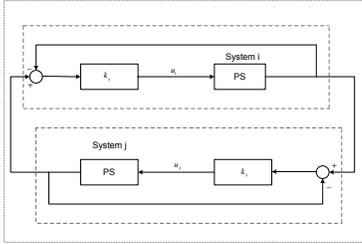
$$\frac{P_i}{P_i^{\max}} \rightarrow \alpha_p, \quad \forall i,$$

that is, utilization percentages of all the DERs approach the same value. Similarly, the fair utilization ratio could be required for inverter-based DERs to compensate for reactive power, for demand response of adjustable loads, etc. Accordingly, cooperative control can be used as the underlying methodology to make micro-grid operations self-organizing, autonomous and robust. To this end, three fundamental research topics are described in the subsequent sections.

2 Modular Design and Plug-n-Play Operation of Networked Systems

For inverter-based DERs described by simple dynamic equations, cooperative control has been shown in [13] to be very effective for both dispatch of active power as well as reactive power compensation. In general, the dynamics of both DERs and adjustable loads can be quite distinct from one to another. To characterize input-output relationship of such heterogeneous devices and to enable plug-n-play of their networked operation,

we can use the concept of passivity: The i th dynamic system of $\dot{z}_i = f(z_i, u_i)$ is said to be *dissipative* if, for a storage function $V_i(z_i)$ and a supply rate $\Phi_i(z_i, u_i)$, the following inequality holds:



$$V_i(z_i(t)) - V_i(z_i(0)) \leq \int_0^t \Phi_i(z_i(\tau), u_i(\tau)) d\tau.$$

The system is said to be *input feedforward passive* or simply *passive* if, for some positive semi-definite function $\eta_i(\cdot)$ and for some $\epsilon_i \geq 0$,

$$\Phi_i(z_i, u_i) = -\eta_i(z_i) + u_i^T y_i + \frac{\epsilon_i}{2} \|u_i\|^2.$$

Fig. 2: Networked operation of two PS systems

If $\epsilon_i \geq 0$ in the above definition, the system is said to be *passivity-short* (PS), and ϵ_i is referred to as the *impact coefficient*. It is apparent that passivity-short (PS) systems include passive systems as a special case of $\epsilon_i = 0$. It is shown in [12, 9] that controllable linear and nonlinear systems can individually be stabilized into PS systems and that, as illustrated by figure 2, PS systems are plug-n-play under cooperative control laws. This modular design methodology and local distributed implementation are well suited for applications to energy cyber-physical systems, and on-going research focuses upon some of these applications.

3 Secure Cooperative Systems Against Attacks

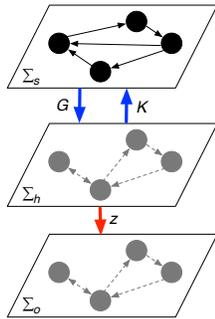


Fig. 3: A design of secure cooperative systems

Cooperative control is specifically geared toward networked systems and requires only local information, but its dispersed implementation makes the cooperative system susceptible to attacks by malicious agents. It can be shown using counterexample that, unless all the dynamic systems are passive, cooperative systems could be destabilized by data attacking involving simply linear dynamics. It is shown in [1] that this vulnerability can be overcome by introducing competitive stabilization and desired robustification can be achieved by using the three-layer design shown in figure 3. Specifically, networked system nodes and their distributed cooperative control are denoted by Σ_s of Laplacian L_s , a hidden network denoted by Σ_h of Laplacian L_h is then designed to achieve robustification of the overall network system through competitive stabilization, and finally an observation network of Σ_o can be employed to identify potential attackers. Fundamental research is being carried out to develop the relationship among Σ_s , Σ_h and Σ_o for design and performance guarantee.

4 Game Theoretical Algorithms for Energy Cyber-Physical Systems

As has been shown in [11, 5], distributed optimization and game algorithms are instrumental to enable formation of self-evolving micro-grids and their intelligent and reliable operations and to make DERs and loads respond to the incentive or stability demands of the main grid. Recent research efforts focused upon development of distributed game strategies, both cooperative algorithms [10, 6, 7], and noncooperative strategies [4]. We plan to apply these algorithms to smart distribution networks and also investigate game-theoretical designs of secure cyber-physical systems.

Through the workshop, we hope to exchange ideas and collaborate toward developing systematic methodologies for analyzing, designing and operating energy cyber-physical systems.

References

- [1] A. Gusrialdi, Z. Qu, and M. A. Simaan, “Robust design of cooperative systems against attacks,” in *2014 American Control Conference*, Portland, Oregon, submitted.
- [2] M. Ilic, “Engineering energy services of the future by means of dynamic energy control protocols (DECPs),” in *Proceedings of the 2007 IEEE Systems, Man, and Cybernetics Conference*, Montreal, Canada, October 2007.
- [3] —, “From hierarchical to open access electric power systems,” *IEEE Proceedings*, vol. 95, pp. 1060–1084, 2007.
- [4] W. Lin, Z. Qu, and M. A. Simaan, “Distributed ϵ -nash strategies for multi-pursuer single-evader differential games,” in *2014 American Control Conference*, Portland, Oregon, submitted.
- [5] A. Maknouninejad, W. Lin, H. G. Harno, Z. Qu, and M. A. Simaan, “Cooperative control for self-organizing microgrids and game strategies for optimal dispatch of distributed renewable generations,” *Springer’s Journal of Energy Systems*, vol. 3, no. 1, pp. 23–60, 2012.
- [6] A. Maknouninejad and Z. Qu, “Control of distributed generators by cooperative distributed optimization,” in *the 2013 Virtual Control Conference on Smart Grid Modeling and Control (VCC-13)*, Aalborg University, Denmark, September 2013.
- [7] —, “Realizing unified microgrid voltage profile and loss minimization: a cooperative distributed optimization approach,” *IEEE Transactions on Smart Grid*, submitted 10/21/2012, revised 4/7/2013, revised 8/15/13.
- [8] Z. Qu, *Cooperative Control of Dynamical Systems*. London: Springer Verlag, 2009.
- [9] —, “An impact equivalence principle of separating control designs for networked heterogeneous affine systems,” in *Proceedings of the 3rd IFAC Workshop on Distributed Estimation and Control in Networked Systems*, Santa Barbara, CA, USA, September 2012.
- [10] Z. Qu and M. A. Simaan, “A design of distributed game strategies for networked agents,” in *Proceedings of the 1st IFAC Workshop on Estimation and Control of Networked Systems (NecSys’09)*, Venice, Italy, September 24-26 2009, pp. 270–275.
- [11] —, “Power systems with distributed generation: Self-organizing micro-grids, optimization, and control,” in *National Workshop on New Research Directions for Future Cyber-Physical Energy Systems*, Baltimore, Maryland, June 2009.
- [12] —, “Modularized design for cooperative control and plug-and-play operation of networked heterogeneous systems,” *Automatica*, submitted 8/28/2012, revised 3/6/2013, revised 10/28/13.
- [13] H. Xin, Z. Qu, J. Seuss, and A. Maknouninejad, “A self organizing strategy for power flow control of photovoltaic generators in a distribution network,” *IEEE Transactions on Power Systems*, vol. 26, no. 3, pp. 1462–1473, 2011.