

The Evolution of Software-Programmable Cyber-Physical Digital Microfluidic Laboratories-on-a-Chip

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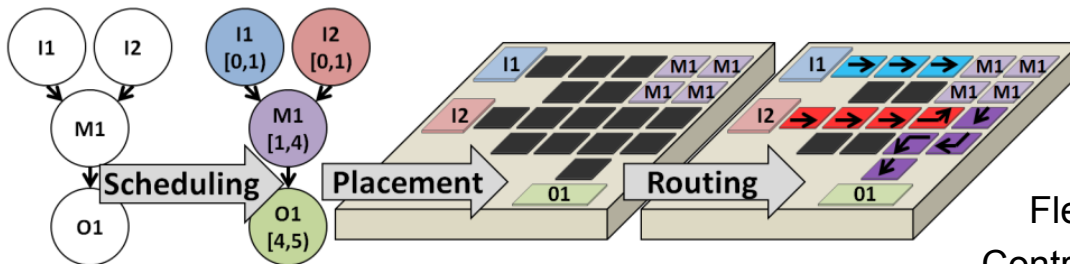
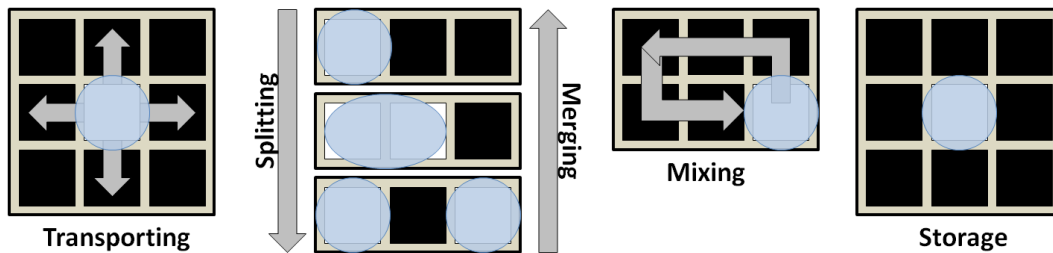
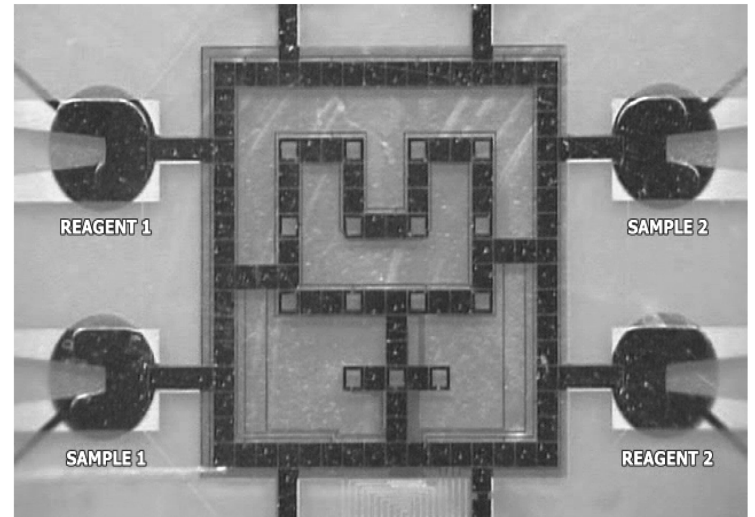
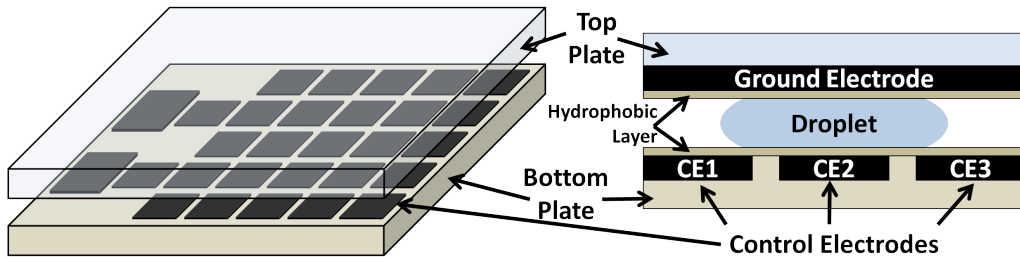
University of California, Riverside



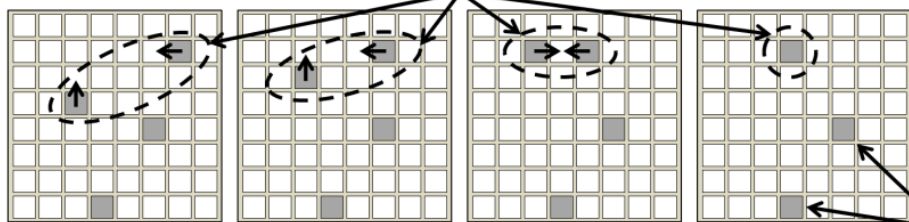
2014 NSF Workshop on Research Frontiers in
Medical Cyber-Physical Systems

February 6-7, 2014

Digital Microfluidic Technology: Pre-CPS



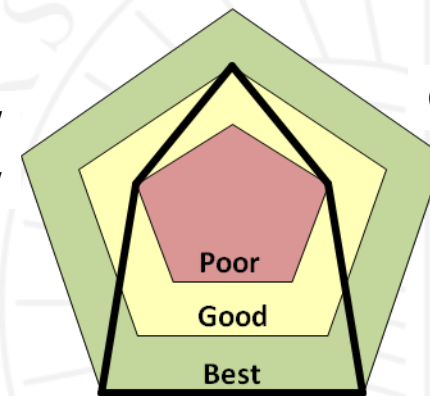
Two droplets brought together and merged



Flexibility/
Control-Flow

Programmability

Computational
Overhead

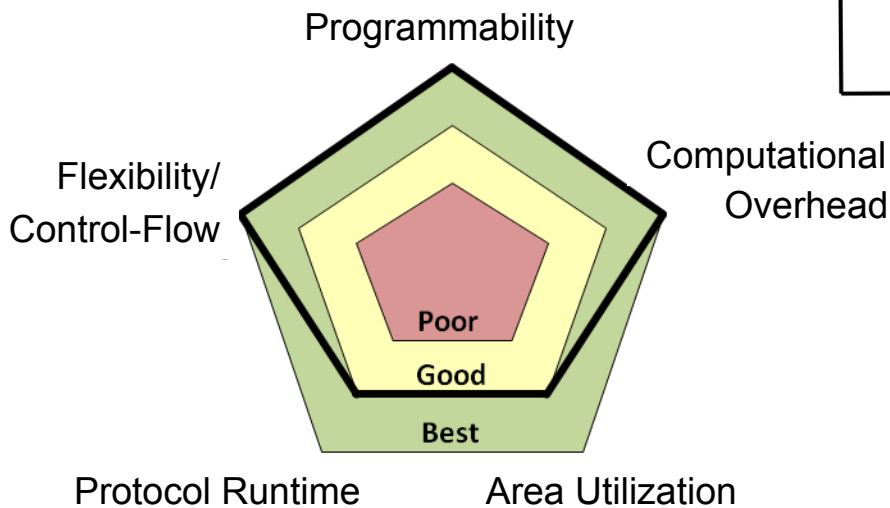
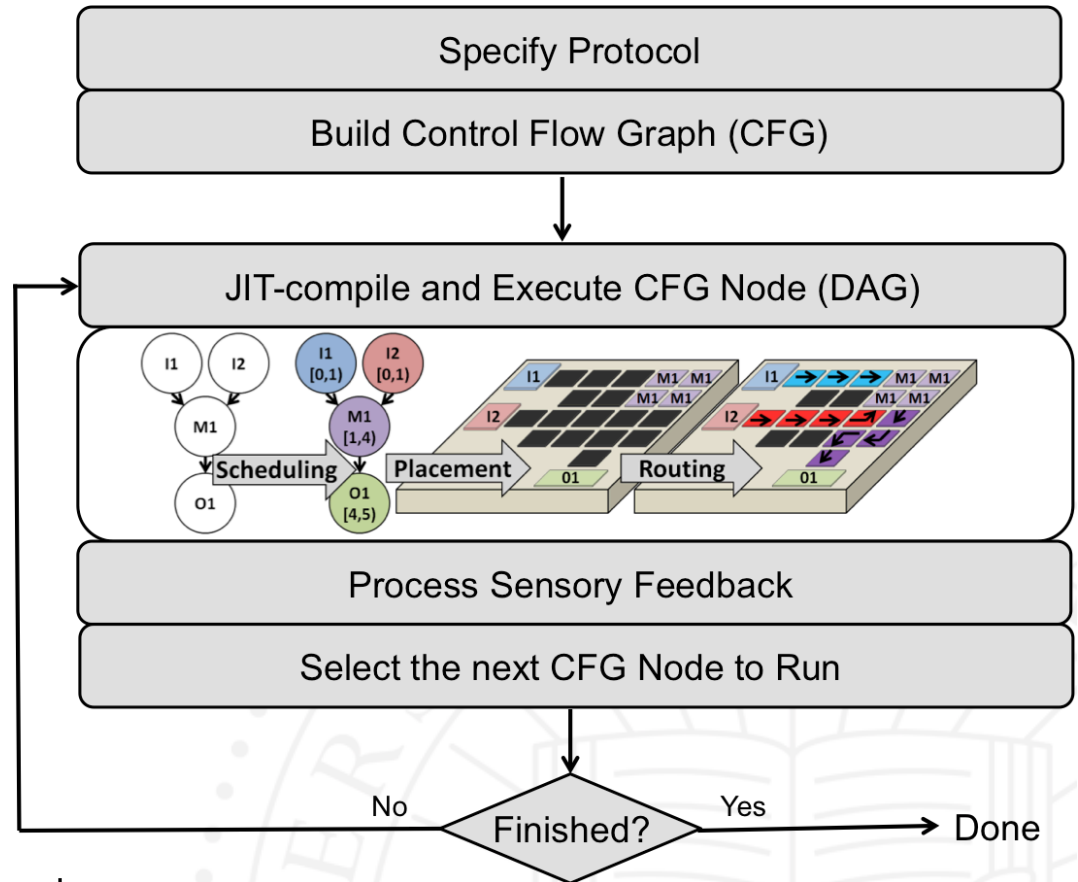
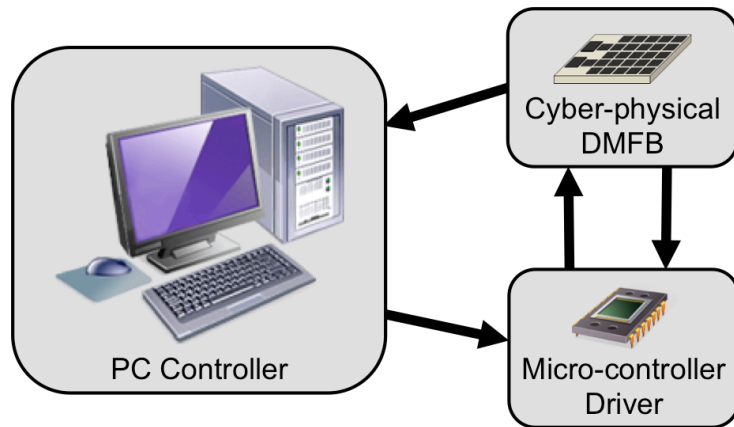


Protocol Runtime

Area Utilization

Cyber-physical Integration

NSF CPS Funding
 CNS-1035603 (Brisk, UCR)
 CNS-1135853 (Chakrabarty, Duke)



Contributions (CNS-1035603)

- Real-time decision-making based on sensory feedback
- Programming language support
- Fast JIT compilation flow

Future Directions

- ▶ Better domain-specific programming languages for automated biology
 - ▶ Syntax must be acceptable to biologists
 - ▶ Express timing of operations / constraints
 - ▶ Automatically extract / exploit parallelism
- ▶ Automate loading / unloading of samples
 - ▶ Robotic liquid handling
 - ▶ Off-chip fluid storage
- ▶ Distributed control over the Internet
 - ▶ Multi-site collaboration
 - ▶ Ensure timing constraints / QoS