

Center for Human, Artificial Intelligence, and Robot Teaming

The Future Workforce: Human-Al-Robot Teaming

Nancy J. Cooke
Professor, Human Systems Engineering
Director, Center for Human, AI, and Robot Teaming
Arizona State University

Draw from Social Science Principles of Human Teaming

1. Team members have <u>different roles and</u> <u>responsibilities</u>



Don't Replicate Ourselves







2. Effective teams understand that each team member has different roles and responsibilities and avoid role confusion, but back each other up as necessary

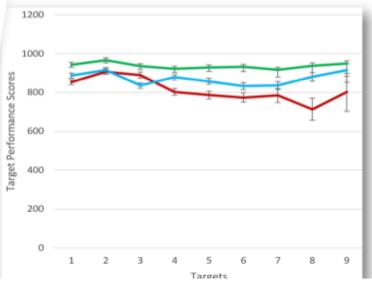




VBCTOT**Stock**® Vecaurised.com/239

Technology Needs to Understand the Bigger Team Task





- Synthetic teammate
 - Performance
 - Coordination
- Control teammate
- Experimenter teammate

3. With team practice, effective teams share knowledge about the team goals and the current situation and this facilitates coordination and implicit communication



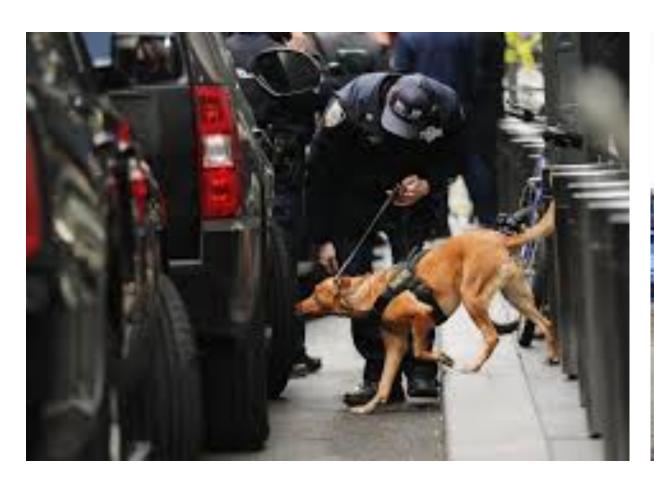


Humans and Technology
Need to Train
Together



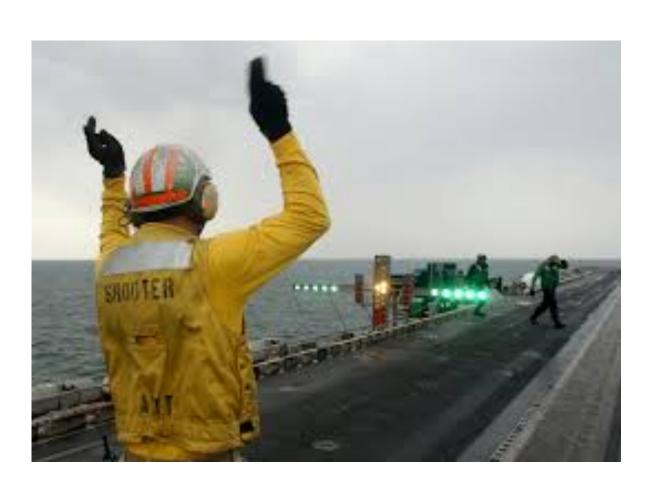


4. Effective teams have team members who are interdependent and thus need to <u>interact/communicate</u> even when direct communication is impossible





Interaction is Important But Natural Language Communication May Be Unnecessary

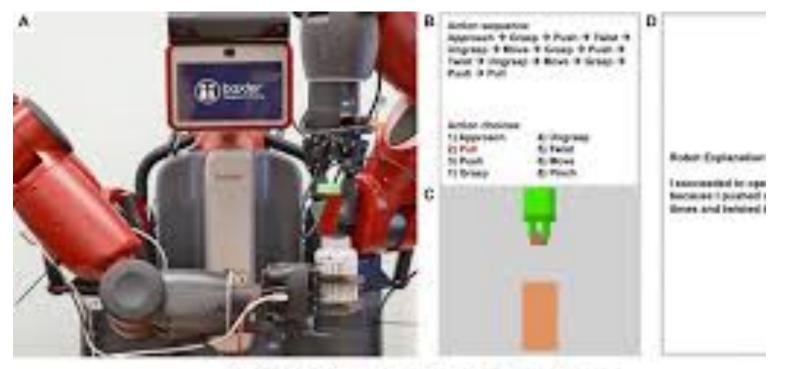




5. Interpersonal trust is important to human teams







E. Summary of human subject groups and explanations presented:

Group	2008 (4)	Symbolic (B)	Haptic (C)	Tiest (D)
Barrier	1			
Symbolic	1	V.		
Heptie	1		12	
GEP	16.	140		
Trox	4			400

Transparency and Explanation are Important

Social Science Research for Informing Human-Al-Robot Teaming

Synthetic Task Environments

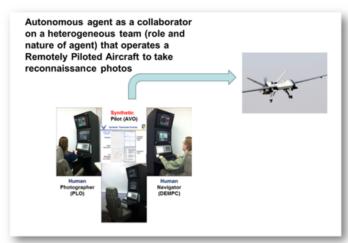
Testbed







- Some vehicles will be autonomous and some remotely driven
- Human-driven cars will have to interact with the driverless cars
- Will be situated in a model urban setting





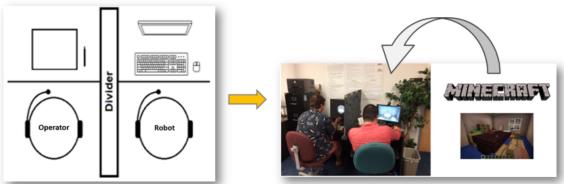
- Extend ACT-R cognitive modeling
- Better understand essentials of team coordination
- Use synthetic teammates for team training

Testbed

Wizard of OZ



Testbed



- A simulated USAR task environment (Minecraft)
- Human Operator and Robot work together to complete the USAR task and identify victim locations
- A human playing the role of the robot in a Wizard-of-Oz paradigm
- Operator has restricted view of the environment and has map before building collapse that is inconsistent with current structure

Conclusions

- Principles from the social science of teams have implications for human-Al-robot teaming
- Testbeds and the Wizard of Oz method can provide human subjects data on interactions with robots/Al ahead of robot/Al development



